



DTSC-200 ATS Controller



Configuration
Software Version 1.0xxx

**WARNING**

Read this entire manual and all other publications pertaining to the work to be performed before installing, operating, or servicing this equipment. Practice all plant and safety instructions and precautions. Failure to follow instructions can cause personal injury and/or property damage.

The engine, turbine, or other type of prime mover should be equipped with an overspeed (overtemperature, or overpressure, where applicable) shutdown device(s), that operates totally independently of the prime mover control device(s) to protect against runaway or damage to the engine, turbine, or other type of prime mover with possible personal injury or loss of life should the mechanical-hydraulic governor(s) or electric control(s), the actuator(s), fuel control(s), the driving mechanism(s), the linkage(s), or the controlled device(s) fail.

Any unauthorized modifications to or use of this equipment outside its specified mechanical, electrical, or other operating limits may cause personal injury and/or property damage, including damage to the equipment. Any such unauthorized modifications: (i) constitute "misuse" and/or "negligence" within the meaning of the product warranty thereby excluding warranty coverage for any resulting damage, and (ii) invalidate product certifications or listings.

**CAUTION**

To prevent damage to a control system that uses an alternator or battery-charging device, make sure the charging device is turned off before disconnecting the battery from the system.

Electronic controls contain static-sensitive parts. Observe the following precautions to prevent damage to these parts.

- Discharge body static before handling the control (with power to the control turned off, contact a grounded surface and maintain contact while handling the control).
- Avoid all plastic, vinyl, and Styrofoam (except antistatic versions) around printed circuit boards.
- Do not touch the components or conductors on a printed circuit board with your hands or with conductive devices.

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Important definitions**WARNING**

Indicates a potentially hazardous situation that, if not avoided, could result in death or serious injury.

**CAUTION**

Indicates a potentially hazardous situation that, if not avoided, could result in damage to equipment.

**NOTE**

Provides other helpful information that does not fall under the warning or caution categories.

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Chapter 1.

General Information

Type	English	German
DTSC-200 Series		
DTSC-200 - Installation	37385	-
DTSC-200 - Configuration	this manual ⇨	-
DTSC-200 - Operation	37387	-
DTSC-200 - Application	37388	-
DTSC-200 - Interfaces	37389	-
Additional Manuals		
IKD 1 - Manual	37135	GR37135
Discrete expansion board with 8 discrete inputs and 8 relay outputs that can be coupled via the CAN bus to the control unit. Evaluation of the discrete inputs as well as control of the relay outputs is done via the control unit.		
LeoPC1 - User Manual	37146	GR37146
PC program for visualization, configuration, remote control, data logging, language upload, alarm and user management, and management of the event recorder. This manual describes the set up of the program and interfacing with the control unit.		
LeoPC1 - Engineering Manual	37164	GR37164
PC program for visualization, configuration, remote control, data logging, language upload, alarm and user management, and management of the event recorder. This manual describes the configuration and customization of the program.		

Table 1-1: Manual - overview

Intended Use The unit must only be operated for the uses described in this manual. The prerequisite for a proper and safe operation of the product is correct transportation, storage, and installation as well as careful operation and maintenance.



NOTE

This manual has been developed for a unit fitted with all available options. Inputs/outputs, functions, configuration screens and other details described, which do not exist on your unit may be ignored.

The present manual has been prepared to enable the installation and commissioning of the unit. On account of the large variety of parameter settings, it is not possible to cover every possible combination. The manual is therefore only a guide. In case of incorrect entries or a total loss of functions, the default settings can be taken from the enclosed list of parameters at the rear of this manual.

Chapter 2. Configuration

Configuration Via The Front Panel



How to operate the unit via the front panel is explained in the operation manual 37387. Please familiarize yourself with the unit, the buttons and their meaning/operation and the display monitoring using this manual. The display of parameters via the front panel will differ from the display of the parameters via the LeoPC1 program described in this manual. The sequence, the meaning and the setting limits are identical.

Configuration Using The PC



CAUTION

For the configuration of the unit via the PC please use the LeoPC1 software with the following software version:

LeoPC1 from 3.1.xxx



NOTE

Please note that configuration using the direct configuration cable DPC (product number 5417-557) is possible starting with revision B of the DPC (first delivered July 2003). If you have an older model please contact our sales department.

For configuration of the unit via PC program please proceed as follows:

- Install the PC program on your laptop/PC according to the installation manual.
- Before the end of the installation you are requested to select the language with which you want to start the PC program. You can change the language at any time. The selection of the language refers only to language with which the menus and subprograms of the PC program works. This setting will not change the language of the control unit being configured.
- After the installation of the PC program reboot your laptop/PC.
- Establish the connection between your laptop/PC and the unit via the DPC. Plug one side to the configuration plug of the unit and the other side to the COM1 port of your laptop/PC (other possibilities are described in the installation manual).
- You may start the PC program as follows:
 - by "Start/Program/Woodward/LeoPC" (starting at version 3.1.xxx), or
 - by a double click on a file ending ".cfg" in the subdirectory "/LeoPC".
- After the PC program was started, establish the communication by pressing the "F2" button. This will establish a data link between the unit and the laptop/PC.
- Start the sub program "Device Parameterization" and adjust the parameter of the unit to your application using this manual.



NOTE

The connection cables delivered with the DPC must be used to connect to the DTSC to ensure that the controller functions properly. An extension or utilization of different cable types for the connection between DTSC and DPC may result a malfunction of the DTSC. This may possibly result in damage to components of the system. If an extension of the data connection line is required, only the serial cable between DPC and laptop/PC may be extended.



NOTE

If the laptop/PC fails to communicate with the control unit being configured, refer to LeoPC1 manual 37146.



NOTE

Depending on the used computer and the installed operation system, problems with the communication via an infrared connection may occur.



NOTE

If you want to read or write parameters using a [LeoPC1 Gateway-RS-232 via GW4] connection, you must configure the parameter "Visualization" to "not active" in LeoPC1. The parameter "Visualization" may be configured back to "active" after reading and/or writing.

General Information



The DTSC-200 has been developed to control ATS (Automatic Transfer Switch) units.

The main purpose of the ATS controller is to control and monitor the transfer switch as well as issuing an engine start signal to a connected genset control. The controller is continuously monitoring the presence of a source. If the preferred source fails, it attempts to transfer to a second source (emergency power supply, etc.).

It is NOT the task of an ATS controller to monitor a start/stop sequence. Start and stop failures will be displayed, but have no effect on the functionality of the controller. Only switch failures or problems with connected position limit switches, which signal the actual position of the ATS (connected with utility or connected with emergency power supply, etc.) to the controller, block the ATS controller for further automatic functions.

Important Designations

- Source 1 Usually the preferred power source, e.g. utility supply (depends on application)
- Source 2 Usually the emergency power source, e.g. genset (depends on application)
- Transfer Change from one source to the other

Signal and Command Abbreviations

- S1 Signal: breaker in source 1 position
- S2 Signal: breaker in source 2 position
- S1O Signal: breaker in source 1 OPEN position
- S2O Signal: breaker in source 2 OPEN position
- C1 Command: close to source 1
- C2 Command: close to source 2
- C1O Command: open from source 1
- C2O Command: open from source 2

Monitoring Functions

Source Monitoring

- Overvoltage / undervoltage
- Overfrequency / underfrequency
- Voltage imbalance
- Rotation field monitoring



NOTE

If one of these monitoring functions is triggered, the ATS controller attempts to change to the non-preferred source.

Load Monitoring

- Overload
- Overcurrent

Switch Monitoring

- Monitoring for plausible position feedback
- Monitoring for transfer failure



NOTE

If one of these monitoring functions is triggered, the all automatic transfers are blocked.

Generator Monitoring

- Unintended stop
- Start failure

Battery Monitoring

- Overvoltage / undervoltage

Interface Monitoring

- Monitoring of the CANopen communication

Function Of The Inputs And Outputs



Discrete Inputs

The discrete inputs may be grouped into two categories:

- **programmable**
The programmable discrete input has been programmed with a factory default function using the *LogicsManager*. The following text describes how these functions may be changed using the *LogicsManager*.
- **fixed**
The discrete input has a specific function that cannot be changed. The discrete input cannot be used in the *LogicsManager*.



NOTE

Depending on the configured transfer switch type (Parameter 3424), the discrete inputs can be "*programmable*" or "*fixed*". Please refer to Table 3-7 on page 76.

Reply from ATS limit switch: Breaker in source 1 position

fixed to discrete input [DI 1], terminal 51/50

⇒ Note: Normally closed (break) contact!

This discrete input indicates to the control that the breaker is closed to source 1 position if it is de-energized (logic "0").

Reply from ATS limit switch: Breaker in source 2 position

fixed to discrete input [DI 2], terminal 52/50

⇒ Note: Normally closed (break) contact!

This discrete input indicates to the control that the breaker is closed to source 2 position if it is de-energized (logic "0").

Reply from ATS limit switch: Breaker in source 1 open position

fixed to discrete input [DI 3], terminal 53/50

⇒ Note: Normally closed (break) contact!

This discrete input indicates to the control that the breaker is in source 1 open position if it is de-energized (logic "0"). This discrete input is *programmable* with standard transfer switch type.

Reply from ATS limit switch: Breaker in source 2 open position

fixed to discrete input [DI 4], terminal 54/50

⇒ Note: Normally closed (break) contact!

This discrete input indicates to the control that the breaker is in source 2 open position if it is de-energized (logic "0"). This discrete input is *programmable* with standard transfer switch type.

Disconnect switch: Inhibit ATS

programmable to discrete input [DI 5], terminal 55/50

⇒ Note: Normally closed (break) contact!

This discrete input indicates to the control that the disconnect switch is actuated. If this discrete input is de-energized (logic "0"), the "Inhibit ATS" function is enabled.

Control Inputs

programmable to discrete inputs [DI 6] through [DI 12], terminals 56 through 62 / 50

These discrete inputs may be used as control signals for functions, like priority selection, remote peak shave, inhibit transfer, etc. The control inputs can be configured freely. Please refer to Discrete Inputs on page 66.

Relay Outputs

The discrete outputs can be grouped into two categories:

- **programmable**
The relay output is freely programmable using the *LogicsManager* (which is described in the following text).
- **pre-defined**
The relay output has been pre-defined (programmed) with this function using the *LogicsManager* (which is described in the following text). The function may be changed by using the *LogicsManager*.



NOTE

The relay outputs can be "**programmable**" or "**pre-defined**" for a specific function required for the configured transfer switch type (Parameter 3424). Please refer to Table 3-10 on page 78.

LogicsManager Relay {all} *programmable* to relay [R1] through [R3], terminals 32 through 34 / 31
⇒ **Note: Normally open (make) contact!**

All relays not assigned a defined function, may be configured via the *LogicsManager*.

LogicsManager Relay {all} *programmable* to relay [R4], terminals 35/36/37
⇒ **Note: Change-over contact!**

All relays not assigned a defined function, may be configured via the *LogicsManager*.

Start engine {all} *pre-defined* to relay [R5], terminals 39/40/41
⇒ **Note: Change-over contact!**

By energizing (or de-energizing, depending on the utilized contact) this relay an engine start signal will be issued to the genset control.

Command: close to source 1 position {all} *pre-defined* to relay [R6], terminals 42/43
⇒ **Note: Normally open (make) contact!**

By energizing this relay, a "close to source 1 position" command will be issued to the ATS.

Command: close to source 2 position {all} *pre-defined* to relay [R7], terminals 44/45
⇒ **Note: Normally open (make) contact!**

By energizing this relay, a "close to source 2 position" command will be issued to the ATS.

Command: open from source 1 position to neutral position{all} *pre-defined* to relay [R8], terminals 46/47
⇒ **Note: Normally open (make) contact!**

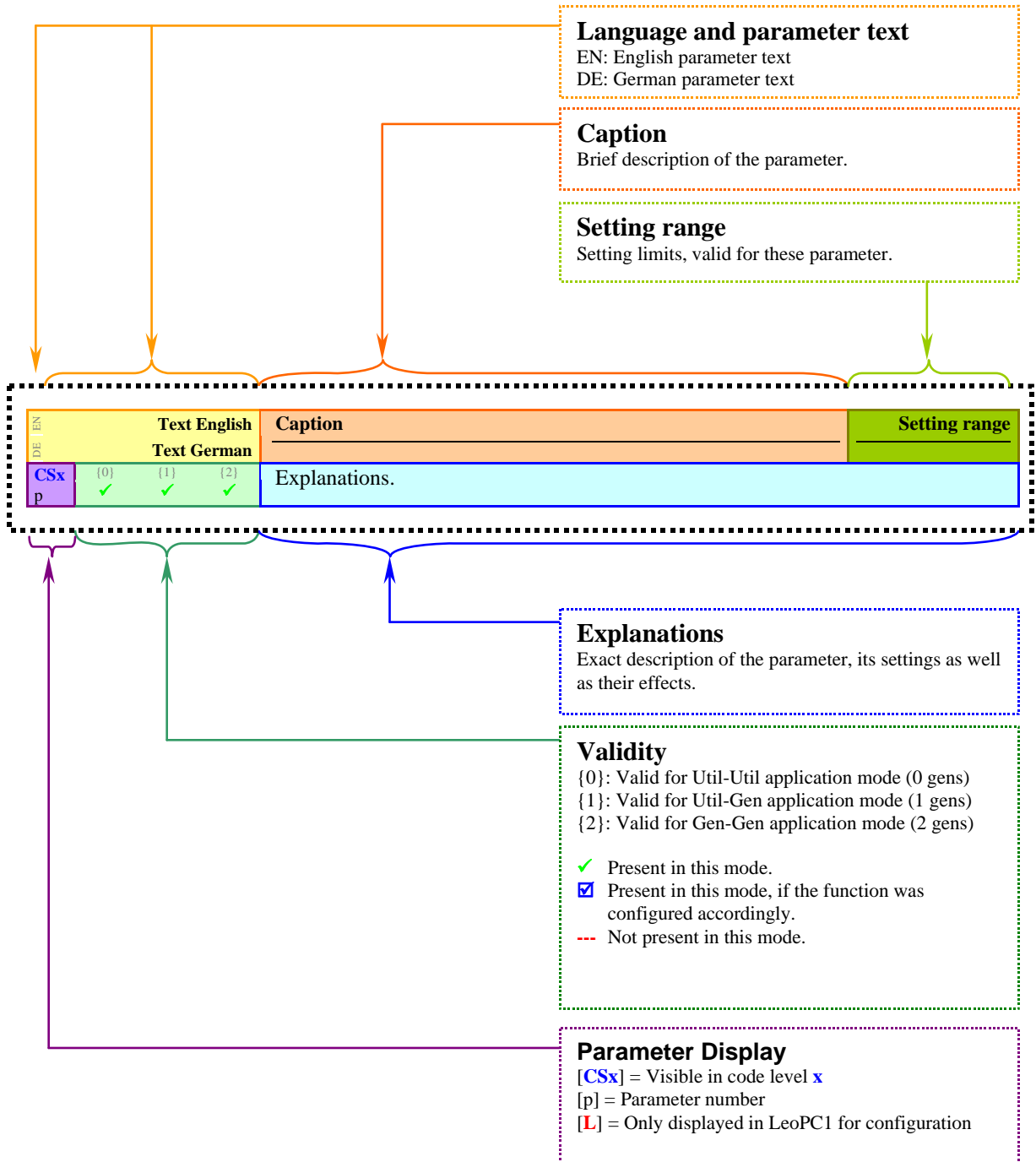
By energizing this relay, an "open from source 1 position to neutral position" command will be issued to the ATS.

Command: open from source 2 position to neutral position{all} *pre-defined* to relay [R9], terminals 48/49
⇒ **Note: Normally open (make) contact!**

By energizing this relay, an "open from source 2 position to neutral position" command will be issued to the ATS.

Chapter 3. Parameters

The description of the parameters is confined to the illustration via the PC-program. The parameters are thereby described as follows.



Language



The following parameter is used to set the unit display language.

EN	Language			
DE	Language			
CS0	{0}	{1}	{2}	
1700	✓	✓	✓	

Set language

English / Deutsch

The desired language for the unit display text is configured here.

Password



The DTSC-200 utilizes a password protected multi-level configuration access hierarchy. This permits varying degrees of access to the parameters being granted by assigning unique passwords to designated personnel. A distinction is made between the access levels as follows:

Code level CL0 (User Level)

Standard password = none

This code level permits for monitoring of the system and limited access to the parameters. Configuration of the control is not permitted. Only the parameters for setting the language, the date, the time, and the horn reset time are accessible. The unit powers up in this code level.

Code level CL1 (Basic Level)

Standard password = "0 0 0 1"

This code level entitles the user to change selected non-critical parameters, such as setting the parameters accessible in CL0 plus Bar/PSI, °C/°F. The user may also change the password for level CL1. Access granted by this password expires two hours after the password has been entered and the user is returned to the CL0 level.

Code level CL2 (Temporary Commissioning Level)

No standard password available

This code level grants temporary access to most of the parameters. The password is calculated from the random number generated when the password is initially accessed. It is designed to grant a user one-time access to a parameter without having to give him a reusable password. The user may also change the password for level CL1. Access granted by this password expires two hours after the password has been entered and the user is returned to the CL0 level. The password for the temp. commissioning level may be obtained from the vendor.

Code level CL3 (Commissioning Level)

Standard password = "0 0 0 3"

This code level grants complete and total access to most of the parameters. In addition, the user may also change the passwords for levels CL1, CL2 and CL3. Access granted by this password expires two hours after the password has been entered and the user is returned to the CL0 level.



NOTE

Once the code level is entered, access to the configuration menus will be permitted for two hours or until another password is entered into the control. If a user needs to exit a code level then code level, CL0 should be entered. This will block unauthorized configuration of the control. A user may return to CL0 by allowing the entered password to expire after two hours or by changing any one digit on the random number generated on the password screen and entering it into the unit.

It is possible to disable expiration of the password by entering "0000" after the CL1 or CL3 password has been entered. Access to the entered code level will remain enabled until another password is entered. Otherwise, the code level would expire when loading the standard values (default 0000) via LeoPC 1.

EN	Password			
DE	Password			
CS0	{0}	{1}	{2}	
10416	✓	✓	✓	

Password: Entry via front panel

0000 to 9999

The password for configuring the control via the front panel must be entered here.

Event History



The event history is a FIFO (First In/First Out) memory for logging alarm events and operation states of the unit. The capacity of the event history is 300 entries. As new event messages are entered into the history, the oldest messages are deleted once 300 events have occurred.

The individual alarm messages, which are stored in the event history, are described in detail in Appendix A: Operation of manual 37387. The operation states, which are stored in the event history, are listed in the table below.

The event history display is password-protected.

Refer to Appendix B: GetEventLog starting at page 120 for a description about reading out the event logger using a software tool.

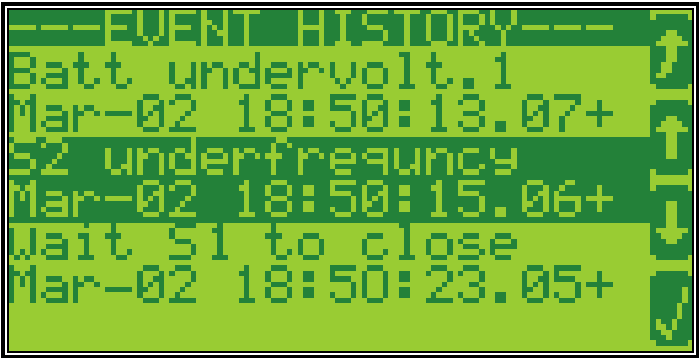





Figure 3-1: Event history- display

NOTE

The button deletes the highlighted entry!

A date/time stamp is added to each entry. Additional characters (+ and -) indicate the state of the alarm. The "+" character indicates an alarm condition that is still active. If the alarm conditions are no longer present anymore, the "+" character will be changed to "-".

DE	Event history display			Event history: Display event history	Info
	Ereignisspeicher anzeigen				
CL2	{0}	{1}	{2}	Individual entries can be selected with the  or  keys and deleted from the event history with the  key.	
	✓	✓	✓		










NOTE

Refer to Table 3-17 on page 122 for a complete list of all entries, which may appear in the event history.

DE	Clear event log			Event history: Clear event history	YES / NO
	Ereignisspeicher löschen				
CL2 1706	(0) ✓	(1) ✓	(2) ✓	YES..... The complete event history will be deleted. After the event history has been deleted, this parameter changes back to "NO" automatically.	
				NO..... The event history will not be deleted.	


Measuring





NOTE
This controller is available in two different hardware version with either 1A [../1] or 5A [../5] current transformer inputs. Both versions are discussed in this manual. The set points for specific parameters will differ depending upon the hardware version.



**NOTE**
It is absolutely necessary for correct rated voltage values to be entered, as many measurement and monitoring functions refer to these values.

Measuring: Rated Values

EN

Rated system frequency

50/60 Hz

CL2

Nennfrequenz im System

1750

{0}

{1}

{2}

✓

✓

✓

The rated frequency of the system is used as a reference figure for all frequency related functions, which use a percentage value, like frequency monitoring or breaker operation windows.

EN

Rated voltage source 1

50 to 650,000 V

CL2

Nennspannung S1

1774

{0}

{1}

{2}

✓

✓

✓

① This value refers to the rated voltage of source 1 and is the voltage measured on the potential transformer primary.

The source 1 potential transformer primary voltage is entered in this parameter. The source 1 rated voltage is used as a reference figure for all source 1 voltage related functions, which use a percentage value, like utility voltage monitoring or breaker operation windows.

EN

Rated voltage source 2

50 to 650,000 V

CL2

Nennspannung S2

1772

{0}

{1}

{2}

✓

✓

✓

① This value refers to the rated voltage of source 2 and is the voltage measured on the potential transformer primary.

The source 2 potential transformer primary voltage is entered in this parameter. The source 2 rated voltage is used as a reference figure for all source 2 voltage related functions, which use a percentage value, like utility voltage monitoring or breaker operation windows.

EN	S1 voltage measuring		
DE	S1 Spannungsmessung		
CL2	{0}	{1}	{2}
1862	✓	✓	✓

Measurement principle: Source 1

3Ph 4W / 3Ph 3W / 1Ph 2W / 1Ph 3W

① Please refer to the comments on measuring principles in the installation manual (37385).

3Ph 4W Measurement is performed Line-Neutral (WYE connected system). Phase voltages and the neutral must be connected for proper calculation. The measurement, display and protection are adjusted according to the rules for WYE connected systems. Monitoring refers to the following voltages:

- V_{L12} , V_{L23} , and V_{L31} , or
- V_{L1N} , V_{L2N} and V_{L3N} .

3Ph 3W Measurement is performed Line-Line (Delta connected system). Phase voltages must be connected for proper calculation. The measurement, display and protection are adjusted according to the rules for Delta connected systems. Monitoring refers to the following voltages:

- V_{L12} , V_{L23} , V_{L31} .

1Ph 2W Measurement is performed for single-phase systems. The measurement, display and protection are adjusted according to the rules for single-phase systems. Monitoring refers to the following voltages:

- V_{L1N} , V_{L12}

1Ph 3W Measurement is performed Line-Neutral (WYE connected system). The measurement, display, and protection are adjusted according to the rules for single-phase systems. Monitoring refers to the following voltages:

- V_{L1N} , V_{L3N} .

EN	S2 voltage measuring		
DE	S2 Spannungsmessung		
CL2	{0}	{1}	{2}
1861	✓	✓	✓

Measurement principle: Source 2

3Ph 4W / 3Ph 3W / 1Ph 2W / 1Ph 3W

① Please refer to the comments on measuring principles in the installation manual (37385).

3Ph 4W Measurement is performed Line-Neutral (WYE connected system). Phase voltages and the neutral must be connected for proper calculation. The measurement, display and protection are adjusted according to the rules for WYE connected systems. Monitoring refers to the following voltages:

- V_{L12} , V_{L23} , and V_{L31} , or
- V_{LIN} , V_{L2N} and V_{L3N} .

3Ph 3W Measurement is performed Line-Line (Delta connected system). Phase voltages must be connected for proper calculation. The measurement, display and protection are adjusted according to the rules for Delta connected systems. Monitoring refers to the following voltages:

- V_{L12} , V_{L23} , V_{L31} .

1Ph 2W Measurement is performed for single-phase systems. The measurement, display and protection are adjusted according to the rules for single-phase systems. Monitoring refers to the following voltages:

- V_{LIN} , V_{L12}

1Ph 3W Measurement is performed Line-Neutral (WYE connected system). The measurement, display, and protection are adjusted according to the rules for single-phase systems. Monitoring refers to the following voltages:

- V_{LIN} , V_{L3N} .

EN	Def. of 1PH2W measuring		
DE	Def. von 1PH2W Messung		
CL2	{0}	{1}	{2}
1858	✓	✓	✓

Measurement principle: 1Ph 2W measuring

phase-phase / phase-neutral

① Please refer to the comments on measuring principles in the installation manual (37385).

This parameter is only visible, if Parameter 1862 and/or Parameter 1861 is configured as "1Ph 2W".

phase-phase. The phase-phase voltages are monitored for 1Ph 2W measuring.

phase-neut... The phase-neutral voltages are monitored for 1Ph 2W measuring.

EN	Def. of 1PH 2W Phase rotation		
DE	Def. von 1PH 2W Drehrichtung		
CL2	{0}	{1}	{2}
1859	✓	✓	✓

Measurement principle: 1Ph 2W phase rotation

CW / CCW

① Please refer to the comments on measuring principles in the installation manual (37385).

This parameter is only visible, if Parameter 1862 and/or Parameter 1861 is configured as "1Ph 2W".

CW A clockwise rotation field is considered for 1Ph 2W measuring .

CCW A counter-clockwise rotation field is considered for 1Ph 2W measuring.

EN	Load current measuring		
DE	Last Strommessung		
CL2	{0}	{1}	{2}
1860	✓	✓	✓

Measurement principle: Load current

L1 L2 L3 / Phase L1 / Phase L2 / Phase L3

① Please refer to the comments on measuring principles in the installation manual (37385).

L1 L2 L3..... All three phases are monitored. The measurement, display and protection are adjusted according to the rules for 3-phase measurement. Monitoring refers to the following currents:

- I_{L1} , I_{L2} , I_{L3} .

Phase L{1/2/3} Only one phase is monitored. The measurement, display and protection are adjusted according to the rules for single-phase measurement. Monitoring refers to the selected phase.

**NOTE**

It is absolutely necessary for correct rated power and current values to be entered, as many measurement and monitoring functions refer to these values.

EN	Rated active power [kW]		
DE	Nennwirkleistung [kW]		
CL2	{0}	{1}	{2}
1752	✓	✓	✓

Rated active power

0.5 to 99,999.9 kW

This value specifies the rated power.

EN	Rated current		
DE	Nennstrom Generator		
CL2	{0}	{1}	{2}
1754	✓	✓	✓

Rated current

5 to 32,000 A

This value specifies the rated current.

Measuring: Transformers

Voltage Transformer

EN	S1 voltage transf. primary		
DE	S1 Spannungswandler primär		
CL2	{0}	{1}	{2}
1819	✓	✓	✓

Voltage transformer, source 1, primary

50 to 650,000 V

Some applications may require the use of potential transformers to facilitate measuring the source voltages. The rating of the primary side of the potential transformer on source 1 must be entered into this parameter.
If the application does not require potential transformers (i.e. the generated voltage is 480 V or less), then the source volt. will be entered into this parameter.

EN	S1 voltage transf. secondary		
DE	S1 Spannungswandler sekund.		
CL2	{0}	{1}	{2}
1818	✓	✓	✓

Voltage transformer, source 1, secondary

50 to 480 V

④ The control is equipped with dual voltage measuring inputs. The voltage range of these measurement inputs is dependent upon input terminals are used (see below). This value refers to the secondary voltages of the potential transformers, which are directly connected to the control.

Some applications may require the use of potential transformers to facilitate measuring the source voltages. The rating of the secondary side of the potential transformer on source 1 must be entered into this parameter.
If the application does not require potential transformers (i.e. the generated voltage is 480 V or less), then the source volt. will be entered into this parameter.

- Rated voltage: 100 Vac (this parameter configured between 50 and 130 V)
 - Source 1 voltage: Terminals 15/17/19/21
- Rated voltage: 400 Vac (this parameter configured between 131 and 480 V)
 - Source 1 voltage: Terminals 16/18/20/22

EN	S2 volt. transf. primary		
DE	S2 Spannungswandler primär		
CL2	{0}	{1}	{2}
1816	✓	✓	✓

Voltage transformer, source 2, primary

50 to 650,000 V

Some applications may require the use of potential transformers to facilitate measuring the source voltages. The rating of the primary side of the potential transformer on source 2 must be entered into this parameter.
If the application does not require potential transformers (i.e. the generated voltage is 480 V or less), then the source volt. will be entered into this parameter.

EN	S2 volt. transf. secondary		
DE	S2 Spannungswandler sekund.		
CL2	{0}	{1}	{2}
1815	✓	✓	✓

Voltage transformer, source 2, secondary

50 to 480 V

④ The control is equipped with dual voltage measuring inputs. The voltage range of these measurement inputs is dependent upon input terminals are used (see below). This value refers to the secondary voltages of the potential transformers, which are directly connected to the control.

Some applications may require the use of potential transformers to facilitate measuring the source voltages. The rating of the secondary side of the potential transformer on source 2 must be entered into this parameter.
If the application does not require potential transformers (i.e. the generated voltage is 480 V or less), then the source volt. will be entered into this parameter.

- Rated voltage: 100 Vac (this parameter configured between 50 and 130 V)
 - Source 2 voltage: Terminals 23/25/27/29
- Rated voltage: 400 Vac (this parameter configured between 131 and 480 V)
 - Source 2 voltage: Terminals 24/26/28/30

Current Transformer



NOTE

This controller is available in two different hardware version with either 1A [../1] or 5A [../5] current transformer inputs. Both versions are discussed in this manual. The set points for specific parameters will differ depending upon the hardware version, indicated on the data plate.

- [1] DTSC-200-1 = Current transformer with ../1 A rated current
- [5] DTSC-200-5 = Current transformer with ../5 A rated current

EN	Load Current transformer			Current transformer, load	1 to 32,000/5 A
	Last Stromwandler				
CL2 1821	{0} ✓	{1} ✓	{2} ✓	This screen only applies to controls equipped with 5 A CT inputs. This will not be displayed in the controller screen of a unit equipped with 1 A CT inputs.	

The input of the current transformer ratio is necessary for the indication and control of the actual monitored value. The current transformers ratio should be selected so that at least 60% of the secondary current rating can be measured when the monitored system is at 100% of operating capacity (i.e. at 100% of system capacity a 5 A CT should output 3 A). If the current transformers are sized so that the percentage of the output is lower, the loss of resolution may cause inaccuracies in the monitoring and control functions and affect the functionality of the control.

EN	Load Current transformer			Current transformer, load	1 to 32,000/1 A
	Last Stromwandler				
CL2 1822	{0} ✓	{1} ✓	{2} ✓	This screen only applies to controls equipped with 1 A CT inputs. This will not be displayed in the controller screen of a unit equipped with 5 A CT inputs.	

The input of the current transformer ratio is necessary for the indication and control of the actual monitored value. The current transformers ratio should be selected so that at least 60% of the secondary current rating can be measured when the monitored system is at 100% of operating capacity (i.e. at 100% of system capacity a 5 A CT should output 3 A). If the current transformers are sized so that the percentage of the output is lower, the loss of resolution may cause inaccuracies in the monitoring and control functions and affect the functionality of the control.

Application



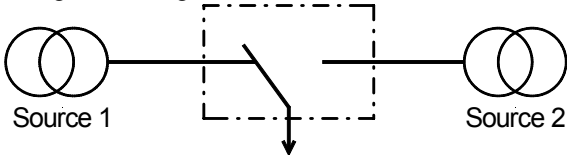
Application: Application Mode

EN	Application mode		
DE	Betriebsmodus		
CL2	{0}	{1}	{2}
4148	✓	✓	✓

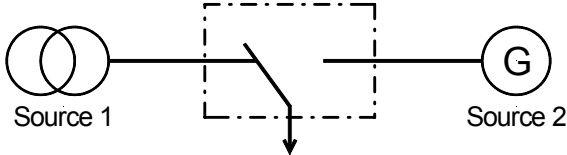
Application mode	Util-Gen / Gen-Gen / Util-Util
------------------	--------------------------------

This parameter selects the basic function of the unit. If the unit is used to transfer the load between two utility sources (setting "Util-Util"), no engine start signals are issued.

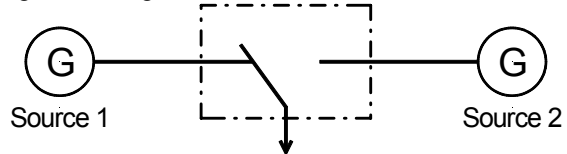
Util-Util.....Application "utility-utility" {0}
No engine start signals will be issued.



Util-Gen.....Standard application "utility-generator" {1}
Engine start signals will be issued for source 2 only.



Gen-Gen.....Application "generator-generator" {2}
Engine start signals will be issued for source 1 and source 2.



NOTE

In Util-Gen application, source S2 is considered as the generator.

Application: Transfer Timers

Transfer commit				YES / NO
	Transfer zustimmen			
CL2	{0}	{1}	{2}	This function is only effective if a transfer from the preferred source to the non-preferred source is requested.
4146	---	✓	---	
<p>YES..... A transfer to the non-preferred source is committed as soon as the non-preferred source stable timer has started to count. The transfer will be performed after the stable timer has expired, even if the preferred source restores.</p> <p>NO..... A transfer to the non-preferred source is only committed, if the non-preferred source stable timer has expired completely. If the preferred source restores while the non-preferred source stable timer is still counting, the whole process will be aborted and the transfer switch remains on the preferred source.</p>				

DE EN	S1 start delay time			Source 1 start delay time	1 to 300 s
	S1 Startverzögerung				
CL2	{0}	{1}	{2}	<p>This parameter delays the de-energizing of the start relay (and thus the engine start) if source 2 is considered as "not OK" or a start, "Load Test", " No Load Test", remote peak shave or interruptible power rates request is performed.</p> <p>The counter starts as soon as source 2 is considered as "not OK" or the start request is initiated.</p> <p>If source 2 returns before this counter has expired, the timer will be terminated and the controller returns to standby mode (since it is not intended that the engine starts with every short temporary line fault).</p> <p>If the timer has expired and source 2 has not been considered as "OK", the engine start relay will be de-energized, the engine will be started, and flag 20.05 "S1 Start Signal" will be enabled.</p> <p>If this timer is running, the "S1 start delay" message and the Bypass softkey are displayed.</p>	
4149	---	---	✓		

DE EN	S2 start delay time			Source 2 start delay time	1 to 300 s
	S2 Startverzögerung				
CL2	{0}	{1}	{2}	<p>This parameter delays the de-energizing of the start relay (and thus the engine start) if source 1 is considered as "not OK" or a start, "Load Test", " No Load Test", remote peak shave or interruptible power rates request is performed.</p> <p>The counter starts as soon as source 1 is considered as "not OK" or the start request is initiated.</p> <p>If source 1 returns before this counter has expired, the timer will be terminated and the controller returns to standby mode (since it is not intended that the engine starts with every short temporary line fault).</p> <p>If the timer has expired and source 1 has not been considered as "OK", the engine start relay will be de-energized, the engine will be started, and flag 20.06 "S2 Start Signal" will be enabled.</p> <p>If this timer is running, the "S2 start delay" message and the Bypass softkey are displayed.</p>	
3330	---	✓	✓		

EN	S1 Source Stable time		
DE	S1 Stabilisierungszeit		
CL2	{0}	{1}	{2}
3333	✓	✓	✓

Source 1 source stable time**1 to 6500 s**

This parameter configures the delay before source 1 is considered as OK. This timer starts after the last monitored value has returned within the restore limits following a source 1 outage. Source 1 will be considered as OK again after this timer has expired. If the voltage and/or frequency exceeds the restore limits again before the timer expires, the timer will be reset (refer to Figure 3-2).

The source 1 stable timer is automatically bypassed if source 1 is the preferred source and the outage delay of source 2 (non-preferred) has expired.

If source 1 fails unexpectedly before this timer has expired, it will be terminated and the load will still be supplied by source 2.

This timer is intended to delay the transfer to ensure that source 1 voltage and frequency are definitely stable before the ATS switch is operated to perform a transfer to source 1.

If this timer is running, the "S1 stable timer" message and the Bypass softkey are displayed.

**NOTE**

In case a "load test" is being performed (i.e. the load is supplied by source 2, but source 1 is present as well and OK) and source 2 fails, the "S1 source stable timer" will be bypassed completely to be able to change back (OK) to source 1 immediately. This is intended to ensure that the load is not de-energized if a genset failure takes place during a load test.

EN	S2 Source Stable time		
DE	S2 Stabilisierungszeit		
CL2	{0}	{1}	{2}
3332	✓	✓	✓

Source 2 source stable time**1 to 6500 s**

This parameter configures the delay before source 2 is considered as OK. This timer starts after the last monitored value has returned within the restore limits following a source 2 outage. Source 2 will be considered as OK again after this timer has expired. If the voltage and/or frequency exceeds the restore limits again before the timer expires, the timer will be reset (refer to Figure 3-2).

The source 2 stable timer is automatically bypassed if source 2 is the preferred source and the outage delay of source 1 (non-preferred) has expired.

If source 2 fails unexpectedly before this timer has expired, it will be terminated and the load will still be supplied by source 1.

This timer is intended to delay the transfer to ensure that source 2 voltage and frequency are definitely stable before the ATS switch is operated to perform a transfer to source 2.

If this timer is running, the "S2 stable timer" message and the Bypass softkey are displayed.

	S1 outage delay		
	S1 Ausfallverzögerung		
EN	{0}	{1}	{2}
CL2	---	---	✓
2804	---	---	✓

Source 1 outage delay**0.1 to 10.0 s**

This timer defines the maximum time before source 1 (voltage, frequency and phase rotation) is considered as "not OK" to initiate a transfer to source 2. This timer starts if one of the monitored source 1 values exceeds the fail limits. Source 1 will be considered as "not OK", after this timer has expired. If the voltage and/or frequency returns within the fail limits before the timer expires, the timer will be reset (refer to Figure 3-2).

This timer is intended to prevent an immediate transfer to source 2 in case of a temporary voltage or frequency drop during a load test due to a short temporary failure of source 1 (i.e. ignition miss of a genset, etc.).

If this timer has expired, the alarm "Unint. stop S1" is issued.

Note: If source 2 is the "preferred source" and the "S1 outage delay" timer has expired (i.e. source 1 is considered as "not OK"), the "S2 source stable timer" will be bypassed.

	S2 outage delay		
	S2 Ausfallverzögerung		
EN	{0}	{1}	{2}
CL2	---	✓	✓
2803	---	✓	✓

Source 2 outage delay**0.1 to 10.0 s**

This timer defines the maximum time before source 2 (voltage, frequency and phase rotation) is considered as "not OK" to initiate a transfer to source 1. This timer starts if one of the monitored source 2 values exceeds the fail limits. Source 2 will be considered as "not OK", after this timer has expired. If the voltage and/or frequency returns within the fail limits before the timer expires, the timer will be reset (refer to Figure 3-2).

This timer is intended to prevent an immediate transfer to source 1 in case of a temporary voltage or frequency drop during a load test due to a short temporary failure of source 2 (i.e. ignition miss of a genset, etc.).

If this timer has expired, the alarm "Unint. stop S2" is issued.

Note: If source 1 is the "preferred source" and the "S2 outage delay" timer has expired (i.e. source 2 is considered as "not OK"), the "S1 source stable timer" will be bypassed.

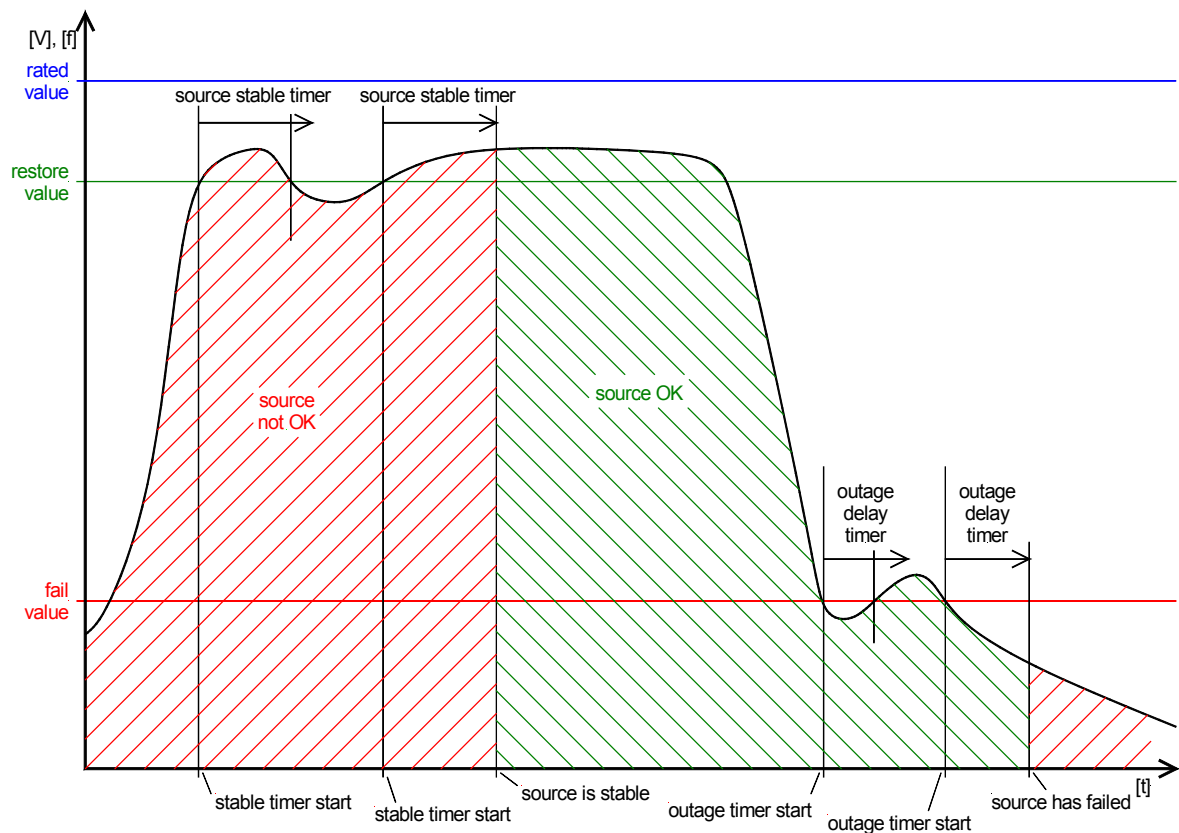


Figure 3-2: Source stable and outage timers



NOTE

Figure 3-2 describes the principle of stable and outage timers for an example where a threshold needs to be exceeded to consider the source as "OK" (like underfrequency or undervoltage). In case, a threshold needs to be fallen below to consider the source as "OK" (like overfrequency, voltage imbalance or overvoltage), the restore value is lower than the fail value.

	S1 cooldown time		
	S1 Nachlaufzeit		
CL2	{0}	{1}	{2}
3343	---	---	✓

Engine 1 cooldown time1 to 6500 s

This parameter configures the duration of the cool down phase of engine 1 after the load has been disconnected.

If this timer is running, the "S1 cooldown" message and the Bypass softkey are displayed.

	S2 cooldown time		
	S2 Nachlaufzeit		
CL2	{0}	{1}	{2}
3344	---	✓	✓

Engine 2 cooldown time1 to 6500 s

This parameter configures the duration of the cool down phase of engine 2 after the load has been disconnected.

If this timer is running, the "S2 cooldown" message and the Bypass softkey are displayed.

Application: Transfer Logics (*LogicsManager*)



NOTE

All functions which are described in the following text may be assigned by the *LogicsManager* to any relay which is available via the *LogicsManager* and not assigned to another function. The assignment of the defined relays to defined functions occurs by selection of the application mode. The same way some relays are designated to specific functions, others may be assigned to different functions. These are listed as "programmed" relays. If a relay is "programmable" the function may be assigned to other relays via the *LogicsManager* by configuration.

Inhibit ATS

If this logical output becomes TRUE, the ATS controller is blocked against automatic transfers and the "ATS Inhibit" message is displayed. Usually, a selected relay output is configured to this *LogicsManager* function, which may be used to block the ATS controller when a disconnect switch is connected to this "Inhibit ATS" relay output.

All automatic transfers will be blocked. Only the "Engine start" signal will still be issued.

EN		Inhibit ATS		Inhibit ATS		<i>LogicsManager</i>	
DE		Blockiere ATS				The <i>LogicsManager</i> and its default settings are explained on page 99 in Appendix A: " <i>LogicsManager</i> ".	
CL2	{0}	{1}	{2}				
12600	✓	✓	✓				



NOTE

The disconnect switch is ALWAYS inside the ATS cabinet. If the ATS shall be operated manually, the disconnect switch will be switched to the "Inhibit ATS" position. This blocks the ATS controller against the automatic initiation of a transfer and the switch may easily be operated manually.



WARNING

If the ATS controller performs a transfer during a service technician switches the ATS with a manual handle, this may cause serious injuries.

Always inhibit automatic ATS transfers before performing a manual transfer!

Inhibit Transfer to Source 1

If this logical output becomes TRUE, the transfer back to source 1 will be blocked temporarily and the "Inhib. XFR to S1" message is displayed.

Application example:

Supposed, there is a failure of source 1 (preferred source) in a hospital. Then, source 2 will be started and a transfer to source 2 will be performed. Now, the load is supplied by source 2.

If source 1 would return, a transfer back to source 1 would be initiated. This may be prevented by making this *LogicsManager* function TRUE (by energizing a DI for example) because a transfer back to source 1 may cause some risks if a difficult surgery is in progress for example. A mechanical failure of the transfer switch during transferring back would be a serious risk for the patient.

EN	Inhib. XFR to S1		
DE	Trans S1 sperren		
CL2 12610	{0} ✓	{1} ✓	{2} ✓

Inhibit transfer to source 1

LogicsManager

The *LogicsManager* and its default settings are explained on page 99 in Appendix A: "*LogicsManager*".

Inhibit Transfer to Source 2

If this logical output becomes TRUE, the transfer to source 2 will be blocked temporarily and the "Inhib. XFR to S2" message is displayed.

This function has the same behavior as the "Inhibit XFR to source 1" function, except that a transfer to source 2 will be prevented.

EN	Inhib. XFR to S2		
DE	Trans S2 sperren		
CL2 12620	{0} ✓	{1} ✓	{2} ✓

Inhibit transfer to source 2

LogicsManager

The *LogicsManager* and its default settings are explained on page 99 in Appendix A: "*LogicsManager*".

Remote Peak Shave

If this logical output becomes TRUE, the non-preferred source will be started, a transfer to the non-preferred source will be performed, and the "Rem.peak shave" message is displayed as soon as the non-preferred source supplies the load. Now, the load will be supplied by the non-preferred source. If the logical output becomes FALSE again, a regular transfer sequence back to the preferred source will be performed including the expiry of all timers belonging to this sequence.

If the non-preferred source fails during a remote peak shave request and the preferred source is available, an immediate transfer back to the preferred source will be performed.

This function may be used to initiate a load test.

EN	Remote peak shave		
DE	Spitzenlast Modus		
CL2 12630	{0} ✓	{1} ✓	{2} ✓

Remote peak shave

LogicsManager

The *LogicsManager* and its default settings are explained on page 99 in Appendix A: "*LogicsManager*".

Interruptible Power Rate Provisions

If this logical output becomes TRUE, the non-preferred source will be started, a transfer to the non-preferred source will be performed, and the "Pwr.rate.prov." message is displayed as soon as the non-preferred source supplies the load. Now, the load will be supplied by the non-preferred source. If the logical output becomes FALSE again, a regular transfer sequence back to the preferred source will be performed including the expiry of all timers belonging to this sequence.

If the non-preferred source fails during an interruptible power rate provisions request and the preferred source is available, an immediate transfer back to the preferred source will be performed.

This function may be used in some countries where the provider offers contracts, which contain provisions for the customer to disconnect from the utility during peak load times and change to a different power supply (e.g. genset), like the United States. In case the alternative (genset) supply fails during a "Interruptible power rate provisions" request, a transfer to the preferred source will be performed with the effect that the customer must pay a reimbursement to the provider.

EN		Int. pow. rates			Interruptible power rate provisions	<i>LogicsManager</i>
DE		Anforder. Netzbetr.				
CL2	{0}	{1}	{2}		The <i>LogicsManager</i> and its default settings are explained on page 99 in Appendix A: " <i>LogicsManager</i> ".	
12660	✓	✓	✓			

External Timer Bypass

If this logical output becomes TRUE (by energizing a DI for example), all timers, which are in progress at the moment and can be bypassed, are bypassed. This has the same effect as pressing the "Bypass" softkey.

EN		Ext. bypass			External timer bypass	<i>LogicsManager</i>
DE		Ext. Zeit Bypass				
CL2	{0}	{1}	{2}		The <i>LogicsManager</i> and its default settings are explained on page 99 in Appendix A: " <i>LogicsManager</i> ".	
12820	✓	✓	✓			



NOTE

If another timer becomes active immediately after the previous timer has been bypassed, the discrete input must be de-energized before it may be energized again to bypass the next timer. We recommend to use a momentary push-to-make button for this function.

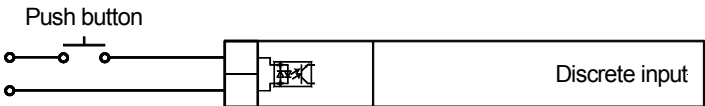


Figure 3-3: External timer bypass - push button

Gen-Gen Enable

This function is only enabled if the application mode (Parameter 4148) is configured to "Gen-Gen". If this logical output becomes TRUE (by energizing a DI for example), the gen-gen mode will be enabled.

The behavior of the function depends on the source priority:

- Only the *LogicsManager* function "Source priority S1" (Parameter 12680) is TRUE:
The source 1 genset will be started. If source 1 doesn't start or fails, source 2 genset will be started automatically.
- Only the *LogicsManager* function "Source priority S2" (Parameter 12810) is TRUE:
The source 2 genset will be started. If source 2 doesn't start or fails, source 1 genset will be started automatically.
- Both source priority *LogicsManager* functions (Parameters 12680 and 12810) are TRUE or both are FALSE:
Source 1 has priority, i.e. the source 1 genset will be started. If source 1 doesn't start, source 2 genset will be started automatically.

If the gen-gen mode will be disabled again, all start requests are terminated and the genset, which is currently in operation, will be shut down with a cool down.

DE	EN	Gen-Gen enable			Generator-Generator mode enable	<i>LogicsManager</i>
		Gen-Gen Aktivieren				
CL2	{0}	{1}	{2}	The <i>LogicsManager</i> and its default settings are explained on page 99 in Appendix A: " <i>LogicsManager</i> ".		
12830	---	---	✓			

Application: Elevator Pre-Signal

The elevator pre-signal flag (20.01) may be assigned to any output relay using the *LogicsManager*.

The elevator pre-signal is important for buildings which are equipped with elevators. This signal will be enabled before any transfer in order to signal a transfer to an elevator control. If this signal is received by an elevator control, the elevator stops at the next floor and opens the doors. This signal is enabled until the transfer is completed. Then, the signal will be disabled and the elevator is able to operate regularly again.

This function may be used if there is a load test performed during regular hospital operation. A load test means that two sources are available. This signal will not be set in case of a utility failure. In this case, the elevator might get stuck between two floors and it makes no sense to enable the elevator pre-signal. Possibly stuck elevators are accepted and the main target is to attempt to supply the load. As soon as the supply returns, the elevators are ready to operate again.



NOTE

The elevator pre signal (EPS) may be enabled in parallel with a motor load disconnect signal (MLD) if a MLD signal is configured. EPS and MLD are two functions, which operate completely independent and don't affect each other.

If the EPS timer will be bypassed, the MLD signal will be processed consequently (if configured). Otherwise, the transfer sequence will be continued. If the transfer has been performed, the EPS signal will be reset. This is also valid, if the EPS signal has been bypassed prior to the transfer and a MLD timer was configured additionally.

This timer is automatically bypassed, if not both sources are available (and stable) for transfer.

If, for example, a load test has been requested and cancelled again while the EPS signal is active, the EPS relay will be reset automatically and the complete process will be terminated.

EN	Elevator Pre Signal			Elevator pre-signal	ON / OFF
DE	Aufzugswarnsignal				
CL2	{0}	{1}	{2}	OFF.....	No elevator pre-signal is issued, no elevator pre-signal timer starts and the <i>LogicsManager</i> flag 20.01 is not enabled.
4490	✓	✓	✓	ON.....	The elevator pre-signal will be issued before any transfer and the <i>LogicsManager</i> flag 20.01 will be enabled. The remaining elevator pre-signal time is displayed.
EN	Elevator pre-signal duration			Elevator pre-signal duration	1 to 6500 s
DE	Warnsignal Dauer				
CL2	{0}	{1}	{2}	The time configured here determines how long the elevator pre-signal is enabled before the transfer process will be continued. The signal will be disabled again if the transfer process has been completed. If this timer is running, the "Pre signal timer" message is displayed.	
4491	✓	✓	✓		

The following examples show the behavior of the elevator pre-signal for different applications.

Example 1 (elevator pre-signal disabled):

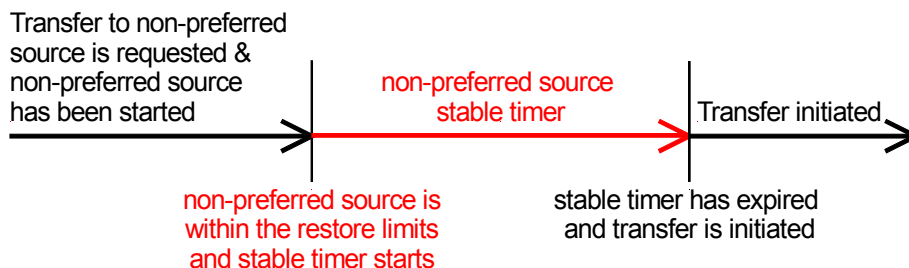


Figure 3-4: Elevator pre-signal - example 1

Example 2 (elevator pre-signal enabled):

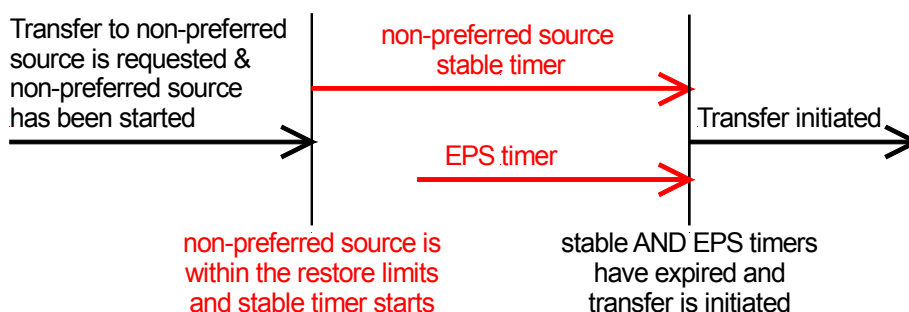


Figure 3-5: Elevator pre-signal - example 2

This example assumes that the non-preferred source stable timer is configured higher than the EPS timer. If the EPS timer would be configured higher, it would start together with the stable timer and the transfer is initiated if all timers have expired.

Example 3 (elevator pre-signal and motor load disconnect enabled):

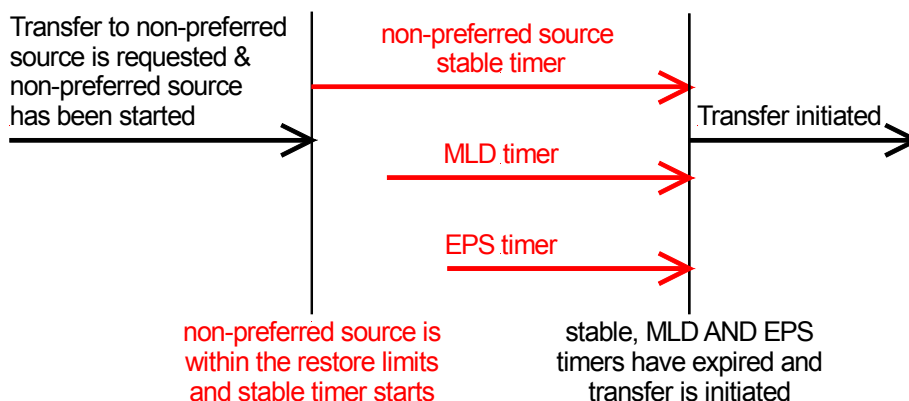


Figure 3-6: Elevator pre-signal - example 3

This example assumes that the non-preferred source stable timer is configured higher than the EPS and the MLD timer. If the EPS or the MLD timer would be configured higher, they would start together with the stable timer and the transfer is initiated if all timers have expired.

Application: Motor Load Disconnect

The motor load disconnect flag (20.02) may be assigned to any output relay using the [LogicsManager](#).

The motor load disconnect function is intended for sequential load shedding before a transfer and sequential load addition after a transfer. This shall prevent the addition of the complete load at once.

The loads will be disconnected one after the other before a transfer. Then, the loads will be connected again in the same order following the transfer.

In contrast to the elevator pre-signal, this signal will also be enabled in case of a preferred source failure. No automatic or manual bypass of this signal will be performed.

Motor Load Disconnect				Motor load disconnect	ON / OFF
EN	Lastabwurf				
DE					
CL2	{0}	{1}	{2}	OFF	No motor load disconnect signal is issued, no motor load disconnect signal timer starts and the LogicsManager flag 20.02 is not enabled. It will be proceeded with the operation of the transfer switch.
4550	✓	✓	✓	ON	The motor load disconnect signal will be issued before any transfer and the LogicsManager flag 20.02 will be enabled. The remaining motor load disconnect signal time is displayed with the "Motor Load Disc." message. After the motor load disconnect timer expires, the transfer switch will be operated. The signal will be disabled again if the transfer process has been completed.

Active direction				Active direction	S1->S2 / S1<-S2 / Both
EN					
DE	Aktive Richtung für Lastabwurf				
CL2	{0}	{1}	{2}	This parameter configures the transfer direction into which the motor load disconnect signal is enabled.	
4553	✓	✓	✓	S1->S2	The motor load disconnect signal is only enabled in this transfer direction. The LogicsManager flag 20.02 will not be enabled when transferring from source 2 to source 1.
				S1<-S2	The motor load disconnect signal is only enabled in this transfer direction. The LogicsManager flag 20.02 will not be enabled when transferring from source 1 to source 2.
				Both	The motor load disconnect signal is always enabled in both transfer directions.

Disconnect time S1->S2				Disconnect time S1 -> S2	1 to 6500 s
EN					
DE	Lastabwurfszeit S1				
CL2	{0}	{1}	{2}	This parameter configures the maximum duration of the motor disconnect signal in source 1 to source 2 transfer direction. After the timer has expired, the transfer to source 2 will be performed	
4551	✓	✓	✓		

Disconnect time S2->S1				Disconnect time S2 -> S1	1 to 6500 s
EN					
DE	Lastabwurfszeit S2				
CL2	{0}	{1}	{2}	This parameter configures the maximum duration of the motor disconnect signal in source 2 to source 1 transfer direction. After the timer has expired, the transfer to source 1 will be performed	
4552	✓	✓	✓		

Application: Source Priority Selection

The two *LogicsManager* functions "Source Priority S1" and "Source Priority S2" are used to determine which source is to be considered as preferred. The *LogicsManager* enables to use a discrete input for example to select the preferred source externally using a source priority selector switch, which is usually on the operation panel.

In general, the preferred source is the one, which is permanently available. The NON-preferred source serves as second source, which will be enabled if the preferred source fails or if a remote start signal is present.

The following constellations are possible:

- One utility supply, one generator (Util-Gen application)
If the utility (source 1) is defined as preferred source, the genset (source 2) will be started if the utility fails.
If the genset is defined as preferred source, the engine start signal is permanently enabled until the source priority changes to the other source.



NOTE

Changing the priority during a load test (parameter 12640), remote peak shave (parameter 12630) or interruptible power rates (parameter 12660) operation is enabled, results in a transfer to the selected non-preferred source.

- Two utility supply networks (Util-Util application)
In this case, the customer might select one utility supply as preferred source. In case of a failure of the preferred source, the load will be transferred to the other source.
- Two generators (Gen-Gen application)
In this case, the customer might select one generator as preferred source. In case of a failure of the preferred source, the other genset will be started and the load will be transferred to the other source.

If the *LogicsManager* function "Source Priority S1" becomes TRUE, source 1 will be considered as preferred.

	S1 Priority		
	S1 Priorität		
CL2 12680	{0} ✓	{1} ✓	{2} ✓

Source Priority S1

LogicsManager

The *LogicsManager* and its default settings are explained on page 99 in Appendix A: "*LogicsManager*".

If the *LogicsManager* function "Source Priority S2" becomes TRUE, source 2 will be considered as preferred.

	S2 Priority		
	S2 Priorität		
CL2 12810	{0} ✓	{1} ✓	{2} ✓

Source Priority S2

LogicsManager

The *LogicsManager* and its default settings are explained on page 99 in Appendix A: "*LogicsManager*".



NOTE

If no source is preferred (both *LogicsManager* functions are FALSE or both *LogicsManager* functions are TRUE), source 1 will be the preferred source.

Application example 1 (source priority = S1):

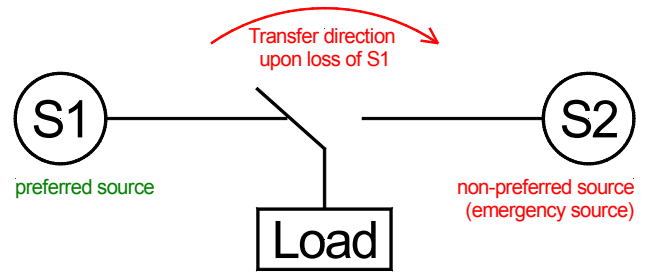


Figure 3-7: Source priority selection - S1 preferred

Application example 2 (source priority = S2):

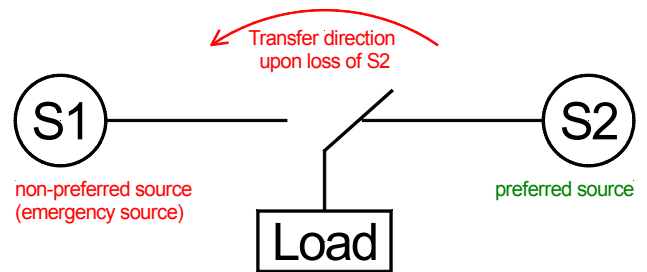


Figure 3-8: Source priority selection - S2 preferred

If the preferred source is available, the load will automatically be connected to the preferred source (except a transfer to the non-preferred source is forced by a load test or remote peak shave, etc.).

It is also possible to change the source priority while the load is connected to the preferred or non-preferred source.

If the load is connected to the non-preferred source and this non-preferred source will be declared as the preferred source, the load remains connected to this source.

If the load is connected to the preferred source and this preferred source will be declared as the non-preferred source, the load will be transferred to the "new" preferred source.

Extended Parallel Time



NOTE

This function is only effective if the transfer switch type (parameter 3424) is configured to "Closed" and in-phase monitoring (parameter 4570) is enabled.

If a closed transition is performed, the overlap time of the make-before-break process, in which both sources are parallel, is as configured in parameter 4577 (Max. overlap time). If this time is to be extended, a *LogicsManager* function is available to keep the transition switch in overlap position. This may be achieved by a digital signal of an external synchronization device for example.

If the *LogicsManager* function "Ext. para. time" becomes TRUE, the transfer switch will remain in overlap position. If it becomes FALSE again, the source, from which the transfer has been initiated, will be disconnected and the load will be supplied by the new source.

EN	Ext. para. time			Extended parallel time	<i>LogicsManager</i>
	Erweiterte para. Zeit				
CL2	{0}	{1}	{2}	The <i>LogicsManager</i> and its default settings are explained on page 99 in Appendix A: " <i>LogicsManager</i> ".	
12860	✓	✓	✓		



NOTE

As long as this function is TRUE, parameter 4577 (Max. overlap time) is not effective.

Exception: If parameter 4577 (Max. overlap time) is configured to 0.1 s, an extended parallel time is not possible regardless of the state of this function.



NOTE

If one source fails as long as this function is TRUE, the failed source will automatically be disconnected.



WARNING

Both sources remain in overlap position as long as this function is TRUE.

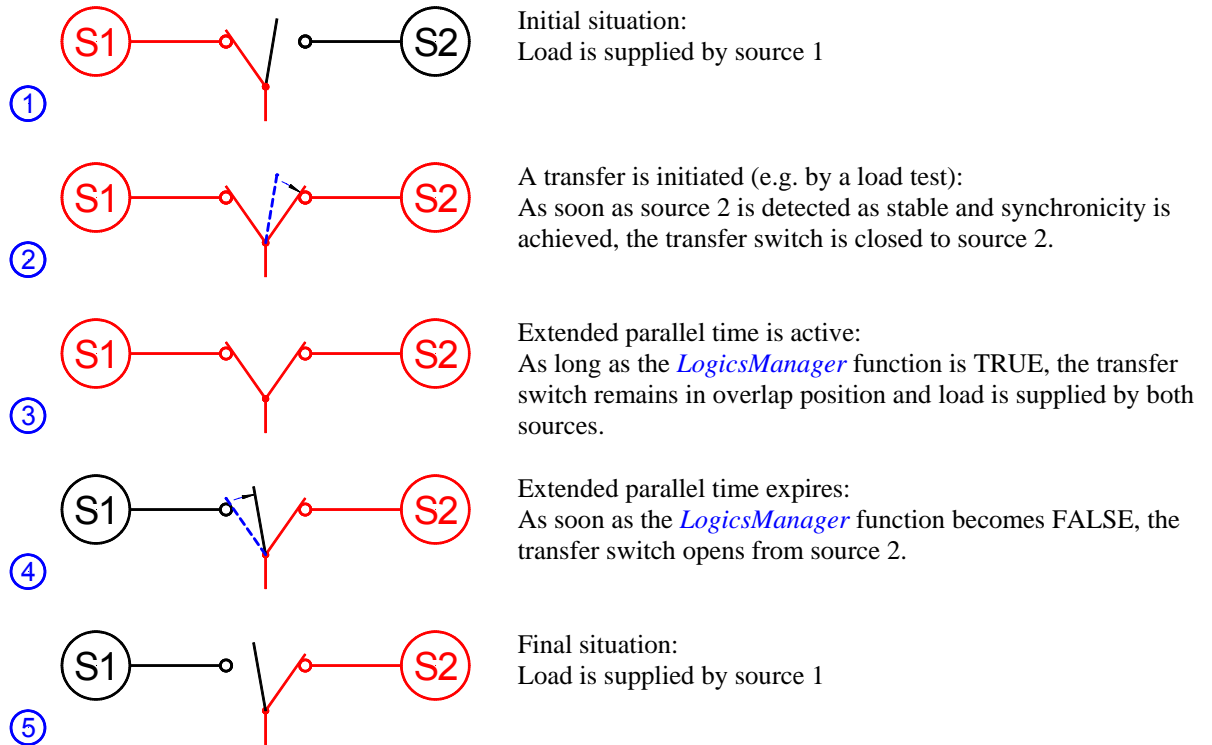
Both sources are not decoupled if

- a load test (parameter 12640 on page 48) is disabled
- a remote peak shave request (parameter 12630 on page 28) is disabled
- an interruptible power rate request (parameter 12660 on page 29) is disabled
- the priority is changed

An overlap situation is only decoupled if

- the "Extended parallel time" function becomes FALSE again
- the phase angle during overlap position is $> 2.0^\circ$ or $< -2.0^\circ$

The following example shows a typical transfer sequence from source 1 to source 2 with extended parallel time:



Load Shed



NOTE

Load shed is inactive as long as an "Extended parallel time" (parameter 12860) is enabled.

The load shed function bypasses the in-phase monitoring function. This can cause an asynchronous transfer in case a standard transition switch is used.

The load shed function is intended to shed the load from the non-preferred source if a load shed signal is received from a master controller (e.g. SCADA system) via a discrete input.

If a load shed signal is received from a master control, the DTSC disconnects the load from the non-preferred source immediately. The following rules are valid for the load shed function:

- The load must be supplied by the non-preferred source. The load shed function can only trigger to disconnect the load from the non-preferred source. If the load is supplied by the preferred source while a load shed signal is triggered, the load will not be disconnected.
- Possible timers for pre-transfer signals like motor load disconnect or elevator pre-signal, which are enabled prior to the transfer will be ignored in case of a load shed request.
- If in-phase monitoring is enabled, this will be ignored in case of a load shed request.
- If the *LogicsManager* function "Inhibit XFR to S1" or "Inhibit XFR to S2" is TRUE and would prevent a transfer to the preferred source, this function will be ignored on case of a standard transition switch. If a delayed or closed transition switch is used, the switch will open to neutral position.
- If transfer switches are used, which may only be operated in case a measuring voltage is present, a transfer to the preferred source may only be possible, when it is present. If only the non-preferred source is present, the *LogicsManager* flag "Load shed" (20.11) will be enabled. This flag enables to close a load shed relay, which connects the voltage of the non-preferred source to the preferred source side of the transfer switch to operate it. If the neutral position (delayed / closed switch) or the preferred source position (standard switch) is detected by the DTSC, the load shed signal will be reset again. Refer to Figure 3-9 and Figure 3-10 for more detailed information.

If the *LogicsManager* function "Load shed" becomes TRUE, a load shed from the non-preferred source will be performed.

Load shed				Load shedding enabled	<i>LogicsManager</i>
EN					
DE	Nicht prio. LS auf				
CL2	{0}	{1}	{2}		
12870	✓	✓	✓	The <i>LogicsManager</i> and its default settings are explained on page 99 in Appendix A: " <i>LogicsManager</i> ".	

Table 3-1 defines the behavior in case of a load shed request when utilizing a standard transition switch depending on the system conditions.

Load is connected to	Pre-transfer signals	In-phase monitoring	Preferred source available	Behavior on load shed request
Non-preferred source	Bypassed	Bypassed	Yes	Immediate transfer to preferred source
Non-preferred source	Bypassed	Bypassed	No	<i>LogicsManager</i> flag "Load shed" (20.11) is set to transfer to the preferred source
Preferred source	N/A	N/A	Yes	No action performed - load remains connected to preferred source

Table 3-1: Application - load shed with standard transition switch

Table 3-2 defines the behavior in case of a load shed request when utilizing a delayed or closed transition switch depending on the system conditions.

Load is connected to	Pre-transfer signals	In-phase monitoring	Preferred source available	Behavior on load shed request
Non-preferred source	Bypassed	Bypassed	Yes	Immediate transfer to preferred source
Non-preferred source	Bypassed	Bypassed	No	<i>LogicsManager</i> flag "Load shed" (20.11) is immediately set to open to neutral position If the preferred source restores while the switch is in neutral position, a transfer to the preferred source is initiated without waiting for the preferred source stable timer to expire
Preferred source	N/A	N/A	Yes	No action performed - load remains connected to preferred source

Table 3-2: Application - load shed with delayed or closed transition switch

Figure 3-9 shows how to wire a load shed relay for applications, which use a standard transition switch (S1 is the preferred source and S2 is the non-preferred source with this application).

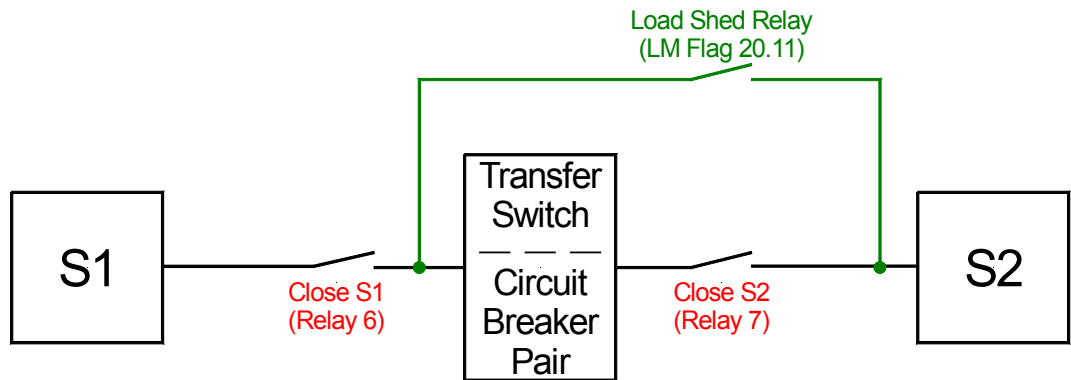


Figure 3-9: Load shed relay wiring - standard transition switch

Figure 3-10 shows how to wire a load shed relay for applications, which use a delayed or closed transition switch (S1 is the preferred source and S2 is the non-preferred source with this application).

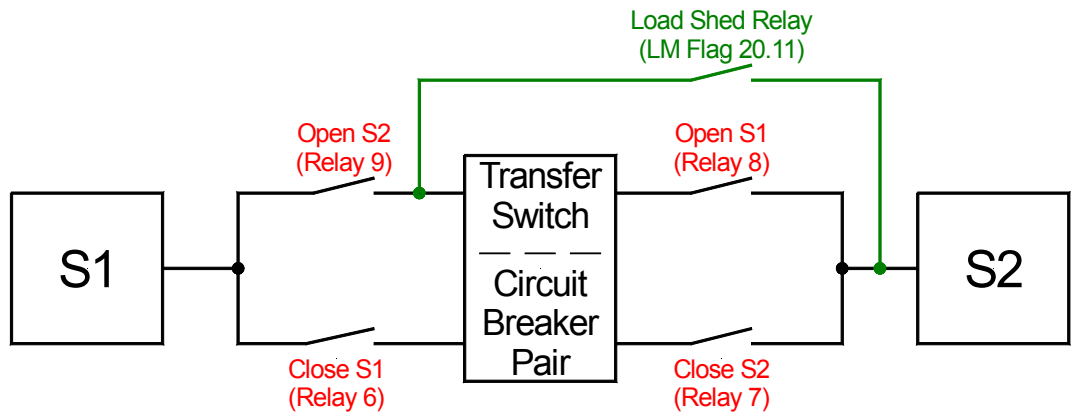


Figure 3-10: Load shed relay wiring - delayed or closed transition switch



NOTE

The load shed relay must always be operated at the non-preferred source side with the power of the non-preferred source.

If a load shed relay is used, preferred and non-preferred source must not be changed since this would lead to a malfunction of the load shed function.

Breaker



Breaker: Transfer Switch Type

Transfer switch type		Transfer switch type			Standard / Delayed / Closed
DE	Transfer Schalter Typ				
CL2	{0}	{1}	{2}	This parameter configures the type of ATS switch, which is connected to the controller. The switch logic behavior depends on the setting configured here. StandardAn "open transition" switch is selected. DelayedA "delayed transition" switch is selected. ClosedA "closed transition" switch is selected.	
3424	✓	✓	✓		

Standard Transfer Switch

If an open transition switch is used, "Standard" transfer switch type must be selected.
This switch type may only take on two states:

- Position 1: Connected to source 1

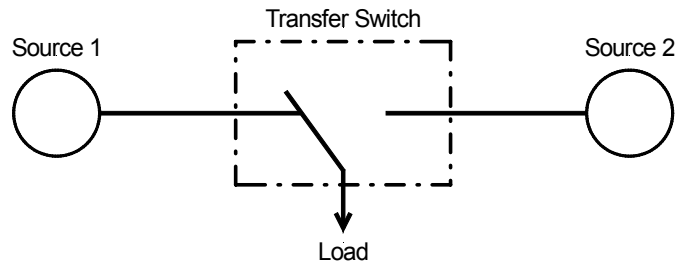


Figure 3-11: Open transition switch - connected to source 1

- Position 2: Connected to source 2

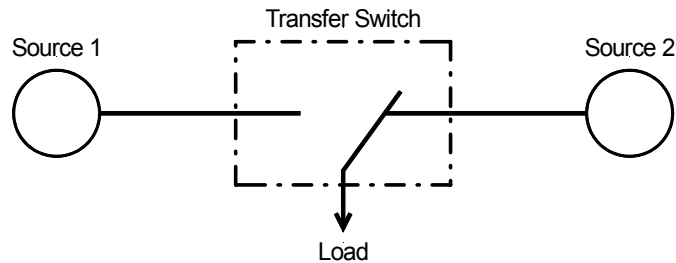


Figure 3-12: Open transition switch - connected to source 2

The following switch commands are enabled in this mode:

- *LogicsManager* flag (20.07) : Command: Close to Source 1
- *LogicsManager* flag (20.09) : Command: Close to Source 2

These signals may be configured to relay outputs to operate the ATS switch mechanics.

The following feedback signals are evaluated in this mode:

- Discrete input 1 (ATS breaker in Source 1 position) = signal designation: S1
- Discrete input 2 (ATS breaker in Source 2 position) = signal designation: S2

These feedback signals are evaluated by the ATS controller for monitoring the actual switch position.

The following additional features are recommended for this mode:

- In-phase monitor (refer to the In-Phase Monitor section)
- Motor load disconnect

Delayed Transfer Switch

If an delayed transition switch is used, "Delayed" transfer switch type must be selected.
This switch type may take on three states:

- Position 1: Connected to source 1

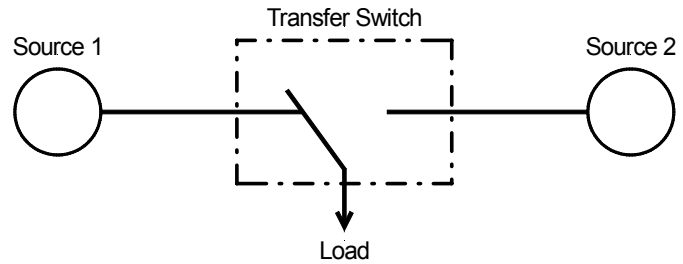


Figure 3-13: Delayed transition switch - connected to source 1

- Position 2: Neutral

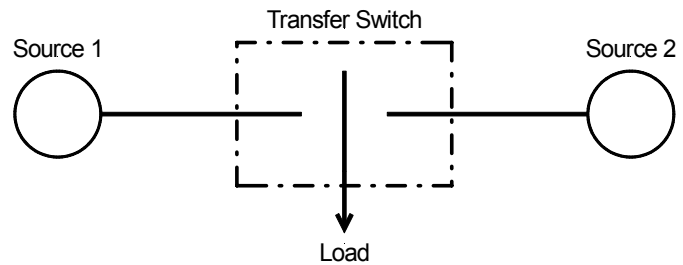


Figure 3-14: Delayed transition switch - neutral position

- Position 3: Connected to source 2

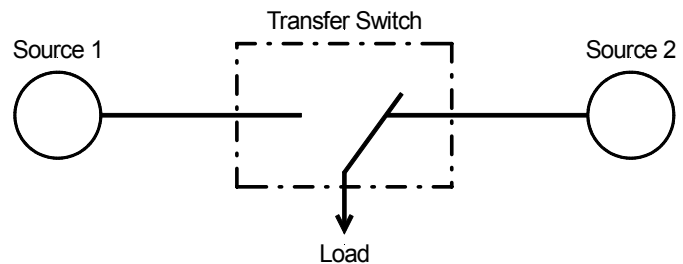


Figure 3-15: Delayed transition switch - connected to source 2

The following switch commands are enabled in this mode:

- *LogicsManager* flag (20.07) : Command: Close to Source 1
- *LogicsManager* flag (20.08) : Command: Open Source 1
- *LogicsManager* flag (20.09) : Command: Close to Source 2
- *LogicsManager* flag (20.10) : Command: Open Source 2

These signals may be configured to relay outputs to operate the ATS switch mechanics.

The following feedback signals are evaluated in this mode:

- Discrete input 1 (ATS breaker in Source 1 position) = signal designation: S1
- Discrete input 2 (ATS breaker in Source 2 position) = signal designation: S2
- Discrete input 3 (ATS breaker in Source 1 OPEN position) = signal designation: S1O
- Discrete input 4 (ATS breaker in Source 2 OPEN position) = signal designation: S2O

These feedback signals are evaluated by the ATS controller for monitoring the actual switch position.

The following additional features are recommended for this mode:

- In-phase monitor (refer to the In-Phase Monitor section)
- Motor load disconnect

Closed Transfer Switch

If an closed transition switch is used, "Closed" transfer switch type must be selected.

This switch type may take on four states:

- Position 1: Connected to source 1

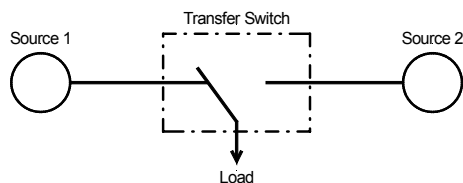


Figure 3-16: Closed transition switch - connected to source 1

- Position 2: Neutral

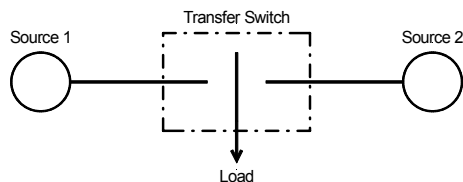


Figure 3-17: Closed transition switch - neutral position

- Position 3: Synchronized

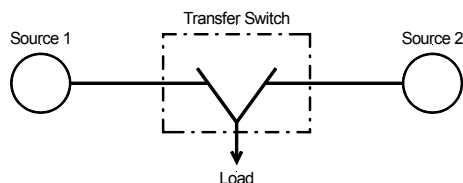


Figure 3-18: Closed transition switch - connected to source 1 and 2 (overlap position)

- Position 4: Connected to source 2

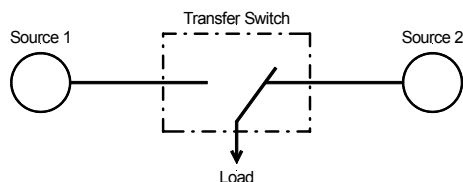


Figure 3-19: Closed transition switch - connected to source 2

The following switch commands are enabled in this mode:

- *LogicsManager* flag (20.07) : Command: Close to Source 1
- *LogicsManager* flag (20.08) : Command: Open Source 1
- *LogicsManager* flag (20.09) : Command: Close to Source 2
- *LogicsManager* flag (20.10) : Command: Open Source 2

These signals may be configured to relay outputs to operate the ATS switch mechanics.

The following feedback signals are evaluated in this mode:

- Discrete input 1 (ATS breaker in Source 1 position) = signal designation: S1
- Discrete input 2 (ATS breaker in Source 2 position) = signal designation: S2
- Discrete input 3 (ATS breaker in Source 1 OPEN position) = signal designation: S1O
- Discrete input 4 (ATS breaker in Source 2 OPEN position) = signal designation: S2O

These feedback signals are evaluated by the ATS controller for monitoring the actual switch position.

The following additional features are recommended for this mode:

- In-phase monitor (refer to the In-Phase Monitor section)
- Motor load disconnect

Use Limit Switch Open Replies

This function is used to define the limit switch reply signals, which are evaluated for determining the current ATS switch position.

The following four signals are available for determining the ATS switch position:

- Discrete input 1 (ATS breaker in Source 1 position) = signal designation: S1
- Discrete input 2 (ATS breaker in Source 2 position) = signal designation: S2
- Discrete input 3 (ATS breaker in Source 1 OPEN position) = signal designation: S1O
- Discrete input 4 (ATS breaker in Source 2 OPEN position) = signal designation: S2O



NOTE

All reply signals, which are selected for determining the current ATS switch position must be connected to the discrete inputs of the DTSC to ensure a correct evaluation of the switch replies.

These discrete inputs have an N.C. logic, i.e. the breaker is considered as "in position" if the respective DI is de-energized.

DE EN	Use Limit sw. OPEN replies			Use limit switch open replies	YES / NO
	Schalter RM OFFEN verwenden				
CL2 3434	{0} ✓	{1} ✓	{2} ✓	<p>This parameter may only be enabled (setting "YES") if parameter 3424 on page 40 is configured to "Delayed" or "Closed". If it is configured to "Standard", this parameter is always disabled (setting "NO").</p> <p>This parameter defines whether the limit switch open signals are also used to determine the ATS switch position.</p> <p>YES..... The signals S1, S2, S1O, and S2O are used to determine the ATS switch position.</p> <p>This setting provides a higher system safety because the "Switch Open" replies are also evaluated besides the "Switch Closed" replies.</p> <p>NO Only the signals S1 and S2 are used to determine the ATS switch position.</p> <p>This setting does <u>not</u> use the DIs 3 and 4 for determining the ATS switch position and makes them available for other functions.</p>	

Delayed Mode Active

This function is only effective if parameter 3424 (Transfer switch type) is configured to "Closed". If the *LogicsManager* function "Delayed mode act." becomes TRUE, the transfer switch type will be set to "Delayed" temporarily.

DE	EN	Delayed mode act.			Enable delayed mode	<i>LogicsManager</i>
		Verzög. modus akt.				
CL2	{0}	{1}	{2}	The <i>LogicsManager</i> and its default settings are explained on page 99 in Appendix A: " <i>LogicsManager</i> ".		
12850	✓	✓	✓			

Transition Timers

The "Neutral Time S2 -> S1" parameter is only enabled, if "Delayed" or "Closed" is configured as "Transfer switch type" (Parameter 3424) and inphase monitoring is disabled (parameter 4570).

EN	Neutral Time S2->S1	Neutral Time S2 -> S1	0.0 to 999.9 s
DE	Neutral Verweilzeit S2->S1		
CL2	{0} {1} {2}		
3426	✓ ✓ ✓		

This parameter configures the residence time in neutral position when transferring the load in this transfer direction.

After this timer has expired, the transfer to source 1 will be performed.

If this timer is running, the "Neutral S1 -> S2" message is displayed.

The "Neutral Time S2 <- S1" parameter is only enabled, if "Delayed" or "Closed" is configured as "Transfer switch type" (Parameter 3424) and inphase monitoring is disabled (parameter 4570).

EN	Neutral Time S1->S2	Neutral Time S1 -> S2	0.0 to 999.9 s
DE	Neutral Verweilzeit S1->S2		
CL2	{0} {1} {2}		
3425	✓ ✓ ✓		

This parameter configures the residence time in neutral position when transferring the load in this transfer direction.

After this timer has expired, the transfer to source 2 will be performed.

If this timer is running, the "Neutral S1 <- S2" message is displayed.

EN	Limit switch reply timeout	Limit switch reply timeout	0.1 to 99.9 s
DE	Zeitüberschreitung Rückmeld.		
CL2	{0} {1} {2}		
3428	✓ ✓ ✓		

This parameter configures the maximum waiting time for a feedback signal from the ATS switch. If no reply is detected within the configured time, a new transition attempt will be performed after the "Wait time until next XFR attempt" (Parameter 3429) has expired (refer to Figure 3-20 on page 45). If the "Max. of transfer attempts" (Parameter 3427) is exceeded, a switch failure will be issued.

If this timer is running, the Bypass softkey is not displayed. The display message while the timer is running indicates that a reply is expected and depends on the command issued:

- If source 1 is to be opened : "Wait S1 open"
- If source 2 is to be opened : "Wait S2 open"
- If source 1 is to be closed : "Wait S1 close"
- If source 2 is to be closed : "Wait S2 close"

Note: The operator coils may be damaged, if this timer is configured too long (i.e. the maximum time, for which the transition pulse may be enabled must not be exceeded).



NOTE

The limit switch reply timeout monitoring is only enabled if a transfer command (C2, C1, C2O, or C1O) has been issued from the ATS controller.

EN	Wait time until next XFR attempt		
DE	Wartezeit vor neuem Transfer		
CL2	{0}	{1}	{2}
3429	✓	✓	✓

Waiting time until next transition attempt 0.1 to 99.9 s

This parameter configures the interval following an unsuccessful transition attempt before a new transition attempt is being performed.
This time allows the relay coil to cool down between the open/close signals.

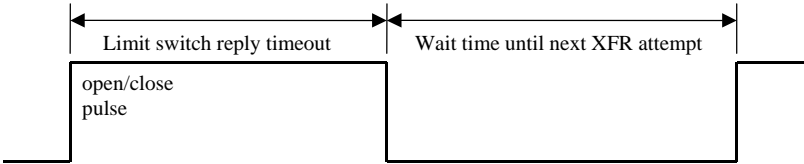


Figure 3-20: Breaker - transition pulse

EN	Max. of Transfer attempts		
DE	Max. Anzahl Fehlzuschaltungen		
CL2	{0}	{1}	{2}
3427	✓	✓	✓

Maximum number of unsuccessful transition attempts 1 to 10

This parameter configures the maximum number of unsuccessful transition attempts before a switch failure will be issued. The counter for the number of unsuccessful transition attempts will be increased with the start of each waiting time period (Parameter 3429)

Triggering of the "Fail to close S1" failure

This failure is triggered if the following conditions are met:

- Source 1 is available
- The ATS controller has issued the C1 signal (*LogicsManager* flag (20.07)) to close to source 1

As soon as the C1 signal (command: close to source 1) is issued, the "Limit switch reply timeout" timer (Parameter 3428) starts to count and the period for monitoring whether the S1 reply (closed to source 1) is fed back from the ATS switch to the controller starts. The C1 signal is enabled until the "Limit switch reply timeout" timer has expired. Thus, this defines maximum permissible pulse duration for the transfer command. If the "Limit switch reply timeout" timer has expired, the C1 signal will be disabled. If the "Wait time until next XFR attempt" timer (Parameter 3429) has expired, the C1 signal will be enabled again and the "Limit switch reply timeout" timer is re-started. If the timer expires again without detecting the S1 reply, the "Fail to close S1" failure is issued. The message "Fail to close S1" will be displayed and entered into the event logger.

If the reply from the ATS controller is detected while the "Limit switch reply timeout" timer is still counting, the C1 signal will be disabled immediately since the transfer was successful. The message is not be displayed anymore and the reply monitoring is terminated.



NOTE

Closing the ATS switch will be attempted until the maximum number of unsuccessful transition attempts (Parameter 3427) is reached. The failure will be issued after the last failed transfer attempt.

Triggering of the "Fail to close S2" failure

This failure is triggered if the following conditions are met:

- Source 2 is available
- The ATS controller has issued the C2 signal (*LogicsManager* flag (20.09)) to close to source 2

As soon as the C2 signal (command: close to source 2) is issued, the "Limit switch reply timeout" timer (Parameter 3428) starts to count and the period for monitoring whether the S2 reply (closed to source 2) is fed back from the ATS switch to the controller starts. The C2 signal is enabled until the "Limit switch reply timeout" timer has expired. Thus, this defines maximum permissible pulse duration for the transfer command. If the "Limit switch reply timeout" timer has expired, the C2 signal will be disabled. If the "Wait time until next XFR attempt" timer (Parameter 3429) has expired, the C2 signal will be enabled again and the "Limit switch reply timeout" timer is re-started. If the timer expires again without detecting the S2 reply, the "Fail to close S2" failure is issued. The message "Fail to close S2" will be displayed and entered into the event logger.

If the reply from the ATS controller is detected while the "Limit switch reply timeout" timer is still counting, the C2 signal will be disabled immediately since the transfer was successful. The message is not be displayed anymore and the reply monitoring is terminated.



NOTE

Closing the ATS switch will be attempted until the maximum number of unsuccessful transition attempts (Parameter 3427) is reached. The failure will be issued after the last failed transfer attempt.



NOTE

If a closure failure occurs, the system always tries to close the second breaker to a good source.

Triggering of the "Fail to open S1" failure

This failure is triggered if the following conditions are met:

- Source 2 is available
- The ATS controller has issued the C1O signal (*LogicsManager* flag (20.08)) to open source 1

As soon as the C1O signal (command: open source 1) is issued, the "Limit switch reply timeout" timer (Parameter 3428) starts to count and the period for monitoring whether the S1O reply (source 1 is open) is fed back from the ATS switch to the controller starts. The C1O signal is enabled until the "Limit switch reply timeout" timer has expired. Thus, this defines maximum permissible pulse duration for the transfer command. If the "Limit switch reply timeout" timer has expired, the C1O signal will be disabled. If the "Wait time until next XFR attempt" timer (Parameter 3429) has expired, the C1O signal will be enabled again and the "Limit switch reply timeout" timer is re-started. If the timer expires again without detecting the S1O reply, the "Fail to open S1" failure is issued. The message "Fail to open S1" will be displayed and entered into the event logger.

If the reply from the ATS controller is detected while the "Limit switch reply timeout" timer is still counting, the C1O signal will be disabled immediately since the transfer was successful. The message is not be displayed anymore and the reply monitoring is terminated.

**NOTE**

Opening the ATS switch will be attempted until the maximum number of unsuccessful transition attempts (Parameter 3427) is reached. The failure will be issued after the last failed transfer attempt.

Triggering of the "Fail to open S2" failure

This failure is triggered if the following conditions are met:

- Source 1 is available
- The ATS controller has issued the C2O signal (*LogicsManager* flag (20.10)) to open source 2

As soon as the C2O signal (command: open source 2) is issued, the "Limit switch reply timeout" timer (Parameter 3428) starts to count and the period for monitoring whether the S2O reply (source 2 is open) is fed back from the ATS switch to the controller starts. The C2O signal is enabled until the "Limit switch reply timeout" timer has expired. Thus, this defines maximum permissible pulse duration for the transfer command. If the "Limit switch reply timeout" timer has expired, the C2O signal will be disabled. If the "Wait time until next XFR attempt" timer (Parameter 3429) has expired, the C2O signal will be enabled again and the "Limit switch reply timeout" timer is re-started. If the timer expires again without detecting the S2O reply, the "Fail to open S2" failure is issued. The message "Fail to open S2" will be displayed and entered into the event logger.

If the reply from the ATS controller is detected while the "Limit switch reply timeout" timer is still counting, the C2O signal will be disabled immediately since the transfer was successful. The message is not be displayed anymore and the reply monitoring is terminated.

**NOTE**

Opening the ATS switch will be attempted until the maximum number of unsuccessful transition attempts (Parameter 3427) is reached. The failure will be issued after the last failed transfer attempt.

Test Modes



There are two different types of system tests:

- Load Test**
This is a test with load transfer. If a load test is requested, a failure of the preferred source will be simulated. The non-preferred source will be started and load will be transferred to the non-preferred source. This test serves to ensure that the complete system is ready for operation in case of a real failure of the preferred source.
- No Load Test**
This is an engine test. If a no load test is requested, only the non-preferred source will be started, but no load transfer will be performed. This test serves to ensure that the non-preferred source is starting and running properly.



NOTE
A "No Load Test" may only be performed if the non-preferred source is a generator.

If the *LogicsManager* function "Load Test" becomes TRUE (by energizing a DI for example), a load test will be performed.

Load Test				<i>LogicsManager</i>	
EN	Load Test				
DE	Lastprobe				
	{0}	{1}	{2}		
CL2	✓	✓	✓	The <i>LogicsManager</i> and its default settings are explained on page 99 in Appendix A: " <i>LogicsManager</i> ".	
12640					

If the *LogicsManager* function "No Load Test" becomes TRUE (by energizing a DI for example), a no load test will be performed.

No Load Test				<i>LogicsManager</i>	
EN	No Load Test				
DE	Motor Test				
	{0}	{1}	{2}		
CL2	---	✓	✓	The <i>LogicsManager</i> and its default settings are explained on page 99 in Appendix A: " <i>LogicsManager</i> ".	
12650					

Monitoring



Monitoring: Alarm Acknowledgement

EN	Time until horn reset		
DE	Zeit Hupenreset		
CL2	{0}	{1}	{2}
1756	✓	✓	✓

Self acknowledgment of the centralized alarm (horn)

0 to 1,000 s

After each alarm occurs, the alarm LED flashes and the command variable 03.05 (horn) is issued. After the delay time 'time until horn reset' has expired, the flashing LED changes into a steady light and the command variable 03.05 (horn) is reset. The alarm LED is illuminated continuously until the alarm has been acknowledged.

Note: If this parameter is configured to 0, the horn will remain active until it will be acknowledged.

EN	External acknowledge		
DE	Ext. Quittierung		
CL2	{0}	{1}	{2}
12490	✓	✓	✓

Protection: External acknowledgment of alarms

LogicsManager

It is possible to acknowledge all alarms simultaneously from remote, e.g. with a discrete input. The command variables of the *LogicsManager* have to become TRUE twice.

- ① The first high signal into the discrete input acknowledges the command variable 03.05 (horn). The second high signal acknowledges all inactive alarm messages.

The ON-delay time is the minimum time the input signals have to be "1". The OFF-delay time is the time how long the input conditions have to be "0" before the next high signal is accepted.

The *LogicsManager* and its default settings are explained on page 99 in Appendix A: "*LogicsManager*".

Monitoring: Limit Switch Monitoring

EN	Limit switch monitoring		
DE	Rückmeldungswächter		
CL2	{0}	{1}	{2}
3430	✓	✓	✓

Limit switch monitoring

ON / OFF

Limit switch monitoring evaluates the ATS limit switch replies and checks them for plausibility with reference to the operating state. If the replies are not plausible, the "Actual" and "Expected" replies are displayed.

Meanwhile, the status of the breaker replies cannot be reset with the Reset button and all further transfers are inhibited.

A table with the actual and expected replies may be found in the Operation Manual 37387.

ON..... The replies of the ATS limit switch are evaluated and compared with the expected replies.

OFF..... The replies of the ATS limit switch are not evaluated.

Note: Do not enable this monitoring function before the system is commissioned and fully operational. Otherwise, missing reply signals would lead to a limit switch failure, which blocks the control unit. This can only be solved by wiring the reply signals correctly or disabling this function using LeoPC1.

Monitoring: Source 1 Monitoring

EN	Voltage monitoring S1	Voltage monitoring source 1	3 phase / 4 phase
DE	Spg.-Überwachung S1		
CL2 1787	{0} {1} {2}	The unit can either monitor the wye voltages (phase-neutral: 3ph-4w, 1ph-3w and 1ph-2w) or the delta voltages (phase-phase: 3ph-3w and 3ph-4w).	

! WARNING:
This parameter influences the protective functions.

3 phaseThe phase-phase voltage will be measured and all subsequent parameters concerning voltage monitoring "source 1" are referred to this value (V_{L-L}).

4 phaseThe phase-neutral voltage will be measured and all subsequent parameters concerning voltage monitoring "source 1" are referred to this value (V_{L-N}).

Monitoring: Source 1 Monitoring: Undervoltage

Voltage is monitored depending on Parameter 1787 "Voltage monitoring S1".

EN	S1 undervoltage restore	Source 1 undervoltage restore	50.0 to 125.0 %
DE	S1 Unterspannung rücksetzen		
CL2 4450	{0} {1} {2}	① This value refers to the Rated voltage Source 1 (Parameter 1774 on page 16).	

This parameter configures the threshold, which must be exceeded to consider source 1 as "OK" again.

EN	S1 undervoltage fail	Source 1 undervoltage fail	50.0 to 125.0 %
DE	S1 Unterspannung auslösen		
CL2 4451	{0} {1} {2}	① This value refers to the Rated voltage Source 1 (Parameter 1774 on page 16).	

This parameter configures the threshold, which must be fallen below to consider source 1 as "not OK".

Monitoring: Source 1 Monitoring: Underfrequency

Three-phase measurement of the frequency is performed, if all voltages are higher than 15 % of the rated value. This permits a very rapid and accurate frequency measurement. The frequency however will be measured properly even if voltage is applied to one phase only.

EN	S1 underfrequency monitoring			Source 1 underfrequency monitoring	ON / OFF
DE	S1 Unterfrequenz Wächter				
CL2	{0}	{1}	{2}	This parameter configures, whether underfrequency monitoring for source 1 is performed. OFFNo underfrequency monitoring is performed for source 1. ONUnderfrequency monitoring is performed for source 1.	
4452	✓	✓	✓		
EN	S1 underfrequency restore			Source 1 underfrequency restore	50.0 to 130.0 %
DE	S1 Unterfrequenz rücksetzen				
CL2	{0}	{1}	{2}	① This value refers to the Rated system frequency (Parameter 1750 on page 16).	
4453	✓	✓	✓		
				This parameter configures the threshold, which must be exceeded to consider source 1 as "OK" again..	
EN	S1 underfrequency fail			Source 1 underfrequency fail	50.0 to 130.0 %
DE	S1 Unterfrequenz auslösen				
CL2	{0}	{1}	{2}	① This value refers to the Rated system frequency (Parameter 1750 on page 16)	
4454	✓	✓	✓		
				This parameter configures the threshold, which must be fallen below to consider source 1 as "not OK".	

Monitoring: Source 1 Monitoring: Overvoltage

Voltage is monitored depending on Parameter 1787 "Voltage monitoring S1".

EN	S1 overvoltage monitoring			Source 1 overvoltage monitoring	ON / OFF
DE	S1 Überspannung Wächter				
CL2	{0}	{1}	{2}	This parameter configures, whether overvoltage monitoring for source 1 is performed. OFFNo overvoltage monitoring is performed for source 1. ONOvervoltage monitoring is performed for source 1.	
4455	✓	✓	✓		
EN	S1 overvoltage restore			Source 1 overvoltage restore	50.0 to 125.0 %
DE	S1 Überspannung rücksetzen				
CL2	{0}	{1}	{2}	① This value refers to the Rated voltage Source 1 (Parameter 1774 on page 16).	
4456	✓	✓	✓		
				This parameter configures the threshold, which must be fallen below to consider source 1 as "OK" again..	
EN	S1 overvoltage fail			Source 1 overvoltage fail	50.0 to 125.0 %
DE	S1 Überspannung auslösen				
CL2	{0}	{1}	{2}	① This value refers to the Rated voltage Source 1 (Parameter 1774 on page 16).	
4457	✓	✓	✓		
				This parameter configures the threshold, which must be exceeded to consider source 1 as "not OK".	

Monitoring: Source 1 Monitoring: Overfrequency

Three-phase measurement of the frequency is performed, if all voltages are higher than 15 % of the rated value. This permits a very rapid and accurate frequency measurement. The frequency however will be measured properly even if voltage is applied to one phase only.

EN	S1 overfrequency monitoring			Source 1 overfrequency monitoring	ON / OFF
DE	S1 Überfrequenz Wächter				
CL2	{0}	{1}	{2}	This parameter configures, whether overfrequency monitoring for source 1 is performed. OFFNo overfrequency monitoring is performed for source 1. ONOverfrequency monitoring is performed for source 1.	
4458	✓	✓	✓		
EN	S1 overfrequency restore			Source 1 overfrequency restore	50.0 to 130.0 %
DE	S1 Überfrequenz rücksetzen				
CL2	{0}	{1}	{2}	ⓘ This value refers to the Rated system frequency (Parameter 1750 on page 16).	
4459	✓	✓	✓		
This parameter configures the threshold, which must be fallen below to consider source 1 as "OK" again..					
EN	S1 overfrequency fail			Source 1 overfrequency fail	50.0 to 130.0 %
DE	S1 Überfrequenz auslösen				
CL2	{0}	{1}	{2}	ⓘ This value refers to the Rated system frequency (Parameter 1750 on page 16).	
4460	✓	✓	✓		
This parameter configures the threshold, which must be exceeded to consider source 1 as "not OK".					

Monitoring: Source 1 Monitoring: Voltage Imbalance

The voltage imbalance monitoring is practically used to detect defective fuses in certain phases. The voltage imbalance monitoring measures voltage differences between the phases of source 1. The voltage is measured three-phase. If the phase-to-phase voltage difference between the three phases exceeds the configured imbalance limit the alarm will be issued.

EN	S1 voltage imbalance monitoring			Source 1 voltage imbalance monitoring	ON / OFF
DE	S1 Asymmetrie Wächter				
CL2	{0}	{1}	{2}	This parameter configures, whether voltage imbalance monitoring for source 1 is performed. OFF No voltage imbalance monitoring is performed for source 1. ON Voltage imbalance monitoring is performed for source 1.	
4461	✓	✓	✓		
EN	S1 volt. imbalance restore			Source 1 voltage imbalance restore	0.5 to 99.9 %
DE	S1 Asymmetrie rücksetzen				
CL2	{0}	{1}	{2}	① This value refers to the Rated voltage Source 1 (Parameter 1774 on page 16).	
4462	✓	✓	✓		
				This parameter configures the threshold, which must be fallen below to consider source 1 as "OK" again..	
EN	S1 volt. imbalance fail			Source 1 voltage imbalance fail	0.5 to 99.9 %
DE	S1 Asymmetrie auslösen				
CL2	{0}	{1}	{2}	① This value refers to the Rated voltage Source 1 (Parameter 1774 on page 16).	
4463	✓	✓	✓		
				This parameter configures the threshold, which must be exceeded to consider source 1 as "not OK".	
EN	Delay			Source 1 voltage imbalance delay	0.02 to 99.99 s
DE	Verzögerung				
CL2	{0}	{1}	{2}	If the monitored voltage imbalance of source 1 exceeds the threshold value for the delay time configured here, an alarm will be issued.	
3914	✓	✓	✓		

Monitoring: Source 1 Monitoring: Phase Rotation

**CAUTION**

Please ensure during installation that all voltages applied to this unit are wired correctly to both sides of the circuit breaker. Failure to do so may result in damage to the control unit and/or generation equipment due to closing the breaker asynchronous or with mismatched phase rotations and phase rotation monitoring enabled at all connected components (engine, generator, breakers, cable, busbars, etc.).

This function may block a connection of systems with mismatched phases systems only under the following conditions:

- The voltages being measured are wired correctly with respect to the phase rotation at the measuring points (i.e. the voltage transformer in front and behind the circuit breaker)
- The measuring voltages are wired without angular phase shift or interruption from the measuring point to the control unit
- The measuring voltages are wired to the correct terminals of the control unit (i.e. L1 of the generator is connected with the terminal of the control unit which is intended for the L1 of the generator)

Correct phase rotation of the phase voltages ensures that damage will not occur during a transfer to either source 1 or source 2. The voltage phase rotation monitoring checks the phase rotation of the voltages and the configured phase rotation to ensure they are identical. The directions of rotation are differentiated as "clockwise" and "counter-clockwise". With a clockwise field the direction of rotation is "L1-L2-L3"; with a counter clockwise field the direction of rotation is "L1-L3-L2". If the control is configured for a clockwise rotation and the voltages into the unit are calculated as counterclockwise the alarm will be initiated.

A connection to certain source is only possible if this source has the correct phase sequence. If a source has a wrong phase sequence, a connection to this source is not possible.

EN	S1 phase rotation monitoring		
DE	S1 Drehfeldüberwachung		
CL2	(0)	(1)	(2)
4562	✓	✓	✓

Source 1 phase rotation monitoring**ON / OFF**

This parameter configures, whether phase rotation monitoring for source 1 is performed.

OFFNo phase rotation monitoring is performed for source 1.

ONPhase rotation monitoring is performed for source 1.

EN	S1 phase rotation		
DE	S1 Drehfeld		
CL2	(0)	(1)	(2)
4563	✓	✓	✓

Source 1 phase rotation**CW / CCW**

This parameter configures the phase rotation of the system. If a different phase rotation is detected at source 1, source 1 is considered as "not OK" and a transfer to source 2 is initiated.

CWThe three-phase measured generator voltage is rotating CW (clockwise; that means the voltage rotates in direction L1-L2-L3; standard setting).

CCWThe three-phase measured generator voltage is rotating CCW (counter-clockwise; that means the voltage rotates in direction L1-L3-L2; standard setting).

Monitoring: Source 2 Monitoring

Voltage monitoring S2		Voltage monitoring source 2		3 phase / 4 phase	
Spg.-Überwachung S2					
CL2 1786	<div> <div>(0)</div> <div>✓</div> </div>	<div> <div>(1)</div> <div>✓</div> </div>	<div> <div>(2)</div> <div>✓</div> </div>	The unit can either monitor the wye voltages (phase-neutral: 3ph-4w, 1ph-3w and 1ph-2w) or the delta voltages (phase-phase: 3ph-3w and 3ph-4w).	

The unit can either monitor the wye voltages (phase-neutral: 3ph-4w, 1ph-3w and 1ph-2w) or the delta voltages (phase-phase: 3ph-3w and 3ph-4w).

! WARNING:
This parameter influences the protective functions.

3 phase..... The phase-phase voltage will be measured and all subsequent parameters concerning voltage monitoring "source 1" are referred to this value (V_{L-L}).

4 phase..... The phase-neutral voltage will be measured and all subsequent parameters concerning voltage monitoring "source 1" are referred to this value (V_{L-N}).

Monitoring: Source 2 Monitoring: Undervoltage

Voltage is monitored depending on Parameter 1786 "Voltage monitoring S2".

DE EN	S2 undervoltage restore			Source 2 undervoltage restore	50.0 to 125.0 %
	S2 Unterspannung rücksetzen				
CL2 4465	(0) ✓	(1) ✓	(2) ✓	① This value refers to the Rated voltage Source 2 (Parameter 1772 on page 16).	

This parameter configures the threshold, which must be exceeded to consider source 2 as "OK" again.

DE	S2 undervoltage fail			Source 2 undervoltage fail	50.0 to 125.0 %
	S2 Unterspannung auslösen				
EN	CL2	(0)	(1)	(2)	
4466	✓	✓	✓	① This value refers to the Rated voltage Source 2 (Parameter 1772 on page 16).	

This parameter configures the threshold, which must be fallen below to consider source 2 as "not OK".

Monitoring: Source 2 Monitoring: Underfrequency

Three-phase measurement of the frequency is performed, if all voltages are higher than 15 % of the rated value. This permits a very rapid and accurate frequency measurement. The frequency however will be measured properly even if voltage is applied to one phase only.

EN	S2 underfrequency monitoring		
DE	S2 Unterfrequenz Wächter		
CL2	{0}	{1}	{2}
4467	✓	✓	✓

Source 2 underfrequency monitoring ON / OFF

This parameter configures, whether underfrequency monitoring for source 2 is performed.

OFF No underfrequency monitoring is performed for source 2.

ON Underfrequency monitoring is performed for source 2.

EN	S2 underfrequency restore		
DE	S2 Unterfrequenz rücksetzen		
CL2	{0}	{1}	{2}
4468	✓	✓	✓

Source 2 underfrequency restore 50.0 to 130.0 %

① This value refers to the Rated system frequency (Parameter 1750 on page 16).

This parameter configures the threshold, which must be exceeded to consider source 2 as "OK" again.

EN	S2 underfrequency fail		
DE	S2 Unterfrequenz auslösen		
CL2	{0}	{1}	{2}
4469	✓	✓	✓

Source 2 underfrequency fail 50.0 to 130.0 %

① This value refers to the Rated system frequency (Parameter 1750 on page 16)

This parameter configures the threshold, which must be fallen below to consider source 2 as "not OK".

Monitoring: Source 2 Monitoring: Overvoltage

Voltage is monitored depending on Parameter 1786 "Voltage monitoring S2".

EN	S2 overvoltage monitoring		
DE	S2 Überspannung Wächter		
CL2	{0}	{1}	{2}
4470	✓	✓	✓

Source 2 overvoltage monitoring ON / OFF

This parameter configures, whether overvoltage monitoring for source 2 is performed.

OFF No overvoltage monitoring is performed for source 2.

ON Overvoltage monitoring is performed for source 2.

EN	S2 overvoltage restore		
DE	S2 Überspannung rücksetzen		
CL2	{0}	{1}	{2}
4471	✓	✓	✓

Source 2 overvoltage restore 50.0 to 125.0 %

① This value refers to the Rated voltage Source 2 (Parameter 1772 on page 16).

This parameter configures the threshold, which must be fallen below to consider source 2 as "OK" again.

EN	S2 overvoltage fail		
DE	S2 Überspannung auslösen		
CL2	{0}	{1}	{2}
4472	✓	✓	✓

Source 2 overvoltage fail 50.0 to 125.0 %

① This value refers to the Rated voltage Source 2 (Parameter 1772 on page 16).

This parameter configures the threshold, which must be exceeded to consider source 2 as "not OK".

Monitoring: Source 2 Monitoring: Overfrequency

Three-phase measurement of the frequency is performed, if all voltages are higher than 15 % of the rated value. This permits a very rapid and accurate frequency measurement. The frequency however will be measured properly even if voltage is applied to one phase only.

EN	S2 overfrequency monitoring			Source 2 overfrequency monitoring	ON / OFF
DE	S2 Überfrequenz Wächter				
CL2	{0}	{1}	{2}	This parameter configures, whether overfrequency monitoring for source 2 is performed. OFF No overfrequency monitoring is performed for source 2. ON Overfrequency monitoring is performed for source 2.	
4473	✓	✓	✓		
EN	S2 overfrequency restore			Source 2 overfrequency restore	50.0 to 130.0 %
DE	S2 Überfrequenz rücksetzen				
CL2	{0}	{1}	{2}	① This value refers to the Rated system frequency (Parameter 1750 on page 16).	
4474	✓	✓	✓		
				This parameter configures the threshold, which must be fallen below to consider source 2 as "OK" again..	
EN	S2 overfrequency fail			Source 2 overfrequency fail	50.0 to 130.0 %
DE	S2 Überfrequenz auslösen				
CL2	{0}	{1}	{2}	① This value refers to the Rated system frequency (Parameter 1750 on page 16).	
4475	✓	✓	✓		
				This parameter configures the threshold, which must be exceeded to consider source 2 as "not OK".	

Monitoring: Source 2 Monitoring: Voltage Imbalance

The voltage imbalance monitoring is practically used to detect defective fuses in certain phases. The voltage imbalance monitoring measures voltage differences between the phases of source 2. The voltage is measured three-phase. If the phase-to-phase voltage difference between the three phases exceeds the configured imbalance limit the alarm will be issued.

EN	S2 voltage imbalance monitoring			Source 2 voltage imbalance monitoring	ON / OFF
DE	S2 Asymmetrie Wächter				
CL2	{0}	{1}	{2}	<p>This parameter configures, whether voltage imbalance monitoring for source 1 is performed.</p> <p>OFF..... No voltage imbalance monitoring is performed for source 1.</p> <p>ON Voltage imbalance monitoring is performed for source 1.</p>	
4476	✓	✓	✓		
EN	S2 volt. imbalance restore			Source 2 voltage imbalance restore	0.5 to 99.9 %
DE	S2 Asymmetrie rücksetzen				
CL2	{0}	{1}	{2}	<p>① This value refers to the Rated voltage Source 2 (Parameter 1772 on page 16).</p> <p>This parameter configures the threshold, which must be fallen below to consider source 2 as "OK" again..</p>	
4477	✓	✓	✓		
EN	S2 volt. imbalance fail			Source 2 voltage imbalance fail	0.5 to 99.9 %
DE	S2 Asymmetrie auslösen				
CL2	{0}	{1}	{2}	<p>① This value refers to the Rated voltage Source 2 (Parameter 1772 on page 16).</p> <p>This parameter configures the threshold, which must be exceeded to consider source 2 as "not OK".</p>	
4478	✓	✓	✓		
EN	Delay			Source 2 voltage imbalance delay	0.02 to 99.99 s
DE	Verzögerung				
CL2	{0}	{1}	{2}	<p>If the monitored voltage imbalance of source 2 exceeds the threshold value for the delay time configured here, an alarm will be issued.</p>	
3904	✓	✓	✓		

Monitoring: Source 2 Monitoring: Phase Rotation

**CAUTION**

Please ensure during installation that all voltages applied to this unit are wired correctly to both sides of the circuit breaker. Failure to do so may result in damage to the control unit and/or generation equipment due to closing the breaker asynchronous or with mismatched phase rotations and phase rotation monitoring enabled at all connected components (engine, generator, breakers, cable, busbars, etc.).

This function may block a connection of systems with mismatched phases systems only under the following conditions:

- The voltages being measured are wired correctly with respect to the phase rotation at the measuring points (i.e. the voltage transformer in front and behind the circuit breaker)
- The measuring voltages are wired without angular phase shift or interruption from the measuring point to the control unit
- The measuring voltages are wired to the correct terminals of the control unit (i.e. L1 of the generator is connected with the terminal of the control unit which is intended for the L1 of the generator)

Correct phase rotation of the phase voltages ensures that damage will not occur during a transfer to either source 1 or source 2. The voltage phase rotation monitoring checks the phase rotation of the voltages and the configured phase rotation to ensure they are identical. The directions of rotation are differentiated as "clockwise" and "counter-clockwise". With a clockwise field the direction of rotation is "L1-L2-L3"; with a counter clockwise field the direction of rotation is "L1-L3-L2". If the control is configured for a clockwise rotation and the voltages into the unit are calculated as counterclockwise the alarm will be initiated.

A connection to certain source is only possible if this source has the correct phase sequence. If a source has a wrong phase sequence, a connection to this source is not possible.

EN	S2 phase rotation monitoring			Source 2 phase rotation monitoring	ON / OFF
DE	S2 Drehfeldüberwachung			This parameter configures, whether phase rotation monitoring for source 2 is performed.	
	(0)	(1)	(2)		
CL2 4566	✓	✓	✓	OFF.....	No phase rotation monitoring is performed for source 2.
				ON.....	Phase rotation monitoring is performed for source 2.

EN	S2 phase rotation			Source 2 phase rotation	CW / CCW
DE	S2 Drehfeld			This parameter configures the phase rotation of the system. If a different phase rotation is detected at source 2, source 2 is considered as "not OK" and a transfer to source 1 is initiated.	
	(0)	(1)	(2)		
CL2 4567	✓	✓	✓	CW.....	The three-phase measured generator voltage is rotating CW (clockwise; that means the voltage rotates in direction L1-L2-L3; standard setting).
				CCW.....	The three-phase measured generator voltage is rotating CCW (counter-clockwise; that means the voltage rotates in direction L1-L3-L2; standard setting).

Monitoring: In-Phase Monitoring (Synch Check)

The in-phase monitoring function is used to determine whether the phase angles of the preferred source and the non-preferred source are in phase, i.e. whether the relative phase difference of the two sources is within specified limits.

Whenever one power source fails, the control follows the programmed transition operation sequence. If in-phase monitoring is enabled and both sources are available as determined by the "restore value" levels, the control shall follow the in-phase monitoring operation sequence.

In-phase Monitoring may be used to improve the transfer with open transition switches. An open (standard) transition transfer switch is the most simple and commonly used ATS. It may only take on two positions, connected with source 1, or connected with source 2. If it transfers a load, this will be performed according to the break-before-make process, i.e. the load will be disconnected from the previous source before it will be connected with the next source. This results a dead time of approximately 160 ms (depending on the ATS) during which the load is not connected to a source. Most of the load consumers are not effected by this dead time in the transfer phase (lamps may only flicker, etc.), but some appliances may be effected seriously, like computers and motor loads, etc. This may lead to damages of the equipment or data loss in the worst case. The problem is that the consumers behave like generators during this dead time and supply power. While some consumers are running out when changing to the other source, very high current may flow between generator and load because the phase angles between the two systems are not synchronous.

This high equalizing current may be minimized with two means:

- Using a transfer switch with neutral position

If a delayed transition switch is used, the residence time in neutral position may be timed as long until the voltages at the load are settled so far that a transfer to the other source is possible.

- Using inphase monitoring

Inphase monitoring checks the phase angle between source 1 and source 2 prior to a transfer and enables the transfer signal only if the phase angle has fallen below a configured threshold. Moreover, the unit calculates the leading angle for the closing commands by entering the "Switch reaction time" to enable a transfer with almost 0° phase shift. This ensures a nearly synchronous transfer to the other source and reduces the equalizing current to a minimum. Compared with the neutral position of a delayed transition switch, the advantage is that the load must not be shut down completely prior to a transfer.

Inphase monitoring may be used with open, delayed, and closed transition switches. As mentioned above, high equalizing current after a transfer may be minimized when utilizing inphase monitoring. However, the behavior of the ATS in case of a failed inphase transition must be considered. This may happen if the generator is equipped with a poorly adjusted frequency controller. Then, it may happen that it is not possible to achieve synchronicity. But the load must be transferred to the other source in any case.



NOTE

Refer to Parameter 4582 "Outcome on in-phase timeout" for the ATS behavior in case of a failed inphase transition.

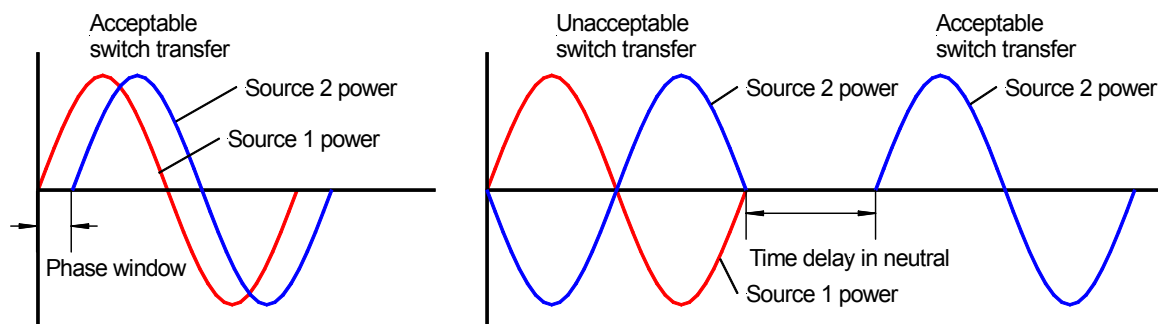


Figure 3-21: Inphase monitoring

Monitoring: Inphase Monitoring: Parameters

DE	EN	In-Phase monitor			Inphase monitoring	ON / OFF
		Synchrocheck				
CL2	{0}	{1}	{2}	This parameter configures, whether inphase monitoring is performed. OFF No inphase monitoring is performed prior to a transfer. ON Inphase monitoring is performed prior to a transfer. If the phase angle between both systems is within the permissible limits, the transfer will be performed.		
4570	✓	✓	✓			

**NOTE**

The following voltages are monitored by the inphase monitoring function depending on the configuration of the measurement principle (Parameter 1862 or 1861):

- 4Ph 3W : V_{L12}
- 3Ph 3W : V_{L12}
- 4Ph 3W : V_{L12} or V_{L1N} depending on the configuration of Parameter 1858
- 1Ph 3W : V_{L1N}

If inphase monitoring enabled and the measurement principle for source 1 (Parameter 1862) is configured as "1Ph 2W", the measurement principle for source 2 (Parameter 1861) must also be configured as "1Ph 2W".

DE EN	Voltage window			Voltage window for synchronization	0.50 to 10.00 %
	Spannungsdifferenz				
CL2 4571	{0} ✓	{1} ✓	{2} ✓	① This value refers to the Rated voltage Source 1/2 (Parameters 1774/1772 on page 16).	

This parameter configures the maximum permissible voltage difference in each of the three phases. The voltage differences in all three phases ($V_{L1}(\text{Source 1}) - V_{L1}(\text{Source 2}) / V_{L2}(\text{Source 1}) - V_{L2}(\text{Source 2}) / V_{L3}(\text{Source 1}) - V_{L3}(\text{Source 2})$) must be within the limit configured here to be able to synchronize.

If the voltage difference in at least one phase exceeds this limit, the synchronization will not be enabled.

DE EN	Positive frequency window			Positive frequency window for synchronization	0.02 to 0.49 Hz
	Maximaler positiver Schlupf				
CL2	{0}	{1}	{2}	This parameter configures the maximum permissible positive frequency difference between source 2 and source 1 ($\Delta f = S2-S1$). If the frequency difference is not within the limits configured here, the synchronization will not be enabled because the frequency difference of the source to be connected to is too high.	
4572	✓	✓	✓		

DE	Negative frequency window			Negative frequency window for synchronization	-0.02 to -0.49 Hz
	Maximaler negativer Schlupf				
CL2	{0}	{1}	{2}	This parameter configures the minimum permissible negative frequency difference between source 2 and source 1 ($\Delta f = S2-S1$). If the frequency difference is not within the limits configured here, the synchronization will not be enabled because the frequency difference of the source to be connected to is too low.	
4573	✓	✓	✓		

Maximum Overlap Time

NOTE
This function is only effective if the transfer switch type (parameter 3424) is configured to "Closed" and in-phase monitoring (parameter 4570) is enabled.

NOTE
If the **LogicsManager** function "Extended parallel time" (parameter 12860) is TRUE, the maximum overlap time is not effective.

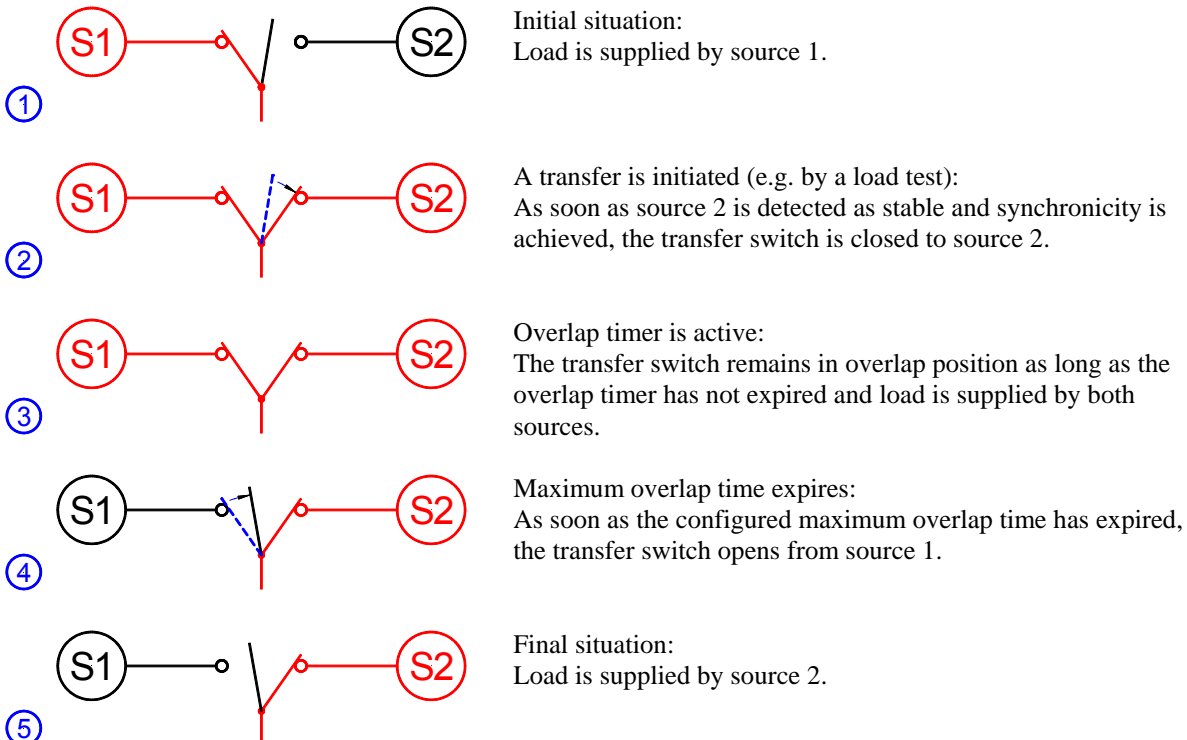
Exception: If the maximum overlap time is configured to 0.1 s, an extended parallel time is not possible regardless of the state of this function.

If a closed transition is performed, the overlap time of the make-before-break process, in which both sources are parallel, is less than 100 ms. If this time is to be extended, an overlap timer is available to keep the transition switch in overlap position for a configured time. The timer starts as soon as the transition switch is in overlap position. The source, from which the transfer has been initiated, will be disconnected and the load will be supplied by the new source as soon as this timer has expired.

EN	Max. overlap time			Maximum overlap time	0.1 to 9.99 s
	Max. Synchronzeit				
CL2	{0}	{1}	{2}	0.10If the maximum overlap time is configured to 0.10 s, an overlap time below 100 ms, which depends on the used transfer switch, will be effective and "Extended parallel time" (parameter 12860) is disabled.	0.11 - 9.99.....The time for which the transfer switch shall remain in overlap position is configured here.
4577	✓	✓	✓		

NOTE
If one source fails before this timer expires, the failed source will automatically be disconnected.

The following example shows a typical transfer sequence from source 1 to source 2 with overlap timer:



Switch Reaction Time Configuration

EN	Open trans. switch reac. time		
DE	Schaltzeit bei nicht Überlapp.		
CL2	{0}	{1}	{2}
4578	✓	✓	✓

Open transition switch reaction time

15 to 300 ms

The time, which is required by the switch in open transition mode to open from one source and close to the other source, is configured here.

This time is required for calculating the lead angle for inphase transfers.

EN	Closed trans. switch reac. time		
DE	Schalterzeit bei Überlapp.		
CL2	{0}	{1}	{2}
4583	✓	✓	✓

Closed transition switch reaction time

15 to 300 ms

The time, which is required by the switch in closed transition mode to close to the other source to get parallel, is configured here.

This time is required for calculating the lead angle for inphase transfers.

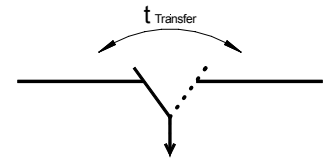


Figure 3-22: Switch reaction time

Vector Group Angle Adjustment



WARNING

Ensure the following parameters are configured correctly to prevent wrong synchronization settings. Incorrect wiring of the system cannot be compensated with this parameter!

EN	Vector group angle adjustment		
DE	Schaltgruppe Winkel Anpassung		
CL2	{0}	{1}	{2}
4581	✓	✓	✓

Vector group angle adjustment

-180° to 180°

This parameter compensates for phase angle deviations, which can be caused by transformers (i.e. a delta to wye transformer) located within the electrical system. Ensure the following parameters are configured correctly to prevent wrong synchronization settings. Incorrect wiring of the system cannot be compensated for with this parameter!

Please act as follows: If a transformer is not located between systems [A] and [B] or if the transformer has a vector group without a phase angle deviation, then a phase angle deviation of 0° should be configured in this parameter.

1. Interconnection of the mains voltage possible

With a phase angle deviation of 0° and the generator not running and source 1 energized, close both breakers. This will result in system [A] and system [B] being at the same voltage potential. The phase angle deviation will now be displayed on the DTSC-200 Counters screen (refer to the Navigation section of the Operation manual 37387). Enter the displayed value into this parameter.



CAUTION

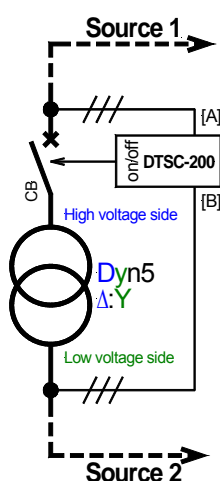
The correct setting must be validated in every control unit with a differential voltage measurement!

2. Interconnection of the mains voltage not possible but the vector group of the transformer is known
 The vector group of the transformer is known and states the phase angle deviation in multiplies of 30° . Out of the vector group the phase angle deviation α can be calculated as an angle from 0° to 360° . **For this value the voltage of the low voltage side is behind the voltage of the high voltage side \Rightarrow phase angle deviation α !**
When calculating the resulting value, the low voltage side of the transformer always lags behind the high voltage side (phase angle deviation α).

The phase difference is to be calculated as follows:

	High voltage side = System [A]	High voltage side = System [B]
$\alpha < 180^\circ$	α	$-\alpha$
$\alpha > 180^\circ$	$-360^\circ + \alpha$	$360^\circ - \alpha$

Table 3-23: Calculation of the phase angle deviation

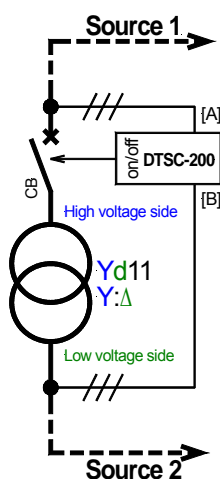


Example 1

System [B] is connected to source 2. Source 2 voltage is connected to the low voltage side of a transformer with the vector group **Dyn5**. The source 1 breaker is connected to the high voltage side, which connects the transformer to the mains. System [A] is connected to source 1. Because of the transformer the phase angles at the breaker differ between the measuring voltages of system [A] and system [B]. A phase angle deviation exists which can be compensated with the DTSC-200.

Using the vector group 5 (Dyn5) it counts $\alpha = 5 \times 30^\circ = 150^\circ$. Because $150^\circ < 180^\circ$ and system [A] is connected to the high voltage side this results into α to be used as phase difference. Enter **150°** into as parameter for the phase difference.

Vector group angle
adjustment **+150°**



Example 2

Data identical with example 1, but the vector group is **Yd11**.

Using the vector group 11 (Yd11) it counts $\alpha = 11 \times 30^\circ = 330^\circ$. Because $330^\circ > 180^\circ$ and system [A] is connected to the high voltage side this results into $(-360^\circ + \alpha)$ to be used as phase difference. Enter **-30°** into as parameter for the phase difference.

Vector group angle
adjustment **-030°**



CAUTION

The correct setting must be validated in every control unit with a differential voltage measurement!

Outcome on Inphase Timeout

EN	In-phase timeout after	Inphase timeout after	0 to 6,500 s
DE	Synchr. Zeitüberschr.		
CL2 4576	{0} ✓	{1} ✓	{2} ✓

This parameter configures the maximum time for attempting to detect synchronicity. This timer starts to count as soon as inphase monitoring is enabled prior to a transfer. If synchronicity is detected between the two sources, the transfer command will be issued. The timer will be bypassed.

EN	Outcome on In-phase timeout	Outcome on inphase timeout	Abort / Delayed
DE	Aktion bei Sync. Zeitüberschr.		
CL2 4582	{0} ✓	{1} ✓	{2} ✓

This parameter determines the behavior of the unit following an unsuccessful synchronicity detection using the following options:

Abort The transfer will be aborted.

Delayed A delayed transition will be performed.

Example:

If a load test is requested and inphase monitoring is enabled (parameter 4570 is configured to "ON"), the inphase timeout timer (parameter 4576) starts prior to a transfer and the unit attempts to detect a synchronicity between the two sources. If no synchronicity can be detected before the timer expires (because of a misadjusted voltage or speed controller at the engine for example), the behavior configured here determines the further transfer proceeding.

If **Abort** is configured here, the complete transfer request will be aborted. This means that all remote start requests (like load test) will be ignored if they are still present and the system will remain on the available source.

If **Delayed** is configured here, a delayed transition will be performed. This means that the switch changes to neutral position for a configured time to ramp down connected motor loads before it changes to the other source. This is important because motors, which are running down, may act as generators, which may lead to a detection of a failed synchronization in case of a too early transfer.

Note: This function may only be used, if "Delayed" or "Closed" is configured as "Transfer switch type" (Parameter 3424). If "Standard" is configured as "Transfer switch type" (Parameter 3424) and "Outcome on In-phase timeout" is configured to "Delayed", the unit behaves as if "Abort" would have been configured here.

Monitoring: Overcurrent

Current is monitored depending on Parameter 1860 "Load current measuring". The load overcurrent alarm contains three limits and can be setup as a step definite time overcurrent alarm as illustrated in the figure below. Monitoring of the maximum phase current is performed in three steps. Every step can be provided with a delay time independent of the other steps.

If this protective function is triggered, the alarm list indicates "Overcurrent 1", "Overcurrent 2", or "Overcurrent 3".

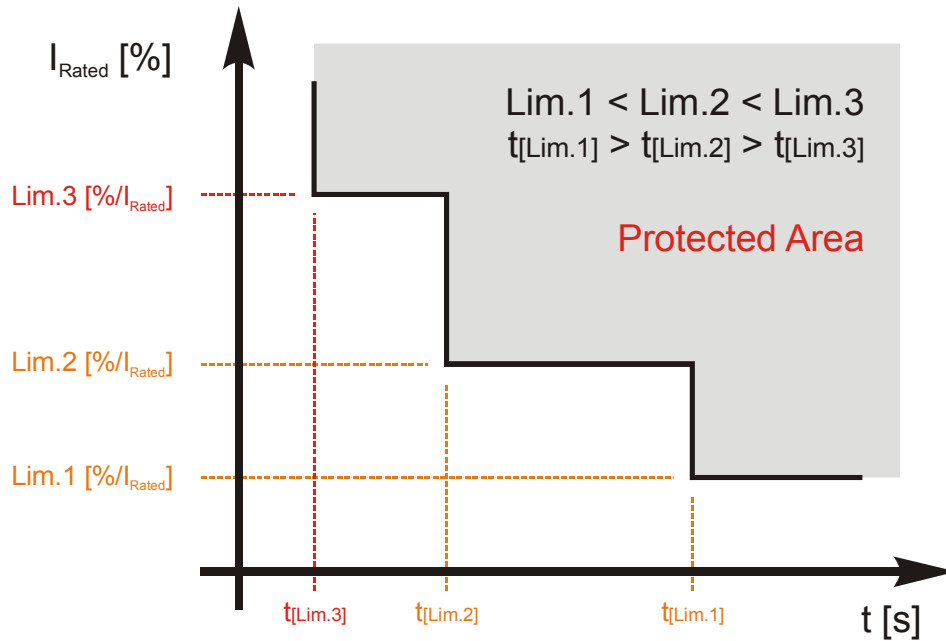


Figure 3-24: Monitoring - load time-overcurrent

Parameter table

The parameters represented in this table are specified in the following, whereas the description is identical for all levels; the levels may only differ in their setting ranges.

Level	Text	Setting range	Standard value
Overcurrent (the hysteresis is 1 % of the rated value)			
Level 1	Monitoring	ON / OFF	ON
	Limit	50.0 to 300.0 %	110.0 %
	Delay	0.02 to 99.99 s	30.00 s
	Self-acknowledgment	YES / NO	NO
Level 2	Monitoring	ON / OFF	ON
	Limit	50.0 to 300.0 %	150.0 %
	Delay	0.02 to 99.99 s	1.00 s
	Self-acknowledgment	YES / NO	NO
Level 3	Monitoring	ON / OFF	ON
	Limit	50.0 to 300.0 %	250.0 %
	Delay	0.02 to 99.99 s	0.40 s
	Self-acknowledgment	YES / NO	NO

Table 3-3: Monitoring - standard values - load time-overcurrent

DE	EN	Monitoring		
		Überwachung		
CL2		{0}	{1}	{2}
2200		✓	✓	✓
2206				
2212				

Load overcurrent, TOC: Monitoring (Level 1/Level 2/Level 3)**ON / OFF**

ON..... Overcurrent monitoring is carried out according to the following parameters. Monitoring is performed at three levels. All three values may be configured independent from each other (prerequisite: Level 1 < Level 2 < Level 3).

OFF..... Monitoring is disabled for level 1, level 2, and/or level 3.

DE	EN	Limit		
		Limit		
CL2		{0}	{1}	{2}
2204		✓	✓	✓
2210				
2216				

Load overcurrent, TOC: Threshold value (Level 1/Level 2/Level 3)**50.0 to 300.0 %**

④ This value refers to the Rated current (Parameter 1754, see page 16).

The percentage values that are to be monitored for each threshold limit are defined here. If this value is reached or exceeded for at least the delay time without interruption, an alarm is issued.

DE	EN	Delay		
		Verzögerung		
CL2		{0}	{1}	{2}
2205		✓	✓	✓
2211				
2217				

Load overcurrent, TOC: Delay (Level 1/Level 2/Level 3)**0.02 to 99.99 s**

If the monitored load current exceeds the threshold value for the delay time configured here, an alarm will be issued. If the monitored load current falls below the threshold (minus the hysteresis) before the delay expires the time will be reset.

DE	EN	Self acknowledge		
		Selbstquittierend		
CL2		{0}	{1}	{2}
2202		✓	✓	✓
2208				
2214				

Load overcurrent, TOC: Self acknowledgment (Level 1/Level 2/Level 3)**ON / OFF**

YES..... The control automatically clears the alarm if it is no longer valid.

NO..... An automatic reset of the alarm does not occur. The reset occurs manually by pressing the appropriate buttons, by activating the *LogicsManager* output "External acknowledgement" via an discrete input, or via an interface.

Monitoring: Overload

Power is monitored depending on parameter 1861 "S2 voltage measuring" and parameter 1860 "Load current measuring". If the real power is above the configured limit an alarm will be issued.

If this protective function is triggered, the alarm list indicates "Overload 1" or "Overload 2".

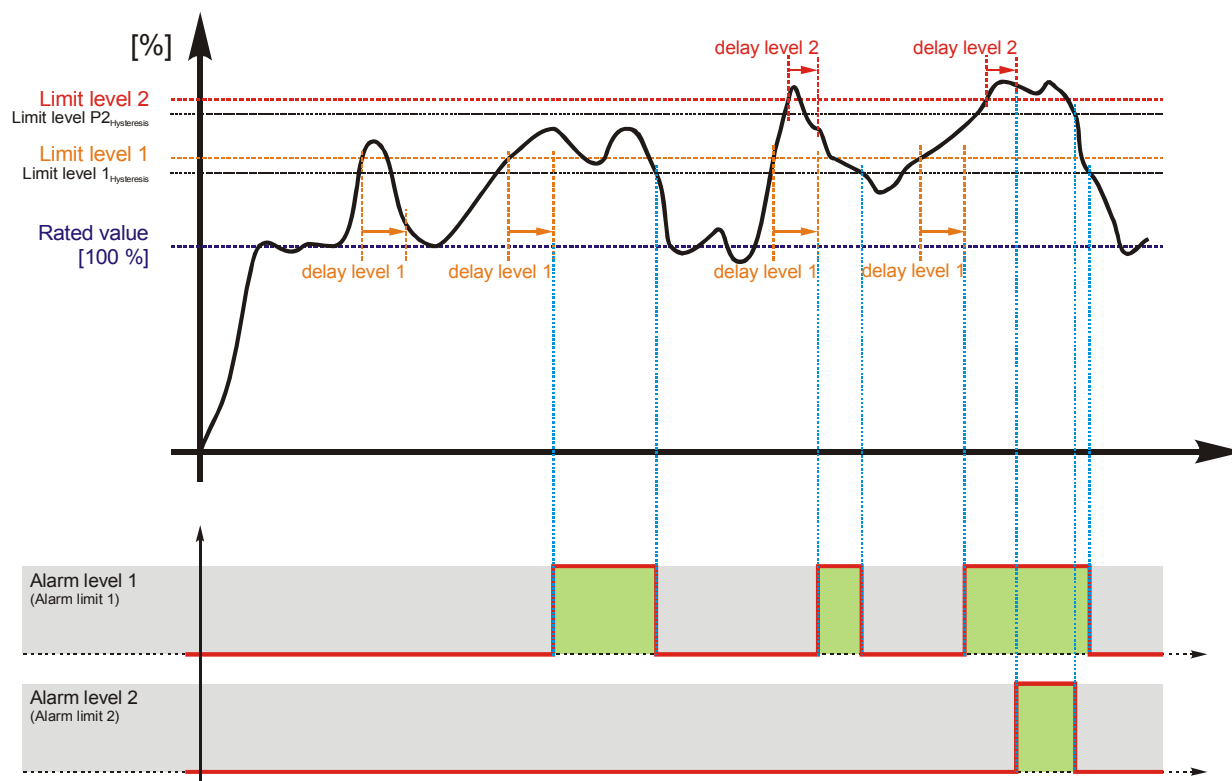


Figure 3-25: Monitoring - overload

Parameter table

The parameters represented in this table are specified in the following, whereas the description is identical for all levels; the levels may only differ in their setting ranges.

Level	Text	Setting range	Standard value
Overload (the hysteresis is 1 % of the rated value)			
Level 1	Monitoring	ON / OFF	ON
	Limit	50.0 to 300.0 %	110.0 %
	Delay	0.02 to 99.99 s	11.00 s
	Self-acknowledgment	YES / NO	NO
Level 2	Monitoring	ON / OFF	ON
	Limit	50.0 to 300.0 %	120.0 %
	Delay	0.02 to 99.99 s	0.10 s
	Self-acknowledgment	YES / NO	NO

Table 3-4: Monitoring - standard values - overload

DE	EN		Monitoring
			Überwachung
CL2	{0}	{1}	{2}
2300	✓	✓	✓
2306			

Overload: Monitoring (Level 1/Level 2)**ON / OFF**

ON..... Overload monitoring is carried out according to the following parameters. Monitoring is performed at two levels. Both values may be configured independent from each other (prerequisite: limit 1 < limit 2).

OFF..... Monitoring is disabled for level 1 and/or level 2.

DE	EN		Limit
			Limit
CL2	{0}	{1}	{2}
2304	✓	✓	✓
2310			

Overload: Threshold value (Level 1/Level 2)**50.0 to 300.00 %**

④ This value refers to the Rated active power (Parameter 1752, see page 16).

The percentage values that are to be monitored for each threshold limit are defined here. If this value is reached or exceeded for at least the delay time without interruption, an alarm is issued.

DE	EN		Delay
			Verzögerung
CL2	{0}	{1}	{2}
2305	✓	✓	✓
2311			

Overload: Delayed (Level 1/Level 2)**0.02 to 99.99 s**

If the monitored load exceeds the threshold value for the delay time configured here, an alarm will be issued. If the monitored load falls below the threshold (minus the hysteresis) before the delay expires the time will be reset.

DE	EN		Self acknowledge
			Selbstquittierend
CL2	{0}	{1}	{2}
2302	✓	✓	✓
2308			

Overload: Self acknowledgment (Level 1/Level 2)**YES / NO**

YES..... The control automatically clears the alarm if it is no longer valid.

NO..... An automatic reset of the alarm does not occur. The reset occurs manually by pressing the appropriate buttons, by activating the *LogicsManager* output "External acknowledgement" via an discrete input, or via an interface.

Monitoring: Engine, Start Failure Source 1

If this protective function is triggered, the alarm list indicates "Start Fail S1".

EN	S1 start fail delay time			Source 1 start fail: delay time	1 to 100 s
	S1 Startfehler Zeit				
CL2	{0}	{1}	{2}	If the "S1 start delay" timer has expired, the engine start signal will be issued. If the "engine start" relay de-energizes, "Source 1 start fail delay" timer starts to count. Now, the controller expects the engine to start within the time configured here. If this time will be exceeded, a "Start Fail" alarm will be issued.	If this timer is running, the "Starting S1" message is displayed.
3341	---	---	✓		
This parameter is only visible, if the application mode (Parameter 4148) is configured to "Gen-Gen".					

Monitoring: Engine, Start Failure Source 2

If this protective function is triggered, the alarm list indicates "Start Fail S2".

DE	EN	S2 start fail delay time			Source 2 start fail: delay time	1 to 100 s
		S2 Startfehler Zeit				
CL2	{0}	{1}	{2}	If the "S2 start delay" timer has expired, the engine start signal will be issued. If the "engine start" relay de-energizes, "Source 2 start fail delay" timer starts to count. Now, the controller expects the engine to start within the time configured here. If this time will be exceeded, a "Start Fail" alarm will be issued.	If this timer is running, the "Starting S2" message is displayed.	
3331	✓	✓	✓			

Monitoring: Battery, Overvoltage

There are two battery overvoltage alarm levels available in the control. Both alarms are definite time alarms and are illustrated in the below figure. The figure diagrams a frequency trend and the associated pickup times and length of the alarms. It should be noted that this figure illustrates a level 1 alarm that is self-acknowledged.

Monitoring of the voltage is done in two steps.

If this protective function is triggered, the alarm list indicates "**Batt. overvolt.1**" or "**Batt. overvolt.2**".

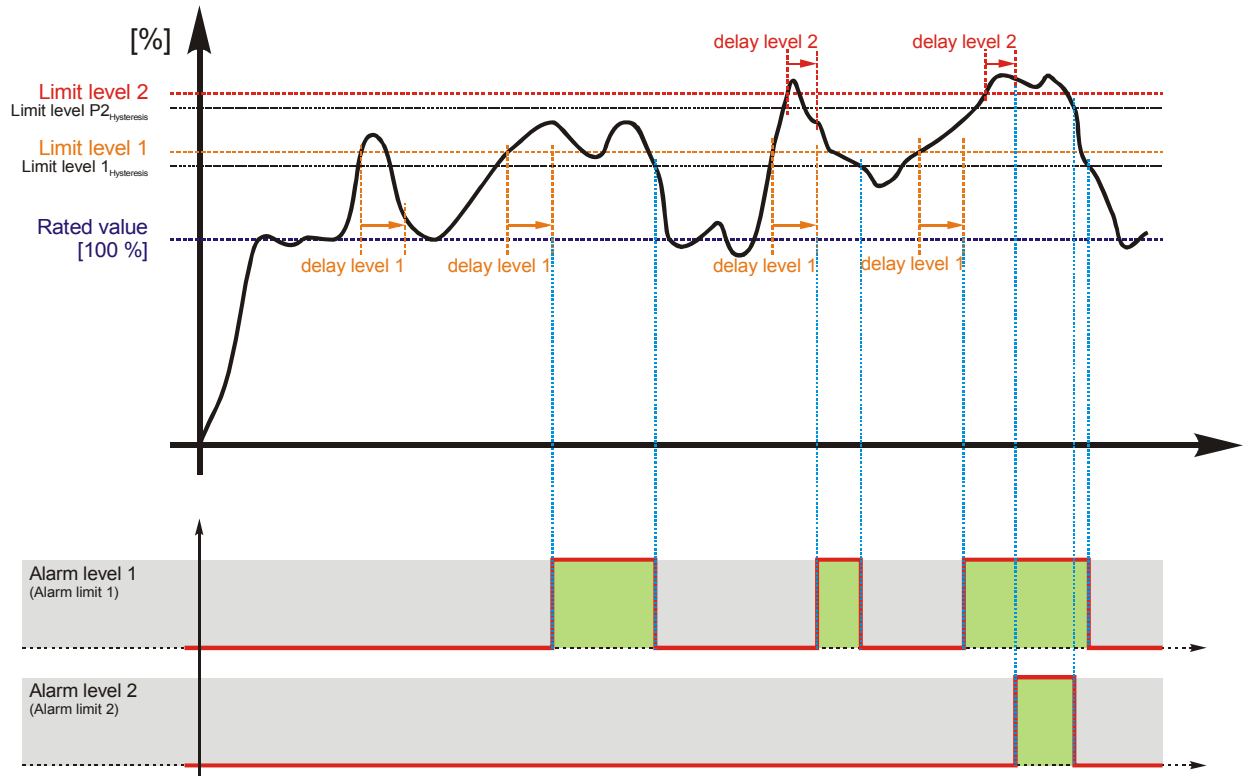


Figure 3-26: Monitoring - battery overvoltage

Parameter table

The parameters represented in this table are specified in the following, whereas the description is identical for all levels; the levels may only differ in their setting ranges.

Level	Text	Setting range	Standard value
Battery overvoltage (the hysteresis is 0,7 % of the rated value.)			
Level 1	Monitoring	ON / OFF	ON
	Limit	8.0 to 42.0 V	32.0 V
	Delay	0.02 to 99.99 s	5.00 s
	Self-acknowledgment	YES / NO	NO
Level 2	Monitoring	ON / OFF	OFF
	Limit	8.0 to 42.0 V	35.0 V
	Delay	0.02 to 99.99 s	1.00 s
	Self-acknowledgment	YES / NO	NO

Table 3-5: Monitoring - standard values - battery overvoltage

EN	Monitoring		
DE	Überwachung		
CL2	{0}	{1}	{2}
3450	✓	✓	✓
3456			

Battery overvoltage: Monitoring (Level 1/Level 2)**ON / OFF**

ONOvervoltage monitoring of the battery voltage is carried out according to the following parameters.

OFFMonitoring is disabled for level 1 and/or level 2.

EN	Limit		
DE	Limit		
CL2	{0}	{1}	{2}
3454	✓	✓	✓
3460			

Battery overvoltage: Threshold value (Level 1/Level 2)**8.0 to 42.0 V**

The threshold values that are to be monitored are defined here. If the monitored battery voltage reaches or exceeds this value for at least the delay time without interruption, an alarm is issued.

EN	Delay		
DE	Verzögerung		
CL2	{0}	{1}	{2}
3455	✓	✓	✓
3461			

Battery overvoltage: Delay time (Level 1/Level 2)**0.02 to 99.99 s**

If the monitored battery voltage exceeds the threshold value for the delay time configured here, an alarm will be issued. If the monitored battery voltage falls below the threshold (minus the hysteresis) before the delay expires the time will be reset.

EN	Self acknowledge		
DE	Selbstquittierend		
CL2	{0}	{1}	{2}
3452	✓	✓	✓
3458			

Battery overvoltage: Self acknowledgment (Level 1/Level 2)**YES / NO**

YESThe control automatically clears the alarm if it is no longer valid.

NOAn automatic reset of the alarm does not occur. The reset occurs manually by pressing the appropriate buttons, by activating the *LogicsManager* output "External acknowledgement" via an discrete input, or via an interface.

Monitoring: Battery, Undervoltage

There are two battery undervoltage alarm levels available in the control. Both alarms are definite time alarms and are illustrated in the below figure. The figure diagrams a frequency trend and the associated pickup times and length of the alarms. It should be noted that this figure illustrates a level 1 alarm that is self-acknowledged.

Monitoring of the voltage is done in two steps.

If this protective function is triggered, the alarm list indicates "**Batt.undervolt.1**" or "**Batt.undervolt.2**".

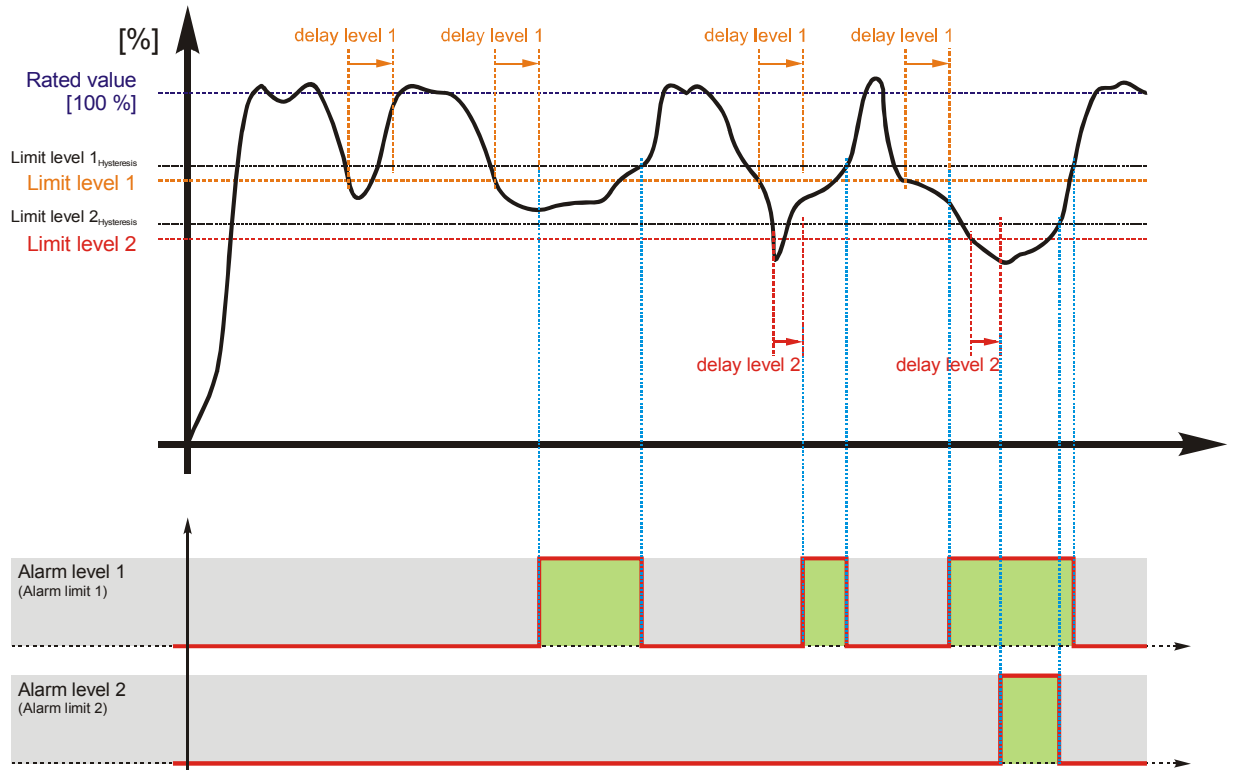


Figure 3-27: Monitoring - battery undervoltage

Parameter table

The parameters represented in this table are specified in the following, whereas the description is identical for all levels; the levels may only differ in their setting ranges.

Level	Text	Setting range	Standard value
Battery undervoltage (The hysteresis is 0,7 % of the rated value).			
Level 1	Monitoring	ON / OFF	ON
	Limit	8.0 to 42.0 V	24.0 V
	Delay	0.02 to 99.99 s	60.00 s
	Self-acknowledgment	YES / NO	NO
Level 2	Monitoring	ON / OFF	ON
	Limit	8.0 to 42.0 V	20.0 V
	Delay	0.02 to 99.99 s	10.00 s
	Self-acknowledgment	YES / NO	NO

Table 3-6: Monitoring - standard values - battery undervoltage

EN	Monitoring		
DE	Überwachung		
CL2	{0}	{1}	{2}
3500	✓	✓	✓
3506			

Battery undervoltage: Monitoring (Level 1/Level 2)**ON / OFF**

ONUndervoltage monitoring of the battery voltage is carried out according to the following parameters.

OFFMonitoring is disabled for level 1 and/or level 2.

EN	Limit		
DE	Limit		
CL2	{0}	{1}	{2}
3504	✓	✓	✓
3510			

Battery undervoltage: Threshold value (Level 1/Level 2)**8.0 to 42.0 V**

The threshold values that are to be monitored are defined here. If the monitored battery voltage reaches or falls below this value for at least the delay time without interruption, an alarm is issued..

Note:

The default monitoring limit for battery undervoltage is 24 Vdc after 60 seconds. This is because in normal operation the terminal voltage is approximately 26 Vdc (alternator charged battery).

EN	Delay		
DE	Verzögerung		
CL2	{0}	{1}	{2}
3505	✓	✓	✓
3511			

Battery undervoltage: Delay time (Level 1/Level 2)**0.02 to 99.99 s**

If the battery voltage falls below the threshold value for the delay time configured here, an alarm will be issued. If the battery voltage exceeds the threshold (plus the hysteresis) again before the delay expires the time will be reset.

EN	Self acknowledge		
DE	Selbstquittierend		
CL2	{0}	{1}	{2}
3502	✓	✓	✓
3508			

Battery undervoltage: Self acknowledgment (Level 1/Level 2)**YES / NO**

YESThe control automatically clears the alarm if it is no longer valid.

NOAn automatic reset of the alarm does not occur. The reset occurs manually by pressing the appropriate buttons, by activating the *LogicsManager* output "External acknowledgement" via an discrete input, or via an interface.

Monitoring: CANopen Interface

The CANopen interface is monitored. If the interface does not receive a CANopen protocol message before the delay expires, an alarm will be initiated.
If this protective function is triggered, the alarm list indicates "CAN Open Fault".

EN

Monitoring

Überwachung

CL2

3150

{0}

{1}

{2}

✓

✓

✓

ON.....

Monitoring of the CANopen interface is carried out according to the following parameters.

OFF.....

Monitoring is disabled.

EN

Delay

Verzögerung

CL2

3154

{0}

{1}

{2}

✓

✓

✓

0.1 to 650.0 s

The delay is configured with this parameter. If the interface does not receive a CANopen protocol message before the delay expires, an alarm is issued. The delay timer is re-initialized after every message is received.

EN

Self acknowledge

Selbstquittierend

CL2

3152

{0}

{1}

{2}

✓

✓

✓

YES.....

The control automatically clears the alarm if it is no longer valid.

NO.....

An automatic reset of the alarm does not occur. The reset occurs manually by pressing the appropriate buttons, by activating the *LogicsManager* output "External acknowledgement" via an discrete input, or via an interface.



NOTE

This protection is only available if an external digital I/O board (e.g. IKD 1) is connected.

Discrete Inputs



Number	Terminal	Function
Internal discrete inputs		
[DI 1]	51	Reply from ATS limit switch: Breaker in source 1 position [S1]
[DI 2]	52	Reply from ATS limit switch: Breaker in source 2 position [S2]
[DI 3]	53	Reply from ATS limit switch: Breaker in source 1 open position [S1O] ^{#1}
[DI 4]	54	Reply from ATS limit switch: Breaker in source 2 open position [S2O] ^{#1}
[DI 5]	55	Control input (<i>LogicsManager</i>), pre-assigned with Inhibit ATS
[DI 6]	56	Control input (<i>LogicsManager</i>)
[DI 7]	57	Control input (<i>LogicsManager</i>)
[DI 8]	58	Control input (<i>LogicsManager</i>)
[DI 9]	59	Control input (<i>LogicsManager</i>)
[DI 10]	60	Control input (<i>LogicsManager</i>)
[DI 11]	61	Control input (<i>LogicsManager</i>)
[DI 12]	62	Control input (<i>LogicsManager</i>)
External discrete inputs (via CANopen; not included in DTSC delivery; can be e.g. IKD1, etc.)		
[DEx01]	---	Control input (<i>LogicsManager</i>)
[DEx02]	---	Control input (<i>LogicsManager</i>)
[DEx03]	---	Control input (<i>LogicsManager</i>)
[DEx04]	---	Control input (<i>LogicsManager</i>)
[DEx05]	---	Control input (<i>LogicsManager</i>)
[DEx06]	---	Control input (<i>LogicsManager</i>)
[DEx07]	---	Control input (<i>LogicsManager</i>)
[DEx08]	---	Control input (<i>LogicsManager</i>)
[DEx09]	---	Control input (<i>LogicsManager</i>)
[DEx10]	---	Control input (<i>LogicsManager</i>)
[DEx11]	---	Control input (<i>LogicsManager</i>)
[DEx12]	---	Control input (<i>LogicsManager</i>)
[DEx13]	---	Control input (<i>LogicsManager</i>)
[DEx14]	---	Control input (<i>LogicsManager</i>)
[DEx15]	---	Control input (<i>LogicsManager</i>)
[DEx16]	---	Control input (<i>LogicsManager</i>)

#1..If the transfer switch type (Parameter 3424) is configured to "Standard", this DI may be used as control input (*LogicsManager*)

Table 3-7: Discrete inputs - assignment

Discrete inputs may be configured to normally open (N.O.) or normally closed (N.C.) states. In the state N.O., no potential is present during normal operation; if a control operation is performed, the input is energized. In the state N.C., a potential is continuously present during normal operation; if a control operation is performed, the input is de-energized.

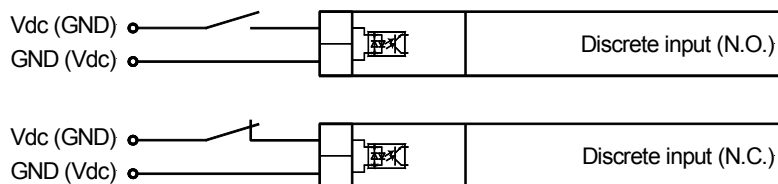


Figure 3-28: Discrete inputs - control inputs - operation logic

NOTE
The discrete inputs for the breaker position reply messages (DIs 1 through 4) are fixed to N.C. and are evaluated as N.C., i.e. the breaker is considered as "in position" if the respective DI is de-energized.

DE	EN	DI {x} operation		
		DI {x} Funktion		
CL2		{0}	{1}	{2}
1281		✓	✓	✓

Discrete input: Operation**N.O. / N.C.**

The discrete inputs may be operated by an normally open (N.O.) or normally closed (N.C.) contact. The idle circuit current input can be used to monitor for a wire break. A positive or negative voltage polarity referred to the reference point of the DI may be applied.

N.O...... The discrete input is analyzed as "enabled" by energizing the input (normally open).

N.C...... The discrete input is analyzed as "enabled" by de-energizing the input (normally closed).

DE	EN	DI {x} delay		
		DI {x} Verzögerung		
CL2		{0}	{1}	{2}
1280		✓	✓	✓

Discrete input: Delay**0.08 to 650.00 s**

A delay time in seconds can be assigned to each alarm or control input. The discrete input must be enabled without interruption for the delay time before the unit reacts. If the discrete input is used within the *LogicsManager* this delay is taken into account as well.

The preceding parameters are used to configure the discrete inputs 5 through 12. The parameter IDs refer to DI 5. Refer to Table 3-8 for the parameter IDs of the parameters DI 6 through DI 12. The DIs 1 through 4 are fixed for breaker position feedback signals to the settings, which are indicated in the List Of Parameters starting on page 123 and cannot be configured. However, they may still be used for other purposes if the breaker position feedback signals are not used.

	DI 5	DI 6	DI 7	DI 8	DI 9	DI 10	DI 11	DI 12
Operation	1281	1301	1321	1341	1361	1381	1206	1226
Delay	1280	1300	1320	1340	1360	1380	1205	1225

Table 3-8: Discrete inputs - parameter IDs

If a Woodward IKD 1 or other external expansion board (Phoenix BK 16DiDo/Co 16DiDo) is connected to the DTSC via the CAN bus, it is possible to use 16 additional discrete inputs.

The configuration of these external DIs is performed in a similar way like for the internal DIs. Refer to Table 3-9 for the parameter IDs of the parameters for external DIs 1 through 16.

External	DI 1	DI 2	DI 3	DI 4	DI 5	DI 6	DI 7	DI 8
Operation	16001	16011	16021	16031	16041	16051	16061	16071
Delay	16000	16010	16020	16030	16040	16050	16060	16070
External	DI 9	DI 10	DI 11	DI 12	DI 13	DI 14	DI 15	DI 16
Operation	16081	16091	16101	16111	16121	16131	16141	16151
Delay	16080	16090	16100	16110	16120	16130	16140	16150

Table 3-9: External discrete inputs - parameter IDs

Discrete Outputs (*LogicsManager*)



The discrete outputs are controlled via the *LogicsManager*.

⇒ Please note the description of the *LogicsManager* starting on page 99.

Some outputs are assigned a function according to the application mode (see following table).

Relay Number	Term.	Function
Internal relay outputs		
[R 1]	31/32	<i>LogicsManager</i>
[R 2]	31/33	<i>LogicsManager</i>
[R 3]	31/34	<i>LogicsManager</i>
[R 4]	35/36/37	<i>LogicsManager</i>
[R 5]	39/40/41	<i>LogicsManager</i> (pre-defined with engine 2 start)
[R 6]	42/43	<i>LogicsManager</i> (pre-defined with command: close to source 1 position) [C1]
[R 7]	44/45	<i>LogicsManager</i> (pre-defined with command: close to source 2 position) [C2]
[R 8]	46/47	<i>LogicsManager</i> (pre-defined with command: open from source 1 to neutral position) [C1O]
[R 9]	48/49	<i>LogicsManager</i> (pre-defined with command: open from source 2 to neutral position) [C2O]
External relay output (via CANopen; not included in DTSC-200 delivery; can be an expansion card like IKD1)		
[REx01]	---	<i>LogicsManager</i>
[REx02]	---	<i>LogicsManager</i>
[REx03]	---	<i>LogicsManager</i>
[REx04]	---	<i>LogicsManager</i>
[REx05]	---	<i>LogicsManager</i>
[REx06]	---	<i>LogicsManager</i>
[REx07]	---	<i>LogicsManager</i>
[REx08]	---	<i>LogicsManager</i>
[REx09]	---	<i>LogicsManager</i>
[REx10]	---	<i>LogicsManager</i>
[REx11]	---	<i>LogicsManager</i>
[REx12]	---	<i>LogicsManager</i>
[REx13]	---	<i>LogicsManager</i>
[REx14]	---	<i>LogicsManager</i>
[REx15]	---	<i>LogicsManager</i>
[REx16]	---	<i>LogicsManager</i>

Table 3-10: Relay outputs - Assignment

DE				Relay {x}
EN				Relais {x}
CL2	{0}	{1}	{2}	
12100	✓	✓	✓	

Digital outputs: *LogicsManager* for relay {x}

LogicsManager

Once the conditions of the *LogicsManager* have been fulfilled, the relay will be energized. The *LogicsManager* and its default settings are explained on page 99 in Appendix A: "*LogicsManager*".

Above parameter IDs refers to R 1. Refer to Table 3-11 for the parameter IDs of the parameters for R 2 to R 9.

	R 1	R 2	R 3	R 4	R 5	R 6	R 7	R 8	R 9
Parameter ID	12100	12110	12310	12320	12130	12140	12150	12160	12170

Table 3-11: Discrete outputs - parameter IDs

If a Woodward IKD 1 or other external expansion board (Phoenix BK 16DiDo/Co 16DiDo) is connected to the DTSC via the CAN bus, it is possible to use 16 additional discrete outputs.

The configuration of these external DOs is performed in a similar way like for the internal DOs. Refer to Table 3-12 for the parameter IDs of the parameters for external DOs 1 through 16.

	DO 1	DO 2	DO 3	DO 4	DO 5	DO 6	DO 7	DO 8
Parameter ID	12330	12340	12350	12360	12370	12380	12390	12400
	DO 9	DO 10	DO 11	DO 12	DO 13	DO 14	DO 15	DO 16
Parameter ID	12410	12420	12430	12440	12450	12460	12470	12480

Table 3-12: External discrete outputs - parameter IDs

Counters



Configure Counters: Operation Hours, kWh, and kvarh

EN	Counter value preset			Counter: Set point value for counters	0 to 99,999,999
DE	Zähler-Setzwert				
CL2 2515	{0} ✓	{1} ✓	{2} ✓		

This value is utilized to set the hours in the following parameters:

- kWh counter
- kvarh counter

The number entered into this parameter is the number that will be set to the parameters listed above when they are enabled.

EN	Set active energy in 0.00MWh			Counter: Set kWh counter	YES / NO
DE	Wirkarbeit setzen in 0,00MWh				
CL2 2510	{0} ✓	{1} ✓	{2} ✓		

YES..... The current value of this counter is overwritten with the value configured in "set point value for counters". After the counter has been (re)set, this parameter changes back to "NO" automatically.

NO The value of this counter is not changed.

EN	Set reactive energy in 0.00MWh			Counter: Set kvarh counter	YES / NO
DE	Blindarbeit setzen in 0,00MWh				
CL2 2511	{0} ✓	{1} ✓	{2} ✓		

YES..... The current value of this counter is overwritten with the value configured in "set point value for counters". After the counter has been (re)set, this parameter changes back to "NO" automatically.

NO The value of this counter is not changed.



NOTE

Example: The counter value preset (parameter 2515 on page 80) is configured to "3456".

If parameter 2510 will be configured to YES, the active energy counter will be set to 34.56MWh.

LogicsManager



LogicsManager: Internal Flags

Internal flags within the *LogicsManager* logical outputs may be programmed and used for multiple functions. For conditions and explanation of programming please refer to page 99 in chapter "*LogicsManager*".

EN

DE

CL2

yyyyy

Flag {x}

Merker {x}

{0}

{1}

{2}

✓

✓

✓

Internal flags: Flag {x} [x = 1 to 8]

LogicsManager

The flags may be used as auxiliary flags for complex combinations by using the logical output of these flags as command variable for other logical outputs.

Parameter ID yyyyy	Flag {x}
12230	Flag 1
12240	Flag 2
12250	Flag 3
12260	Flag 4
12270	Flag 5
12280	Flag 6
12290	Flag 7
12300	Flag 8

Table 3-13: Internal flags - parameter IDs



NOTE

Flag 1 is also used as placeholder in other logical combinations. Flag 8 is preset with a timer start.

LogicsManager: Timer

LogicsManager: Daily Time Set Point

Utilizing the *LogicsManager* it is possible to establish specific times of the day that functions (i.e. generator exerciser) can be enabled. The two daily time set points are activated each day at the configured time. Using the *LogicsManager* these set points may be configured individually or combined to create a time range.

EN	Setpoint {x}: Hour			Timer: Daily time set point {x} [x = 1/2]: hour	0 to 23 h
DE	Setpoint {x}: Stunde				
CL2	{0}	{1}	{2}	Enter the hour of the daily time set point here. Example:	
1652	✓	✓	✓	00 th hour of the day (midnight).	
1657				2323 rd hour of the day (11pm).	
EN	Setpoint {x}: Minute			Timer: Daily time set point {x} [x = 1/2]: minute	0 to 59 min
DE	Setpoint {x}: Minute				
CL2	{0}	{1}	{2}	Enter the minute of the daily time set point here. Example:	
1651	✓	✓	✓	00 th minute of the hour.	
1656				5959 th minute of the hour.	
EN	Setpoint {x}: Second			Timer: Daily time set point {x} [x = 1/2]: second	0 to 59 s
DE	Setpoint {x}: Sekunde				
CL2	{0}	{1}	{2}	Enter the second of the daily time set point here. Example	
1650	✓	✓	✓	00 th second of the minute.	
1655				5959 th second of the minute.	

LogicsManager: Active Time Set Point

Utilizing the *LogicsManager* it is possible to establish specific days (or hours, minutes, seconds) that functions (i.e. generator exerciser) can be enabled. The active switching point is activated only on a specified day (or hour, minute, second). The set points may be configured individually or combined via the *LogicsManager*. You may configure monthly, daily, hourly, minutely, or even secondly time set points depending on how you combine the set points in the *LogicsManager*.

EN	Active day			Timer: Active time set point: day	1 to 31
DE	Aktiver Tag				
CL2	{0}	{1}	{2}	<p>Enter the day of the active switch point here. Example:</p> <p>011st day of the month.</p> <p>3131st day of the month.</p> <p>The active time set point is enabled during the indicated day from 0:00:00 hours to 23:59:59 hours.</p>	
1663	✓	✓	✓		
EN	Active hour			Timer: Active time set point: hour	0 to 23 h
DE	Aktive Stunde				
CL2	{0}	{1}	{2}	<p>Enter the hour of the active switch point here. Example:</p> <p>00th hour of the day.</p> <p>2323rd hour if the day.</p> <p>The active time set point is enabled every day during the indicated hour from minute 0 to minute 59.</p>	
1662	✓	✓	✓		
EN	Active minute			Timer: Active time set point: minute	0 to 59 min
DE	Aktive Minute				
CL2	{0}	{1}	{2}	<p>Enter the minute of the active switch point here. Example:</p> <p>00th minute of the hour.</p> <p>5959th minute of the hour.</p> <p>The active time set point is enabled every hour during the indicated minute from second 0 to second 59.</p>	
1661	✓	✓	✓		

EN	Active second			Timer: Active time set point: second	0 to 59 s
DE	Aktive Sekunde				
CL2	{0}	{1}	{2}	Enter the second of the active switch point here. Example:	
1660	✓	✓	✓	0.....0 th second of the minute.	
				59.....59 th second the minute.	
				The active time set point is enabled every minute during the indicated second.	

LogicsManager: Weekly Time Set Point

Utilizing the *LogicsManager* it is possible to establish specific days of the week that functions (i.e. generator exerciser) can be enabled. The weekly time set point is enabled during the indicated day from 0:00:00 hours to 23:59:59 hours.

EN	Monday active			Timer: Weekly time set points Monday: days	YES / NO
DE	Montag aktiv				
CL2	{0}	{1}	{2}	Please enter the days of the weekly workdays.	
1670	✓	✓	✓	Monday <i>YES</i> - The switch point is enabled every Monday	
				<i>NO</i> - The switch point is disabled every Monday	
EN	Tuesday active			Timer: Weekly time set points Tuesday: days	YES / NO
DE	Dienstag aktiv				
CL2	{0}	{1}	{2}	Please enter the days of the weekly workdays.	
1671	✓	✓	✓	Tuesday <i>YES</i> - The switch point is enabled every Tuesday	
				<i>NO</i> - The switch point is disabled every Tuesday	
EN	Wednesday active			Timer: Weekly time set points Wednesday: days	YES / NO
DE	Mittwoch aktiv				
CL2	{0}	{1}	{2}	Please enter the days of the weekly workdays.	
1672	✓	✓	✓	Wednesday <i>YES</i> - The switch point is enabled every Wednesday	
				<i>NO</i> - The switch point is disabled every Wednesday	
EN	Thursday active			Timer: Weekly time set points Thursday: days	YES / NO
DE	Donnerstag aktiv				
CL2	{0}	{1}	{2}	Please enter the days of the weekly workdays.	
1673	✓	✓	✓	Thursday <i>YES</i> - The switch point is enabled every Thursday	
				<i>NO</i> - The switch point is disabled every Thursday	
EN	Friday active			Timer: Weekly time set points Friday: days	YES / NO
DE	Freitag aktiv				
CL2	{0}	{1}	{2}	Please enter the days of the weekly workdays.	
1674	✓	✓	✓	Friday <i>YES</i> - The switch point is enabled every Friday	
				<i>NO</i> - The switch point is disabled every Friday	
EN	Saturday active			Timer: Weekly time set points Saturday: days	YES / NO
DE	Samstag aktiv				
CL2	{0}	{1}	{2}	Please enter the days of the weekly workdays.	
1675	✓	✓	✓	Saturday <i>YES</i> - The switch point is enabled every Saturday	
				<i>NO</i> - The switch point is disabled every Saturday	
EN	Sunday active			Timer: Weekly time set points Sunday: days	YES / NO
DE	Sonntag aktiv				
CL2	{0}	{1}	{2}	Please enter the days of the weekly workdays.	
1676	✓	✓	✓	Sunday <i>YES</i> - The switch point is enabled every Sunday	
				<i>NO</i> - The switch point is disabled every Sunday	

Interfaces



NOTE

Please refer to the Interface Manual 37389 for a detailed description of the interface parameters.

	Device number		
	Gerätenummer		
CL2	{0}	{1}	{2}
1702	✓	✓	✓

Interfaces: Device address

1 to 127

So that this control unit may be positively identified on the CAN bus, the unit address must be set in this parameter. The address may only be represented once on the CAN bus. All other addresses on the CAN bus are calculated on the basis of the address entered in this parameter.

Interfaces: CAN Bus (*FlexCAN*)



NOTE

The CAN bus is a field bus and subject to various disturbances. Therefore, it cannot be guaranteed that every request will be answered. We recommend to repeat a request, which is not answered within reasonable time.

	Protocol		
	Protokoll		
CL2	{0}	{1}	{2}
3155	✓	✓	✓

CAN bus: Protocol

OFF / CANopen / LeoPC

The CAN bus of this unit may be operated with different protocols and Baud rates. This parameter defines the protocol to be utilized. Please note, that all participants on the CAN bus must use the same protocol.

OFFThe CAN bus is disconnected. Values are not sent or received.

CANopenThe CANopen protocol is used. More information may be found in the interface manual 37262 under CANopen.

LeoPCThe CAN CAL protocol is used. More information may be found in the interface manual 37262 under CAN (CAL).

	Baudrate		
	Baudrate		
CL2	{0}	{1}	{2}
3156	✓	✓	✓

CAN bus: Baud rate

20 / 50 / 100 / 125 / 250 / 500 / 800 / 1,000 kBaud

This parameter defines the used Baud rate. Please note, that all participants on the CAN bus must use the same Baud rate.

Interfaces: CAN BUS: CANopen

CANopen Master				YES / NO																					
<hr/>																									
CAN-open Master																									
CL2 9000	{0}	{1}	{2}	YES The DTSC-200 is the CANopen Master. The unit automatically changes into operational mode and transmits Remote Start messages since Broadcast Attached external devices were configured from the unit with SDO messages. The unit sends a SYNC message all 20ms on COB ID 80 Hex. NO The DTSC-200 is a CANopen Slave.																					
✓	✓	✓																							
<hr/>																									
CAN bus: Producer heartbeat time				20 to 65,530 ms																					
<hr/>																									
Independent from the CANopen Master configuration, the unit transmits a heartbeat message with this configured heartbeat cycle time. If the producer heartbeat time is equal 0, the heartbeat will only be sent as response to a remote frame request. The time configured here will be rounded up to the next 20 ms step.																									
<hr/>																									
COB-ID SYNC Message				1 to FFFFFFFF																					
<hr/>																									
This parameter defines whether the unit generates the SYNC message or not.																									
Complies with CANopen specification: object 1005, subindex 0; defines the COB ID of the synchronization object (SYNC). The structure of this object is shown in the following tables:																									
<div><div>UNSIGNED 32 bits 11 bit ID</div><div>bits 11 bit ID</div><div><div>MSB</div><table><tr><td>31</td><td>30</td><td>29</td><td>28-11</td><td>10-0</td></tr><tr><td>X</td><td>0/1</td><td>X</td><td>00000000000000000000</td><td>11 bit identifier</td></tr></table><div>LSB</div></div></div>					31	30	29	28-11	10-0	X	0/1	X	00000000000000000000	11 bit identifier											
31	30	29	28-11	10-0																					
X	0/1	X	00000000000000000000	11 bit identifier																					
<table><tr><td>bit number</td><td>value</td><td>meaning</td></tr><tr><td>31 (MSB)</td><td>X</td><td>N/A</td></tr><tr><td>30</td><td>0</td><td>Unit does not generate SYNC message</td></tr><tr><td></td><td>1</td><td>Unit generates SYNC message</td></tr><tr><td>29</td><td>X</td><td>N/A</td></tr><tr><td>28-11</td><td>0</td><td>always</td></tr><tr><td>10-0 (LSB)</td><td>X</td><td>bits 10-0 of SYNC COB ID</td></tr></table>					bit number	value	meaning	31 (MSB)	X	N/A	30	0	Unit does not generate SYNC message		1	Unit generates SYNC message	29	X	N/A	28-11	0	always	10-0 (LSB)	X	bits 10-0 of SYNC COB ID
bit number	value	meaning																							
31 (MSB)	X	N/A																							
30	0	Unit does not generate SYNC message																							
	1	Unit generates SYNC message																							
29	X	N/A																							
28-11	0	always																							
10-0 (LSB)	X	bits 10-0 of SYNC COB ID																							
<hr/>																									
Max. answer time ext. devices				0.1 to 9.9 s																					
<hr/>																									
Max. Antwortzeit ext. Geräte																									
CL2 9010	{0}	{1}	{2}	The maximum time that an attached external device has to answer an SDO message. If the external device fails to answer before this time expires, an abort message is sent and the SDO message will be sent again. This is only effective, if DTSC-200 CAN open master is enabled.																					
✓	✓	✓																							
<hr/>																									
Time re-init. ext. devices				0 to 9,999 s																					
<hr/>																									
Zeit Re-init. ext- Geräte																									
CL2 9009	{0}	{1}	{2}	An external device will be configured again with SDO messages after the time set for this parameter. If 0 is input in this parameter, the external device will not be configured again with SDO messages This only functions if DTSC-200 CAN open master is enabled.																					
✓	✓	✓																							

Interfaces: CAN BUS: CANopen: Additional Server SDOs

EN	2nd Client->Server COB-ID (rx)	CAN bus: Client->Server COB-ID (rx)	1 to FFFFFFFF
DE	2. Client->Server COB-ID (rx)	In a multi-master application, each Master needs its own identifier (Node ID) from the unit. in order to send remote signals (i.e. acknowledge) to the unit. The additional SDO channel will be made available by configuring this Node ID to a value different than zero. This is the additional CAN ID for the PLC.	
CL2	{0} {1} {2}		
9020	✓ ✓ ✓		
EN	2nd Server->Client COB-ID (tx)	CAN bus: Server-> Client COB-ID (tx)	1 to FFFFFFFF
DE	2. Server->Client COB-ID (tx)	In a multi-master application, each Master needs its own identifier (Node ID) from the unit. in order to receive remote signals (i.e. acknowledge). The additional SDO channel will be made available by configuring this Node ID to a value different than zero. This is the additional CAN ID for the unit.	
CL2	{0} {1} {2}		
9022	✓ ✓ ✓		
EN	3rd Client->Server COB-ID (rx)	CAN bus: Client->Server COB-ID (rx)	1 to FFFFFFFF
DE	3. Client->Server COB-ID (rx)	In a multi-master application, each Master needs its own identifier (Node ID) from the unit. in order to send remote signals (i.e. acknowledge) to the unit. The additional SDO channel will be made available by configuring this Node ID to a value different than zero. This is the additional CAN ID for the PLC.	
CL2	{0} {1} {2}		
9024	✓ ✓ ✓		
EN	3rd Server->Client COB-ID (tx)	CAN bus: Server-> Client COB-ID (tx)	1 to FFFFFFFF
DE	3. Server->Client COB-ID (tx)	In a multi-master application, each Master needs its own identifier (Node ID) from the unit. in order to receive remote signals (i.e. acknowledge). The additional SDO channel will be made available by configuring this Node ID to a value different than zero. This is the additional CAN ID for the unit.	
CL2	{0} {1} {2}		
9026	✓ ✓ ✓		
EN	4th Client->Server COB-ID (rx)	CAN bus: Client->Server COB-ID (rx)	1 to FFFFFFFF
DE	4. Client->Server COB-ID (rx)	In a multi-master application, each Master needs its own identifier (Node ID) from the unit. in order to send remote signals (i.e. acknowledge) to the unit. The additional SDO channel will be made available by configuring this Node ID to a value different than zero. This is the additional CAN ID for the PLC.	
CL2	{0} {1} {2}		
9028	✓ ✓ ✓		
EN	4th Server->Client COB-ID (tx)	CAN bus: Server-> Client COB-ID (tx)	1 to FFFFFFFF
DE	4. Server->Client COB-ID (tx)	In a multi-master application, each Master needs its own identifier (Node ID) from the unit. in order to receive remote signals (i.e. acknowledge). The additional SDO channel will be made available by configuring this Node ID to a value different than zero. This is the additional CAN ID for the unit.	
CL2	{0} {1} {2}		
9030	✓ ✓ ✓		
EN	5th Client->Server COB-ID (rx)	CAN bus: Client->Server COB-ID (rx)	1 to FFFFFFFF
DE	5. Client->Server COB-ID (rx)	In a multi-master application, each Master needs its own identifier (Node ID) from the unit. in order to send remote signals (i.e. acknowledge) to the unit. The additional SDO channel will be made available by configuring this Node ID to a value different than zero. This is the additional CAN ID for the PLC.	
CL2	{0} {1} {2}		
9032	✓ ✓ ✓		
EN	5th Server->Client COB-ID (tx)	CAN bus: Server-> Client COB-ID (tx)	1 to FFFFFFFF
DE	5. Server->Client COB-ID (tx)	In a multi-master application, each Master needs its own identifier (Node ID) from the unit. in order to receive remote signals (i.e. acknowledge). The additional SDO channel will be made available by configuring this Node ID to a value different than zero. This is the additional CAN ID for the unit.	
CL2	{0} {1} {2}		
9034	✓ ✓ ✓		

**NOTE**

The COB IDs must be entered in decimal numbers in LeoPC 1 and in hexadecimal numbers in the unit.
Here are some important conversions:

Hexadecimal value	Decimal value
80h	128
181h	385
201h	513
281h	641
301h	769
381h	897
401h	1025
481h	1153
501h	1281
581h	1409
601h	1537
80000000h	2147483648

Interfaces: CAN BUS: CANopen: Receive PDO (RPDO) {x} ({x} = 1/2)

Figure 3-29 shows the principle of PDO mapping.

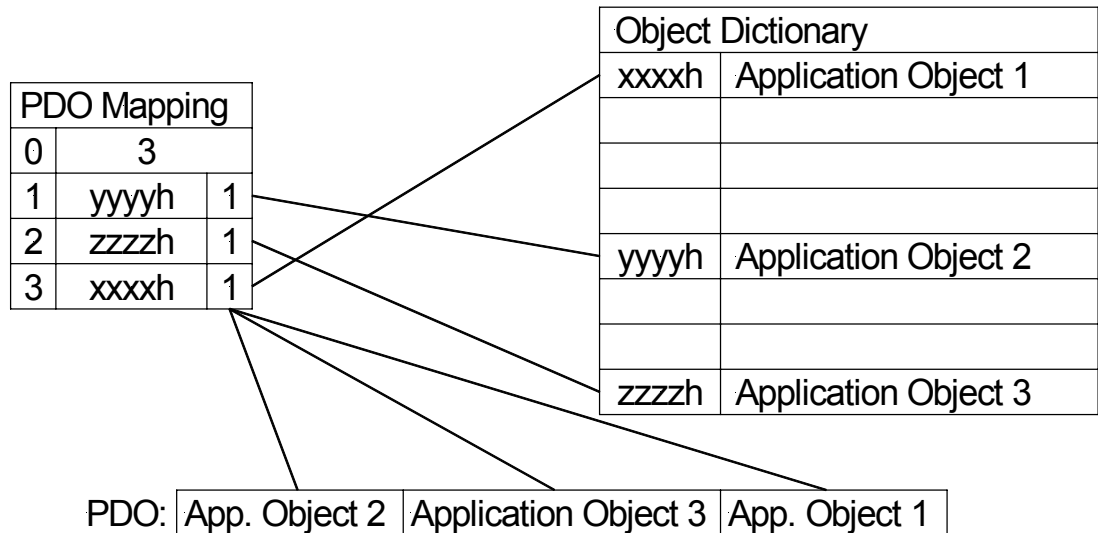


Figure 3-29: Interfaces - Principle of PDO mapping

EN	COB-ID
DE	COB-ID
CL2	{0} {1} {2}
9300	✓ ✓ ✓
9310	

Receive PDO 1/2 - COB-ID**1 to FFFFFFFF**

This parameter contains the communication parameters for the PDOs, the device is able to receive.

Complies with CANopen specification: object 1400 (for RPDO 1 and 1401 for RPDO 2), subindex 1. The structure of this object is shown in the following tables:

UNSIGNED 32 bits	MSB	LSB
11 bit ID	31 30 29 28-11	10-0
	0/1 X X X	0000000000000000 11 bit identifier

bit number	value	meaning
31 (MSB)	0	PDO exists / is valid
	1	PDO does not exist / is not valid
30	X	N/A
29	X	N/A
28-11	0	always
10-0 (LSB)	X	bits 10-0 of COB ID

PDO valid / not valid allows to select, which PDOs are used in the operational state.

**CAUTION**

The COB-IDs have to be configured different, even if one RPDO is configured to "no func."2.

EN	Function
DE	Funktion
CL2	{0} {1} {2}
9050	✓ ✓ ✓
9051	

Function for RPDO 1/2**no func. / 1st IKD / 2nd IKD / Bk 16DIDO / Co 16DIDO**

The unit provides pre-configured CAN bus settings for the connection of different units. The unit to be connected must be selected here.

no func.No external unit is selected for connection. The CAN bus is disabled. Values are not sent or received.

1st IKDThe unit is pre-configured for the connection of a Woodward IKD 1 expansion board.

2nd IKDThe unit is pre-configured for the connection of a second Woodward IKD 1 expansion board.

BK 16 DIDO The unit is pre-configured for the connection of a Phoenix Contact BK 16 DIDO expansion board.

Co 16 DIDO The unit is pre-configured for the connection of a Phoenix Contact Co 16 DIDO expansion board.

The following table shows several possible functional combinations:

PDO1	PDO2	1st IKD	2nd IKD	OFF
1st IKD		NO	YES	YES
2nd IKD		YES	NO	YES
Bk 16DIDO		NO	NO	YES
Co 16DIDO		NO	NO	YES
no func.		YES	YES	YES

Read: If PDO1 is configured as 1. IKD, then PDO2 can only be configured as either 2. IKD or "no func.".

EN	Node-ID of the device
DE	Node-ID des Gerätes
CL2	{0} {1} {2}
9060	✓ ✓ ✓
9061	

Node-ID of the device**1 to 127**

Node-ID of the attached device. The SDO messages were sent on the standard SDO-IDs or the answers were expected.

EN	RPDO-COP-ID ext. device {x}	RPDO-COB-ID ext. device 1	1 to FFFFFFFF
DE	RPDO-COP-ID ext. Gerät {x}		
CL2	{0} {1} {2}	Value to be written in the object 1800h sub index 1h of the external device.	
9070	✓	✓	✓
9072			



CAUTION

COB-IDs already used in other PDOs should be used.

COB-IDs in a CANopen device after loading the standard values:

280h + Node-ID = 640 + Node-ID Object 1801h Subindex 1

380h + Node-ID = 896 + Node-ID Object 1802h Subindex 1

480h + Node-ID = 1152 + Node-ID Object 1803h Subindex 1

The receiving COB-IDs are preallocated:

300h + Node-ID = 768 + Node-ID Object 1401h Subindex 1

400h + Node-ID = 1024 + Node-ID Object 1402h Subindex 1

500h + Node-ID = 1280 + Node-ID Object 1403h Subindex 1.

Problems may be encountered if a COB-ID is assigned multiple times.

Interfaces: CAN Bus: CANopen: Transmit PDO (TPDO) {x} ({x} = 1 to 4)

EN	COB-ID	CAN bus 1: Transmit PDO 1 - COB ID	1 to FFFFFFFF
DE	COB-ID		
CL2	{0} {1} {2}	This parameter contains the communication parameters for the PDOs the unit is able to transmit. The unit transmits data (i.e. visualization data) on the CAN ID configured here.	
9600	✓	✓	✓
9610			
9620			
9630			

Complies with CANopen specification: object 1800 for (TPDO 1, 1801 for TPDO 2, 1802 for TPDO 3, and 1803 for TPDO 4), subindex 1. The structure of this object is shown in the following tables:

UNUNSIGNED 32 bits	bits	MSB			LSB	
		31	30	29	28-11	10-0
11 bit ID	11 bit ID	0/1	X	X	00000000000000000000	11 bit identifier

bit number	value	meaning
31 (MSB)	0	PDO exists / is valid
	1	PDO does not exist / is not valid
30	X	N/A
29	X	N/A
28-11	0	always
10-0 (LSB)	X	bits 10-0 of COB ID

PDO valid / not valid allows to select, which PDOs are used in the operational state.

EN	Transmission type		
DE	Transmission type		
CL2	{0}	{1}	{2}
9602	✓	✓	✓
9612			
9622			
9632			

CAN bus 1: Transmit PDO 1 - Transmission type**0 to 255**

This parameter contains the communication parameters for the PDOs the unit is able to transmit. It defines whether the unit broadcasts all data automatically (value 254 or 255) or only upon request with the configured address of the COB ID SYNC message (parameter 9100).

Complies with CANopen specification: object 1800 (for TPDO 1, 1801 for TPDO 2, 1802 for TPDO 3, and 1803 for TPDO 4), subindex 2. The description of the transmission type is shown in the following table:

transmission type	PDO transmission				
	cyclic	acyclic	synchronous	asynchronous	RTR only
0	will not be sent				
1-240	X		X		
241-251	will not be sent				
252	will not be sent				
253	will not be sent				
254				X	
255				X	

A value between 1 and 240 means that the PDO is transferred synchronously and cyclically. The transmission type indicating the number of SYNC, which are necessary to trigger PDO transmissions. Receive PDOs are always triggered by the following SYNC upon reception of data independent of the transmission types 0 to 240. For TPDOs, transmission type 254 and 255 means, the application event is the event timer.

EN	Event-timer		
DE	Event-timer		
CL2	{0}	{1}	{2}
9604	✓	✓	✓
9614			
9624			
9634			

CAN bus 1: Transmit PDO 1 – Event timer**0 to 65000 ms**

This parameter contains the communication parameters for the PDOs the unit is able to transmit. The broadcast cycle for the transmitted data is configured here. The time configured here will be rounded up to the next 5 ms step.

Complies with CANopen specification: object 1800 (for TPDO 1, 1801 for TPDO 2, 1802 for TPDO 3, and 1803 for TPDO 4), subindex 5

EN	Number of Mapped Objects		
DE	Anzahl der Mapped Objekte		
CL2	{0}	{1}	{2}
9609	✓	✓	✓
9619			
9629			
9639			

CAN bus 1: Transmit PDO 1 - Number of mapped objects**0 to 4**

This parameter contains the mapping for the PDOs the unit is able to transmit. This number is also the number of the application variables, which shall be transmitted with the corresponding PDO.

Complies with CANopen specification: object 1A00 (for TPDO 1, 1A01 for TPDO 2, 1A02 for TPDO 3, and 1A03 for TPDO 4), subindex 0

EN	1. Mapped Object		
DE	1. Mapped Objekt		
CL2	{0}	{1}	{2}
9605	✓	✓	✓
9615			
9625			
9635			

CAN bus 1: Transmit PDO 1 - 1. mapped object**0 to 65535**

This parameter contains the information about the mapped application variables. These entries describe the PDO contents by their index. The sub-index is always 1. The length is determined automatically.

Complies with CANopen specification: object 1A00 (for TPDO 1, 1A01 for TPDO 2, 1A02 for TPDO 3, and 1A03 for TPDO 4), subindex 1

EN	2. Mapped Object		
DE	2. Mapped Objekt		
CL2	{0}	{1}	{2}
9606	✓	✓	✓
9616			
9626			
9636			

CAN bus 1: Transmit PDO 1 - 2. mapped object**0 to 65535**

This parameter contains the information about the mapped application variables. These entries describe the PDO contents by their index. The sub-index is always 1. The length is determined automatically.

Complies with CANopen specification: object 1A00 (for TPDO 1, 1A01 for TPDO 2, 1A02 for TPDO 3, and 1A03 for TPDO 4), subindex 2

EN	3. Mapped Object			CAN bus 1: Transmit PDO 1 - 3. mapped object	0 to 65535
DE	3. Mapped Objekt				
CL2	{0}	{1}	{2}	This parameter contains the information about the mapped application variables. These entries describe the PDO contents by their index. The sub-index is always 1. The length is determined automatically.	
9607	✓	✓	✓		
9617					
9627					
9637					

Complies with CANopen specification: object 1A00 (for TPDO 1, 1A01 for TPDO 2, 1A02 for TPDO 3, and 1A03 for TPDO 4), subindex 3

EN	4. Mapped Object			CAN bus 1: Transmit PDO 1 - 4. mapped object	0 to 65535
DE	4. Mapped Objekt				
CL2	{0}	{1}	{2}	This parameter contains the information about the mapped application variables. These entries describe the PDO contents by their index. The sub-index is always 1. The length is determined automatically.	
9608	✓	✓	✓		
9618					
9628					
9638					

Complies with CANopen specification: object 1A00 (for TPDO 1, 1A01 for TPDO 2, 1A02 for TPDO 3, and 1A03 for TPDO 4), subindex 4



NOTE

CANopen allows to send 8 byte of data with each Transmit PDO. These may be defined separately if no pre-defined data protocol is used.

All data protocol parameters with a parameter ID may be sent as an object with a CANopen Transmit PDO.

In this case, the data length will be taken from the data byte column (refer to the Data Protocols section in the Interface Manual 37389):

- 1,2 UNSIGNED16 or SIGNED16
- 3,4 UNSIGNED16 or SIGNED16
- 5,6 UNSIGNED16 or SIGNED16
- 1,2,3,4 UNSIGNED32 or SIGNED32
- 3,4,5,6 UNSIGNED32 or SIGNED32
- etc.

The object ID is identical with the parameter ID when configuring via front panel or LeoPC 1.

Interfaces: Serial Interface 1 (RS-232)

EN	Baudrate		
DE	Baudrate		
CL2	{0}	{1}	{2}
3163	✓	✓	✓

Serial interface: Baud rate **2.4 / 4.8 / 9.6 / 14.4 / 19.2 / 38.4 / 65 / 115 kBaud**

① A DPC (P/N 5417-557) must be used for connecting the control unit from the service interface to a PC or to another participant.

The serial interface of this unit connects to an RJ45-plug on the side of the housing. This parameter defines the baud rate that communications will be performed. Please note, that all participants on the service interface must use the same Baud rate.

EN	Parity		
DE	Parity		
CL2	{0}	{1}	{2}
3161	✓	✓	✓

Serial interface: Parity **no / even / odd**

The used parity of the service interface is set here.

EN	Stop Bits		
DE	Stop Bits		
CL2	{0}	{1}	{2}
3162	✓	✓	✓

Serial interface: Stop bits **one / two**

The number of stop bits is set here.

Interfaces: Serial Interface 2 (RS-485)

EN	Baudrate		
DE	Baudrate		
CL2	{0}	{1}	{2}
3170	✓	✓	✓

Serial interface 2: Baud rate **2.4 / 4.8 / 9.6 / 14.4 / 19.2 / 38.4 / 56 / 115 kBaud**

This parameter defines the baud rate for communications. Please note, that all participants on the service interface must use the same baud rate.

EN	Parity		
DE	Parity		
CL2	{0}	{1}	{2}
3171	✓	✓	✓

Serial interface 2: Parity **no / even / odd**

The used parity of the service interface is set here.

EN	Stop bits		
DE	Stop Bits		
CL2	{0}	{1}	{2}
3172	✓	✓	✓

Serial interface 2: Stop bits **one / two**

The number of stop bits is set here.

EN	Full-, halfduplex mode		
DE	Voll-, Halbduplex Modus		
CL2	{0}	{1}	{2}
3173	✓	✓	✓

Serial interface 2: Full-/halfduplex mode **Fullduplex / Halfduplex**

Fullduplex ... Fullduplex mode is enabled.
Halfduplex ... Halfduplex mode is enabled.

EN	ModBus Slave ID		
DE	ModBus Slave ID		
CL2	{0}	{1}	{2}
3185	✓	✓	✓

Serial interface: Modbus Slave ID **0 to 255**

The Modbus device address is entered here, which is used to identify the device via Modbus. If 0 is entered here, the Modbus Slave module is disabled.

EN	Modbus Reply delay time		
DE	Modbus Zeitverzöger. der Antwort		
CL2	{0}	{1}	{2}
3186	✓	✓	✓

Serial interface: Reply delay time **0,00 to 1,00 s**

This is the minimum delay time between a request from the Modbus master and the sent response of the slave. This time is also required if an external interface converter to RS-485 is used for example. Please note that you also need the DPC (refer to page 8) in this case.

System



System: Configure Display Backlight

EN	Configure display backlight			Display backlight	ON / OFF / Auto / Key actv.
DE	Konfig. Display Beleuchtung				
CL2	{0}	{1}	{2}	This parameter determines the behavior of the display backlight. The following options are available: ON The display backlight is always enabled. OFF The display backlight is always disabled. Auto The display backlight will be disabled if no voltage is detected anymore at both connected sources. Key actv The display backlight will be disabled if no softkey has been pressed for the time configured in parameter 4557. It will be enabled again after any softkey of the unit has been pressed.	
4556	✓	✓	✓		
EN	Time until backlight shutdown			Time until backlight shutdown	1 to 999 s
DE	Zeit bis Abschaltung				
CL2	{0}	{1}	{2}	ⓘ This parameter is only visible if parameter 4556 has been configured to "Key actv.".	
4557	✓	✓	✓		
				If no softkey has been pressed for the time configured here, the display backlight will be disabled.	

System: Configure Daylight Saving Time

It is possible to configure the real-time clock for an automatic change to daylight saving time. Start and end date/time of the daylight saving time period have to be entered for this.

Example: If daylight saving time starts at 2:00 am on the 2nd Sunday in March and ends at 2:00 am on the 1st Sunday in November, the unit has to be configured like shown in Table 3-14 to enable an automatic change to daylight saving time and back to standard time.

ID	Parameter	Setting
4591	Daylight saving time	ON
4593	DST begin month	3
4592	DST begin sunday	2
4594	DST begin time	2
4596	DST end month	11
4595	DST end sunday	1
4597	DST end time	2

Table 3-14: Daylight saving time - configuration example

EN	Daylight saving time	Daylight saving time	ON / OFF
DE	Sommer-Winterzeit Erkennung		
CL2	{0} {1} {2}	This parameter enables or disables daylight saving time.	
4591	✓ ✓ ✓	ON Daylight saving time is performed according to the following parameters.	
		OFF Daylight saving time is disabled.	
EN	DST begin month	Daylight saving time start month	1 to 12
DE	Monat für Sommerzeitbeginn		
CL2	{0} {1} {2}	Daylight saving time starts in the month configured here.	
4593	✓ ✓ ✓		
EN	DST begin Sunday	Daylight saving time start Sunday	1 to 4
DE	Sonntag für Sommerzeitbeginn		
CL2	{0} {1} {2}	Daylight saving time starts on the Sunday configured here of the month configured in parameter 4593.	
4592	✓ ✓ ✓		
EN	DST begin time	Daylight saving time start time	0 to 23 h
DE	Uhrzeit für Sommerzeitbeginn		
CL2	{0} {1} {2}	Daylight saving time starts at this time on the Sunday configured in parameter 4592.	
4594	✓ ✓ ✓		
EN	DST end month	Daylight saving time end month	1 to 12
DE	Monat für Sommerzeitende		
CL2	{0} {1} {2}	Daylight saving time ends in the month configured here.	
4596	✓ ✓ ✓		
EN	DST end sunday	Daylight saving time end Sunday	1 to 4
DE	Sonntag für Sommerzeitende		
CL2	{0} {1} {2}	Daylight saving time ends on the Sunday configured here of the month configured in parameter 4596.	
4595	✓ ✓ ✓		
EN	DST end time	Daylight saving time end time	0 to 23 h
DE	Uhrzeit für Sommerzeitende		
CL2	{0} {1} {2}	Daylight saving time ends at this time on the Sunday configured in parameter 4595.	
4597	✓ ✓ ✓		

System: Password System

Refer to the Password section on page 14 for a detailed description of the password system.

EN	Code level display			Password system: Code level via display	Info
DE	Codeebene Display				
CL2 10405	{0} ✓	{1} ✓	{2} ✓	This value displays the code level, which is currently enabled for access via the front panel display.	

EN	Code level CAN port			Password system: Code level via CAN-Bus	Info
DE	Codeebene CAN Schnittstelle				
CL2 10407	{0} ✓	{1} ✓	{2} ✓	This value displays the code level, which is currently enabled for access via the CAN interface.	

EN	Code level serial port/DPC			Password system: Code level via serial RS-232 (DPC) interface	Info
DE	Codeebene RS232/DPC				
CL2 10406	{0} ✓	{1} ✓	{2} ✓	This value displays the code level, which is currently enabled for access via RS-232 serial interface #1.	

EN	Supercommissioning level code			Password system: Password "Supercommissioning" (CL5)	0000 to 9999
DE	Code Supercommissioning Ebene				
CL5 10411	{0} ✓	{1} ✓	{2} ✓	The password for the code level "Supercommissioning" is defined in this parameter. Refer to the Password section on page 14 for default values.	

EN	Temp. supercomm. level code			Password system: Password "Temporary Supercommissioning" (CL4)	0000 to 9999
DE	Code temp. Supercomm. Ebene				
CL5 10412	{0} ✓	{1} ✓	{2} ✓	The algorithm for calculating the password for the code level "Temporary Supercommissioning" is defined in this parameter.	

EN	Commissioning level code			Password system: Password "Commission" (CL3)	0000 to 9999
DE	Code Inbetriebnahme Ebene				
CL3 10413	{0} ✓	{1} ✓	{2} ✓	The password for the code level "Commission" is defined in this parameter. Refer to the Password section on page 14 for default values.	

EN	Temp. commissioning level code			Password system: Password "Temporary Commission" (CL2)	0000 to 9999
DE	Code temp. Inbetriebn. Ebene				
CL3 10414	{0} ✓	{1} ✓	{2} ✓	The algorithm for calculating the password for the code level "Temporary Commissioning" is defined in this parameter.	

EN	Basic level code			Password system: Password "Service Level" (CL1)	0000 to 9999
DE	Code Serviceebene				
CL1 10415	{0} ✓	{1} ✓	{2} ✓	The password for the code level "Service" is defined in this parameter. Refer to the Password section on page 14 for default values.	

EN	Password			Password system: Entry via front panel	0000 to 9999
DE	Passwort				
CS0 10416	{0} ✓	{1} ✓	{2} ✓	To configure the control via the front panel bus enter the password.	

EN	Password CAN			Password system: Entry via CAN bus	0000 to 9999
DE	Passwort CAN				
CS0 10402	{0} ✓	{1} ✓	{2} ✓	To configure the control via CAN bus enter "password CAN".	

EN	Password DPC			Password system: Entry via DPC	0000 to 9999
DE	Passwort RS232/DPC				
CS0 10401	{0} ✓	{1} ✓	{2} ✓	To configure the control via DPC please enter "password DPC".	

EN	Factory Settings		
DE	Werkseinstellung		
CL2 1703	{0} ✓	{1} ✓	{2} ✓

Factory settings: Factory settings CAN**YES / NO**

YESThe resetting of the factory settings via CAN bus will be enabled.
NOThe resetting of the factory settings via CAN bus will not be enabled.

EN	Factory Settings DPC/RS232		
DE	Werkseinstellung DPC/RS232		
L 1704	{0} ✓	{1} ✓	{2} ✓

Factory settings: Factory settings DPC/RS-232**YES / NO**

YESThe resetting of the factory settings via DPC/RS-232 will be enabled.
NOThe resetting of the factory settings via DPC/RS-232 will not be enabled.

EN	Factory Settings CAN		
DE	Werkseinstellung CAN		
L 1705	{0} ✓	{1} ✓	{2} ✓

Factory settings: Factory settings CAN**YES / NO**

YESThe resetting of the factory settings via CAN bus will be enabled.
NOThe resetting of the factory settings via CAN bus will not be enabled.

EN	Set default values		
DE	Standardwerte		
CL2 1701	{0} ✓	{1} ✓	{2} ✓

Factory settings: Set default values**YES / NO**

YESThe default values, which have been enabled with Parameter 1703, 1704 or Parameter 1705, will be loaded by the unit.
NOThe factory settings will not be loaded by the unit.

EN	Start Bootloader		
DE	Bootloader starten		
CL3 10500	{0} ✓	{1} ✓	{2} ✓

Factory settings: Start Bootloader**00000**

This function may be used to start the Bootloader. In order to do this, the correct code must be entered here while the unit is in the code level required for this.

**CAUTION**

The Start Bootloader function is used to flash the software and may only be used by authorized Woodward technicians!

**NOTE**

If the DTSC-200 parameters are read out via CAN / DPC and stored as standard values, all parameters behind Parameter 1701 (Set default values) will not be overwritten when writing back the standard value file via CAN / DPC.

This prevents an unintentional start of the Bootloader or an overwriting of the time or date in the unit with a wrong (old) value. The following version information is only for info anyway and cannot be overwritten.

System: Real-Time Clock Set



This screen shows the current date and time. The clock is implemented as real time clock. In case of a voltage supply failure an internal battery guarantees that the information is not lost. The data stand for:

XX:YY:ZZ..... hour:minute:second.

AAAA-BBB-CC Year-month-day.

System: Adjust Clock

EN	Hour		
DE	Stunden		
CL2	{0}	{1}	{2}
1762	✓	✓	✓

Adjust clock: hour

0 to 23 h

The current hour of the clock time is set here. Example:

0..... 0th hour of the day.

23..... 23th hour of the day.

EN	Minute		
DE	Minuten		
CL2	{0}	{1}	{2}
1761	✓	✓	✓

Adjust clock: minute

0 to 59 min

The current minute of the clock time is set here. Example:

0..... 0th minute of the hour.

59..... 59th minute of the hour.

EN	Second		
DE	Sekunden		
CL2	{0}	{1}	{2}
1760	✓	✓	✓

Adjust clock: second

0 to 59 s

The current second of the clock time is set here. Example:

0..... 0th second of the minute.

59..... 59th second of the minute.

System: Adjust Date

EN	Day		
DE	Tag		
CL2	{0}	{1}	{2}
1763	✓	✓	✓

Adjust clock: day

1 to 31

The current day of the date is set here. Example:

1..... 1st day of the month.

31..... 31st day of the month.

EN	Month		
DE	Monat		
CL2	{0}	{1}	{2}
1764	✓	✓	✓

Adjust clock: month

1 to 12

The current month of the date is set here. Example:

1..... 1st month of the year.

12..... 12th month of the year.

EN	Year		
DE	Jahr		
CL2	{0}	{1}	{2}
1765	✓	✓	✓

Adjust clock: year

0 to 99

The current year of the date is set here. Example:

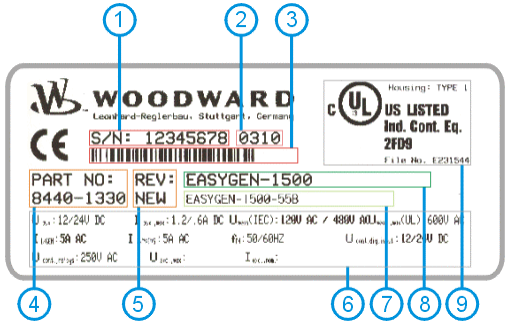
0..... Year 2000.

99..... Year 2099.

System: Versions

The parameters in this section are informational only and cannot be modified.

The control unit may be identified from the numbers located on the unit and in the software. The most important technical information is located on the unit data plate. Technical data can be located in manual 37385.



- | | | |
|---|---------|----------------------------|
| 1 | S/N | serial number (numeric) |
| 2 | S/N | manufactured date (YYMM) |
| 3 | S/N | serial number (as Barcode) |
| 4 | P/N | part number |
| 5 | REV | part number revision |
| 6 | Details | technical data |
| 7 | Type | description (long) |
| 8 | Type | Description (short) |
| 9 | UL | UL sign |

EN	Serial number			Version: Serial number (S/N)	info
	Seriennummer				
900				The serial number (S/N) is utilized to identify individual control units. The number can also be found on the data plate (items #1 & #3).	
EN	Boot item number			Version: Part number of the firmware (P/N)	info
DE	Boot Artikelnummer				
950				The part number (P/N) is the firmware in the control unit.	
EN	Boot revision			Version: Revision of the item number of the firmware (REV)	info
DE	Boot Revision				
960				The revision number (REV) is the revision of the control unit firmware.	
EN	Boot version			Version: Version of the firmware	info
DE	Boot Version				
965				This number (Vx.xxxx) represents the version of the control unit firmware.	
EN	Program item number			Version: Item number of the application software (P/N)	info
DE	Programm Artikelnummer				
930				The part number (P/N) is the application software running the control unit.	
EN	Program revision			Version: Revision of the item number of the software (REV)	info
DE	Programm Revision				
940				The revision number (REV) is the revision of the application software running the control unit.	
EN	Program version			Version: Version of the application software	info
DE	Programm Version				
945				This number (Vx.xxxx) represents the version of the application software running the control unit.	

Appendix A.

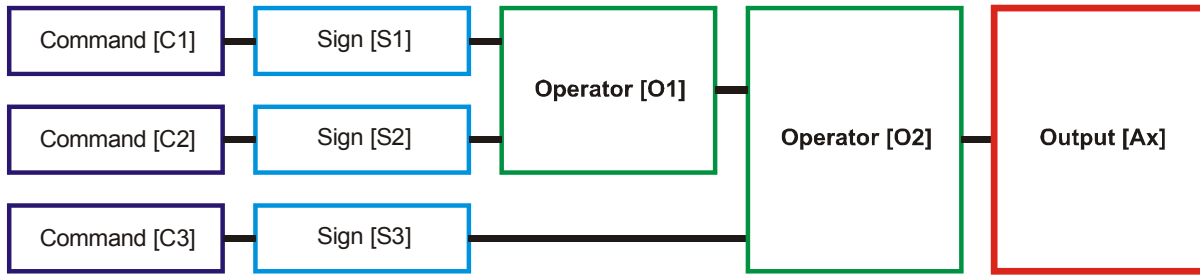
LogicsManager

The *LogicsManager* is used to customize the sequence of events in the control **unit** such as the start command of the engine or the operation of control unit relay outputs. For example, the start routine may be programmed so that it requires the closing of a discrete input or a preset time of day. Two independent time delays are provided for the configured action to take place and be reset. The following table shows the function of each relay in each of the application modes.

Starting the engine can be carried out externally via a discrete input. With it the *LogicsManager* is used whose conditions and programming is defined as follows.

Table 3-10 on page 78 shows the assignment of different functions to various discrete outputs.

Structure and description of the *LogicsManager*

Figure 3-30: *LogicsManager* - function overview

- **Command (variable)** - A list of over 100 parameters and functions is provided for the command inputs. Examples of the parameters that may be configured into these commands are Source 1 undervoltage, Start fail, and Cool down. These command variables are used to control the output function or relay. Refer to Logical Command Variables starting on page 104 for a complete list of all command variables.
- **Sign** - The sign field can be used to invert the state of the command or to fix its output to a logical true or false if the command is not needed. Setting the sign to the NOT state changes the output of the command variable from true to false or vice versa.
- **Operator** - A logical device such as AND or OR.
- **(Logical) output** - The action or control sequence that occurs when all parameters set into the *LogicsManager* are met.

[Cx] - Command {x}	[Sx] - Sign {x}	[Ox] - Operator {x}	[Ax] - Output {x}
The description and the tables of all values, flags, and internal functions that are able to combine via the <i>LogicsManager</i> can be found in the Logical Command Variables section starting on page 104.	Value {[Cx]} The value [Cx] is passed 1:1. ——	AND Logical AND	The description and the tables of all logical outputs, flags, and functions that are able to combine via the <i>LogicsManager</i> can be found in the Logical Outputs section starting on page 102.
	NOT VALUE {[Cx]} The opposite of the value [Cx] is passed. — >—	NAND Logical negated AND	
	0 [always "0"] The value [Cx] is ignored and this logic path will always be FALSE. 0——	OR Logical OR	
	1 [always "1"] The value [Cx] is ignored and this logic path will always be TRUE. 1——	NOR Logical negated OR	
		XOR Exclusive OR	
		NXOR Exclusive negated OR (See Table 3-16 for symbols)	

Table 3-15: *LogicsManager* - command overview

NOTE

A logical output may either be delayed when switching on or switching off. The time starts when all logical functions of the operation have been met.

Configuration of the chain of commands

Using the values specified in the above table, the chain of commands of the *LogicsManager* (for example: operating the relays, setting the flags, specification of the automatic functions) is configured as follows:

$$[Ax] = (([C1] \& [S1]) \& [O1] \& ([C2] \& [S2])) \& [O2] \& ([C3] \& [S3])$$

Programming example for the *LogicsManager*:

Flag 8 shall become TRUE, whenever "Setpoint 1" is TRUE "AND" "Setpoint 2" is "NOT" TRUE "AND" the "Active week day" is TRUE ⇨

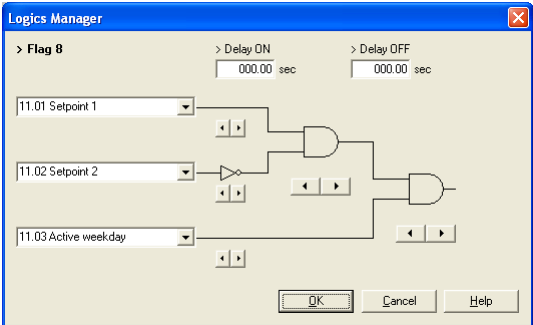


Figure 3-31: *LogicsManager* - display in LeoPC

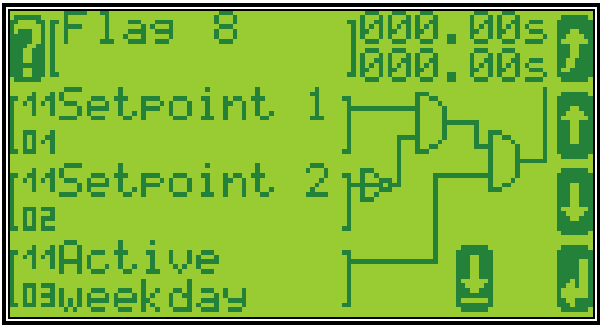


Figure 3-32: *LogicsManager* - display in LCD

Logical Symbols



The following symbols are used for the graphical programming of the *LogicsManager*.

	AND			OR			NAND			NOR			NXOR			XOR		
DTSC																		
DIN 40 700																		
LeoPC1 ASA US MIL																		
IEC617-12																		
Truth table	x1	x2	y	x1	x2	y	x1	x2	y	x1	x2	y	x1	x2	y	x1	x2	y
	0	0	0	0	0	0	0	0	1	0	0	1	0	0	1	0	0	0
	0	1	0	0	1	1	0	1	1	0	1	0	0	1	0	0	1	1
	1	0	0	1	0	1	1	0	1	1	0	0	1	0	0	1	0	1
	1	1	1	1	1	1	1	1	0	1	1	0	1	1	1	1	1	0

Table 3-16: *LogicsManager* - logical symbols

Logical Outputs



The logical outputs or combinations may be grouped into three categories:

- internal logical flags
- Internal functions
- relay outputs



NOTE

The numbers of the logical outputs in the third column may again be used as input variable for other outputs in the [LogicsManager](#).

Logical Outputs: Internal Flags

8 internal logical flags may be programmed to activate/deactivate functions. This permits more than 3 commands to be included in a logical function. They may be used like "auxiliary flags".

Name	Function	Number
Flag 1	Internal flag 1	00.01
Flag 2	Internal flag 2	00.02
Flag 3	Internal flag 3	00.03
Flag 4	Internal flag 4	00.04
Flag 5	Internal flag 5	00.05
Flag 6	Internal flag 6	00.06
Flag 7	Internal flag 7	00.07
Flag 8	Internal flag 8	00.08

Logical Outputs: Internal functions

The following logical functions may be used to activate/deactivate functions.

Name	Function	Number
External acknowledge	The alarm acknowledgement is performed from an external source (refer to parameter 12490 on page 49)	00.15
Operation mode AUTO	Activation of the AUTOMATIC operating mode (always TRUE)	00.16

Logical Outputs: Relay Outputs

All relays may be controlled directly by the *LogicsManager* depending on the respective application mode.

Name	Function	Number
Relay 1	If this logical output becomes true, the relay output 1 will be activated	13.01
Relay 2	If this logical output becomes true, the relay output 2 will be activated	13.02
Relay 3	If this logical output becomes true, the relay output 3 will be activated	13.03
Relay 4	If this logical output becomes true, the relay output 4 will be activated	13.04
Relay 5	If this logical output becomes true, the relay output 5 will be activated	13.05
Relay 6	If this logical output becomes true, the relay output 6 will be activated	13.06
Relay 7	If this logical output becomes true, the relay output 7 will be activated	13.07
Relay 8	If this logical output becomes true, the relay output 8 will be activated	13.08
Relay 9	If this logical output becomes true, the relay output 9 will be activated	13.09
External DO 1	If this logical output becomes true, the external relay output 1 will be activated	14.01
External DO 2	If this logical output becomes true, the external relay output 2 will be activated	14.02
External DO 3	If this logical output becomes true, the external relay output 3 will be activated	14.03
External DO 4	If this logical output becomes true, the external relay output 4 will be activated	14.04
External DO 5	If this logical output becomes true, the external relay output 5 will be activated	14.05
External DO 6	If this logical output becomes true, the external relay output 6 will be activated	14.06
External DO 7	If this logical output becomes true, the external relay output 7 will be activated	14.07
External DO 8	If this logical output becomes true, the external relay output 8 will be activated	14.08
External DO 9	If this logical output becomes true, the external relay output 9 will be activated	14.09
External DO 10	If this logical output becomes true, the external relay output 10 will be activated	14.10
External DO 11	If this logical output becomes true, the external relay output 11 will be activated	14.11
External DO 12	If this logical output becomes true, the external relay output 12 will be activated	14.12
External DO 13	If this logical output becomes true, the external relay output 13 will be activated	14.13
External DO 14	If this logical output becomes true, the external relay output 14 will be activated	14.14
External DO 15	If this logical output becomes true, the external relay output 15 will be activated	14.15
External DO 16	If this logical output becomes true, the external relay output 16 will be activated	14.16

Logical Command Variables



The logical command variables are grouped into 14 categories:

- [00.00] Internal flags
- [01.00] Alarm classes
- [03.00] Engine control
- [04.00] Operating status
- [05.00] Alarms of the engine
- [08.00] Alarms of the system
- [09.00] Discrete inputs
- [11.00] Time functions
- [12.00] External discrete inputs
- [13.00] Status of the internal relay outputs
- [14.00] Status of the external relay outputs
- [19.00] ATS status flags
- [20.00] ATS status flags

Logical Command Variables: [00.00] - Internal Flags

Internal flag, Logic command variables 00.01-00.20

Internal Flags are the result of the output of the logic ladders from Flag 1 to 8. Flags are internal logic that can be sent to other flags or Command variables.

No.	Name	Function	Note
00.01	Flag 1	Internal flag 1	Internal calculation; descr. page 102
00.02	Flag 2	Internal flag 2	Internal calculation; descr. page 102
00.03	Flag 3	Internal flag 3	Internal calculation; descr. page 102
00.04	Flag 4	Internal flag 4	Internal calculation; descr. page 102
00.05	Flag 5	Internal flag 5	Internal calculation; descr. page 102
00.06	Flag 6	Internal flag 6	Internal calculation; descr. page 102
00.07	Flag 7	Internal flag 7	Internal calculation; descr. page 102
00.08	Flag 8	Internal flag 8	Internal calculation; descr. page 102
00.09	-	-	not used
00.10	-	-	not used
00.11	-	-	not used
00.12	-	-	not used
00.13	-	-	not used
00.14	-	-	not used
00.15	External acknowledge	The alarm acknowledgement is performed from an external source	Internal calculation; descr. page 49
00.16	Operation mode AUTO	Activation of the AUTOMATIC operating mode	always TRUE
00.18	-	-	not used
00.19	-	-	not used
00.20	-	-	not used

Logical Command Variables: [01.00] - Alarm Classes

Alarm class commands, Logic command variables 01.01-01.10

Alarm classes may be configured as command variables for all logical outputs in the *LogicsManager*.

Number	Name / Function	Note
-	-	not used
-	-	not used
-	-	not used
-	-	not used
-	-	not used
-	-	not used
-	-	not used
-	-	not used
-	-	not used
01.10	Centralized alarm	TRUE as long as at least one of the alarm classes B/C/D/E/F is active

Logical Command Variables: [03.00] - Engine Control

Engine control commands, Logic command variables 03.01-03.14

These variables may be used as command variable in a logical output to set parameters for customized operations.

Number	Name / Function	Note
03.01	-	not used
03.02	-	not used
03.03	-	not used
03.04	-	not used
03.05	Horn (active)	TRUE if alarm class B to F is activated until the time until horn reset is expired or it is acknowledged for the first time.
03.06	-	not used
03.07	-	not used
03.08	-	not used
03.09	-	not used
03.10	-	not used
03.11	-	not used
03.12	-	not used
03.13	-	not used
03.14	-	not used
03.15	-	not used
03.16	-	not used
03.17	-	not used
03.18	-	not used
03.19	-	not used
03.20	-	not used

Logical Command Variables: [04.00] - Operating Status

Operating status commands, 4.01-04.15

These operating statuses may be used as command variable in a logical output to set parameters for customized operations.

No.	Name	Function	Note
04.01	Auto mode	AUTOMATIC operating mode active	
04.02	-	-	not used
04.03	Manual mode	MANUAL operating mode active	
04.04	Lamp test	A lamp test is being performed	TRUE if the lamp test is active
04.05	Acknowledge	"Acknowledge" push button has been pressed or an external acknowledgment via <i>LogicsManager</i>	Note: this condition is TRUE for approx. 40 ms and must be extended utilizing a delay time
04.06	-	-	not used
04.07	-	-	not used
04.08	-	-	not used
04.09	-	-	not used
04.10	-	-	not used
04.11	-	-	not used
04.12	-	-	not used
04.13	-	-	not used
04.14	Remote acknowledge	Request over remote control to acknowledge	TRUE if the acknowledgement bit is set
04.15	-	-	not used
04.16	-	-	not used
04.17	-	-	not used
04.18	-	-	not used
04.19	-	-	not used
04.20	-	-	not used

Logical Command Variables: [06.00] - Alarms of the Load

Load alarm status commands, 06.01-06.15

These engine alarms may be used as command variable in a logical output to set parameters for customized operations.

Number	Name / Function	Note
06.01	-	not used
06.02	-	not used
06.03	-	not used
06.04	-	not used
06.05	-	not used
06.06	-	not used
06.07	-	not used
06.08	-	not used
06.09	Overcurrent 1	
06.10	Overcurrent 2	
06.11	Overcurrent 3	
06.12	-	not used
06.13	-	not used
06.14	Gen. Overload 1	
06.15	Gen. Overload 2	
06.16	-	not used
06.17	-	not used
06.18	-	not used
06.19	-	not used
06.20	-	not used

Logical Command Variables: [08.00] - Alarms of the System

System alarms status commands, 08.01-08.10

These system alarms may be used as command variable in a logical output n to set parameters for customized operations.

Number	Function	Note
08.01	Battery overvoltage (limit) 1	TRUE = limit value reached FALSE = alarm acknowledged
08.02	Battery overvoltage (limit) 2	
08.03	Battery undervoltage (limit) 1	
08.04	Battery undervoltage (limit) 2	
08.05	-	
08.06	-	
08.07	-	
08.08	-	
08.09	CANopen fault	
08.10	-	not used
08.11	-	not used
08.12	-	not used
08.13	-	not used
08.14	-	not used
08.15	-	not used
08.16	-	not used
08.17	-	not used
08.18	-	not used
08.19	-	not used
08.20	-	not used

Logical Command Variables: [09.00] - Discrete Inputs

Control discrete input commands, 09.01-09.08

The discrete inputs may be used as command variable in a logical output to set parameters for customized operations.

Number	Function	Note
09.01	DI 1 (Discrete input [D1])	TRUE = logical "1" (delay times and NO/NC parameters are ignored) FALSE = logical "0" (alarm has been acknowledged or immediately after TRUE condition is not present anymore, if Control is configured as alarm class)
09.02	DI 2 (Discrete input [D2])	
09.03	DI 3 (Discrete input [D3])	
09.04	DI 4 (Discrete input [D4])	
09.05	DI 5 (Discrete input [D5])	
09.06	DI 6 (Discrete input [D6])	
09.07	DI 7 (Discrete input [D7])	
09.08	DI 8 (Discrete input [D8])	
09.09	DI 9 (Discrete input [D9])	
09.10	DI 10 (Discrete input [D10])	
09.11	DI 11 (Discrete input [D11])	
09.12	DI 12 (Discrete input [D12])	
09.13	-	not used
09.14	-	not used
09.15	-	not used
09.16	-	not used
09.17	-	not used
09.18	-	not used
09.19	-	not used
09.20	-	not used

Logical Command Variables: [11.00] - Time Functions

Time function commands, 11.01-11.10

Time functions may be used as command variable in a logical output.

Number	Name / Function	Note
11.01	Set point 1 (exceeded)	see page 82
11.02	Set point 2 (exceeded)	see page 82
11.03	Active weekday (equal to setting)	see page 82
11.04	Active day (equal to setting)	see page 82
11.05	Active hour (equal to setting)	see page 82
11.06	Active minute (equal to setting)	see page 82
11.07	Active second (equal to setting)	see page 82
11.08	-	not used
11.09	-	not used
11.10	-	not used
11.11	-	not used
11.12	-	not used
11.13	-	not used
11.14	-	not used
11.15	-	not used
11.16	-	not used
11.17	-	not used
11.18	-	not used
11.19	-	not used
11.20	-	not used

Logical Command Variables: [12.00] - External Discrete Inputs (Expansion Board)

External discrete input commands, 12.01-12.16

Additional discrete inputs from an expansion board (i.e. IKD 1 extension board) may be used as command variable in a logical output.

Number	Name / Function	Note
12.01	External discrete input 1 [D.E01]	TRUE = logical "1" (delay times and NO/NC parameters are ignored) FALSE = logical "0" (alarm has been acknowledged, or immediately after TRUE condition is not present anymore, if Control is configured as alarm class)
12.02	External discrete input 2 [D.E02]	
12.03	External discrete input 3 [D.E03]	
12.04	External discrete input 4 [D.E04]	
12.05	External discrete input 5 [D.E05]	
12.06	External discrete input 6 [D.E06]	
12.07	External discrete input 7 [D.E07]	
12.08	External discrete input 8 [D.E08]	
12.09	External discrete input 9 [D.E09]	
12.10	External discrete input 10 [D.E10]	
12.11	External discrete input 11 [D.E11]	
12.12	External discrete input 12 [D.E12]	
12.13	External discrete input 13 [D.E13]	
12.14	External discrete input 14 [D.E14]	
12.15	External discrete input 15 [D.E15]	
12.16	External discrete input 16 [D.E16]	
12.17	-	not used
12.18	-	not used
12.19	-	not used
12.20	-	not used

Logical Command Variables: [13.00] - Status Of The Internal Relay Outputs

Discrete output commands, 13.01-13.08

The discrete outputs may be used as command variable in a logical output.

Number	Name / Function	Note
13.01	Digital output DO1 [R01]	TRUE = logical "1" (this condition indicates the logical status of the internal relays) FALSE = logical "0" (this condition indicates the logical status of the internal relays)
13.02	Digital output DO2 [R02]	
13.03	Digital output DO3 [R03]	
13.04	Digital output DO4 [R04]	
13.05	Digital output DO5 [R05]	
13.06	Digital output DO6 [R06]	
13.07	Digital output DO7 [R07]	
13.08	Digital output DO8 [R08]	
13.09	Digital output DO9 [R09]	
13.10	-	not used
13.11	-	not used
13.12	-	not used
13.13	-	not used
13.14	-	not used
13.15	-	not used
13.16	-	not used
13.17	-	not used
13.18	-	not used
13.19	-	not used
13.20	-	not used

Logical Command Variables: [14.00] - Status Of The External Relay Outputs

Discrete output commands, 14.01-14.16

The external discrete outputs may be used as command variable in a logical output.

Number	Name / Function	Note
14.01	External digital output DO1 [R01]	TRUE = logical "1" (this condition indicates the logical status of the relays, which are connected via external expansion boards) FALSE = logical "0" (this condition indicates the logical status of the relays, which are connected via external expansion boards)
14.02	External digital output DO2 [R02]	
14.03	External digital output DO3 [R03]	
14.04	External digital output DO4 [R04]	
14.05	External digital output DO5 [R05]	
14.06	External digital output DO6 [R06]	
14.07	External digital output DO7 [R07]	
14.08	External digital output DO8 [R08]	
14.09	External digital output DO9 [R09]	
14.10	External digital output DO10 [R10]	
14.11	External digital output DO11 [R11]	
14.12	External digital output DO12 [R12]	
14.13	External digital output DO13 [R13]	
14.14	External digital output DO14 [R14]	
14.15	External digital output DO15 [R15]	
14.16	External digital output DO16 [R16]	
14.17	-	not used
14.18	-	not used
14.19	-	not used
14.20	-	not used

Logical Command Variables: [19.00] - ATS Status Flags

ATS status flags, 19.01-19.20

The external discrete outputs may be used as command variable in a logical output.

No.	Name / Function	Note
19.01	Source 1 OK (voltage and frequency are in range)	
19.02	Source 1 voltage OK (in range)	
19.03	Source 1 overvoltage ("fail" level exceeded)	
19.04	Source 1 undervoltage ("fail" level exceeded)	
19.05	Source 1 frequency OK (in range)	
19.06	Source 1 overfrequency ("fail" level exceeded)	
19.07	Source 1 underfrequency ("fail" level exceeded)	
19.08	Source 1 voltage imbalance ("fail" level exceeded)	
19.09	Source 1 rotation (field =) CCW	
19.10	Source 1 rotation (field =) CW	
19.11	Source 2 OK (voltage and frequency are in range)	
19.12	Source 2 voltage OK (in range)	
19.13	Source 2 overvoltage ("fail" level exceeded)	
19.14	Source 2 undervoltage ("fail" level exceeded)	
19.15	Source 2 frequency OK (in range)	
19.16	Source 2 overfrequency ("fail" level exceeded)	
19.17	Source 2 underfrequency ("fail" level exceeded)	
19.18	Source 2 voltage imbalance ("fail" level exceeded)	
19.19	Source 2 rotation (field =) CCW	
19.20	Source 2 rotation (field =) CW	

Logical Command Variables: [20.00] - ATS Status Flags

ATS status flags, 20.01-20.20

The external discrete outputs may be used as command variable in a logical output.

No.	Name / Function	Note
20.01	Status Flag: Elevator Pre Signal (is active)	
20.02	Status Flag: Motor Load Disconnect (signal is active)	
20.03	Status Flag: Load Test (is) active	
20.04	Status Flag: No Load Test (is) active	
20.05	Status Flag: S1 start signal	
20.06	Status Flag: S2 start signal	
20.07	Command: Close to S1	
20.08	Command: Open from S1	
20.09	Command: Close to S2	
20.10	Command: Open from S2	
20.11	Status Flag: Load shed (is active)	
20.12	Status Flag: Shunt trip enable (is active)	
20.13	Status Flag: S1 closed	TRUE if S1 is closed and S2 is open
20.14	Status Flag: S2 closed	TRUE if S2 is closed and S1 is open
20.15	Status Flag: S1 and S2 open	
20.16	Status Flag: S1 and S2 closed	
20.17	Status Flag: S1 is stabling (at the moment)	
20.18	Status Flag: S2 is stabling (at the moment)	
20.19	-	not used
20.20	-	not used

Logical Command Variables: [21.00] - ATS Alarms

ATS alarms, 21.01-21.20

The external discrete outputs may be used as command variable in a logical output.

No.	Name / Function	Note
21.01	Engine Alarm: Start fail S1	
21.02	Engine Alarm: Start fail S2	
21.03	Engine Alarm: Unintended Stop S1	
21.04	Engine Alarm: Unintended Stop S2	
21.05	Alarm: S1 phase rotation mismatch (failure present)	
21.06	Alarm: S2 phase rotation mismatch (failure present)	
21.07	Switch alarm: Fail to open (from switch position) S1	
21.08	Switch alarm: Fail to open (from switch position) S2	
21.09	Switch alarm: Fail to close (to switch position) S1	
21.10	Switch alarm: Fail to close (to switch position) S2	
21.11	Switch alarm: Mechanical fail (not plausible limit switch feedbacks have been detected by the DTSC-200)	
21.12	In-Phase monitor alarm: In-phase timeout (the system was not able to establish a "Sync" situation within the configured time)	
21.13	Switch alarm: Overlap timeout (the contacts have been in a "parallel" position for longer than the configured time)	
21.14	-	not used
21.15	-	not used
21.16	-	not used
21.17	-	not used
21.18	-	not used
21.19	-	not used
21.20	-	not used

Logical Command Variables: [98.00] - *LogicsManager* Outputs

LogicsManager outputs, 98.01-98.20

The external discrete outputs may be used as command variable in a logical output.

No.	Name / Function	Note
98.01	<i>LogicsManager</i> "Inhibit ATS" is TRUE	
98.02	<i>LogicsManager</i> "Inhibit transfer to S1" is TRUE	
98.03	<i>LogicsManager</i> "Inhibit transfer to S2" is TRUE	
98.04	<i>LogicsManager</i> "Remote peak shave" is TRUE	
98.05	<i>LogicsManager</i> "Interruptible power rate provisions" is TRUE	
98.06	<i>LogicsManager</i> "Gen-Gen enable" is TRUE	
98.07	<i>LogicsManager</i> "Delayed mode activation" is TRUE	
98.08	<i>LogicsManager</i> "Extended parallel time" is TRUE	
98.09	<i>LogicsManager</i> "Load Test" is TRUE	
98.10	<i>LogicsManager</i> "No Load Test" is TRUE	
98.11	<i>LogicsManager</i> "Source 1 priority" is TRUE	
98.12	<i>LogicsManager</i> "Source 2 priority" is TRUE	
98.13	<i>LogicsManager</i> "External bypass" is TRUE	
98.14	<i>LogicsManager</i> "Load shed" is TRUE	
98.15	-	not used
98.16	-	not used
98.17	-	not used
98.18	-	not used
98.19	-	not used
98.20	-	not used

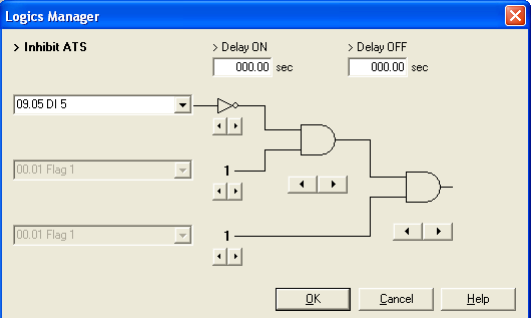
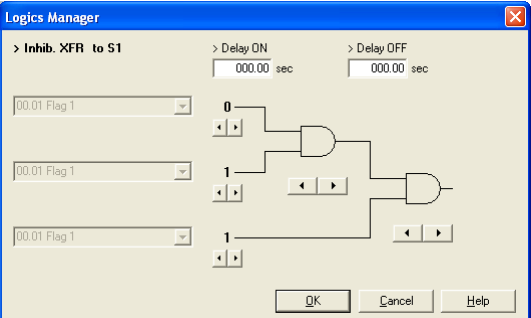
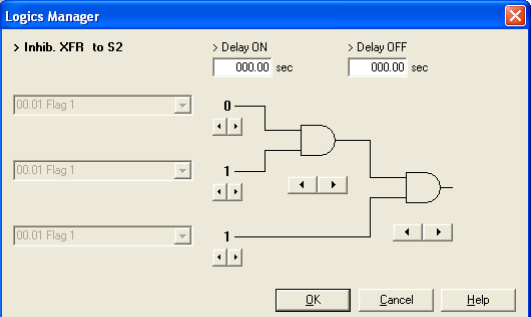
Factory Setting

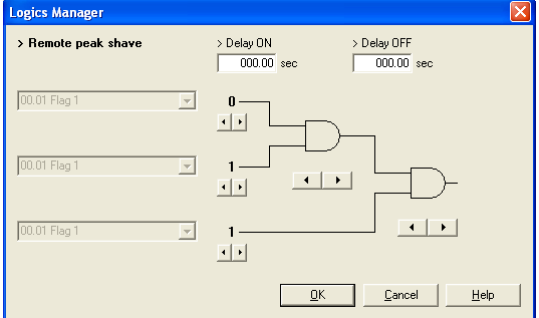
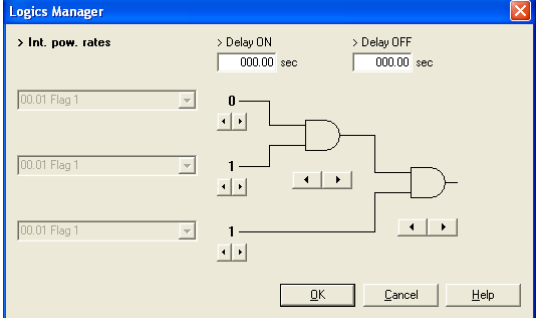
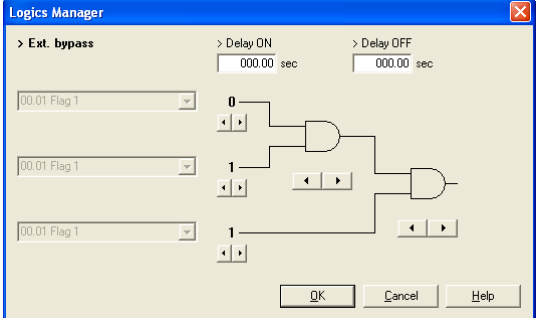
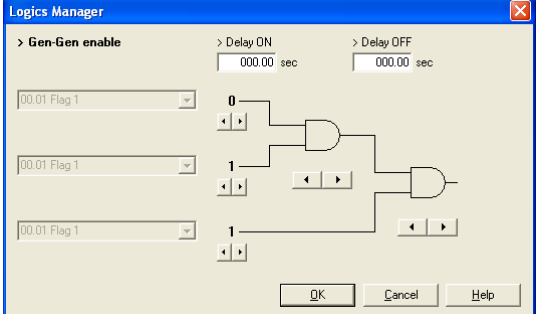


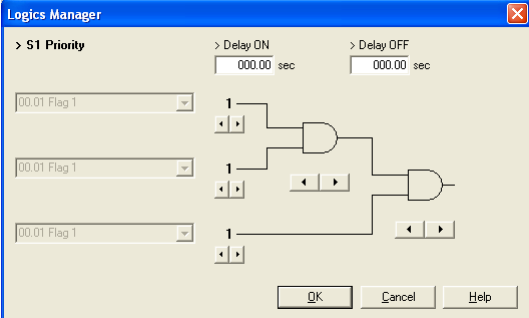
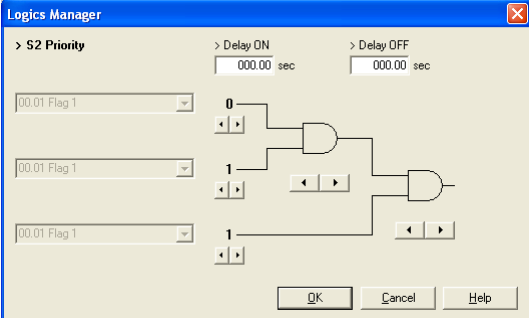
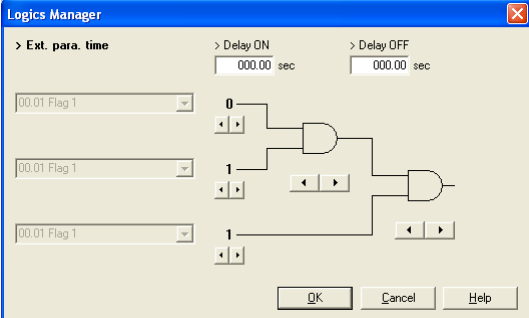
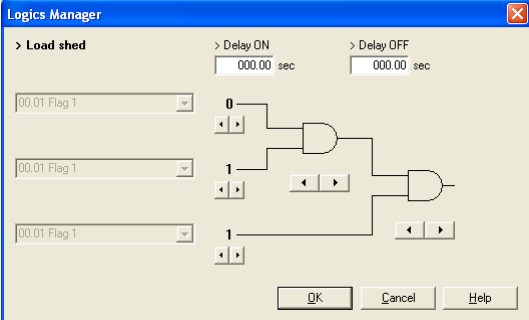
The inputs, outputs, and internal flags, which may be programmed via the *LogicsManager* have the following factory default settings when delivered:

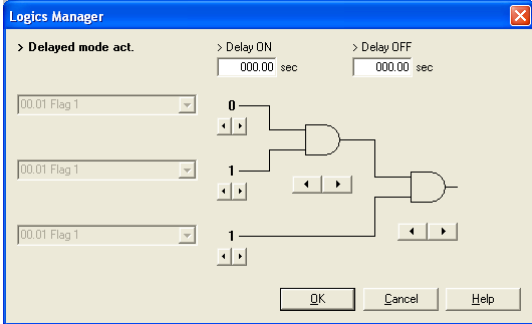
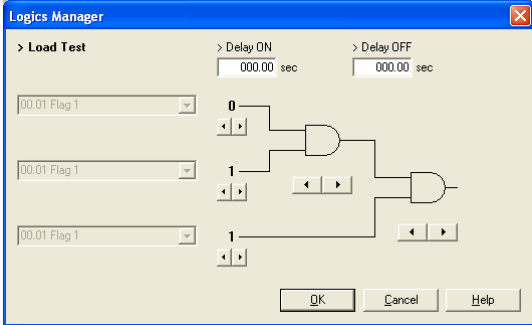
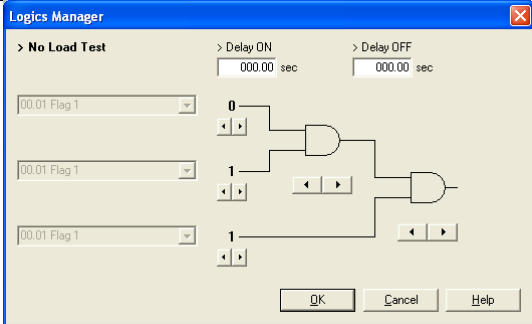
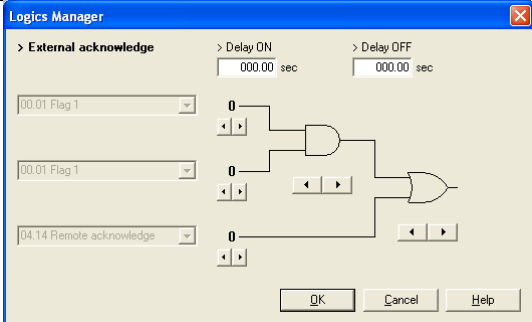
simple (function)	extended (configuration)	result
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Factory Setting: Functions

Inhibit ATS (parameter 12600 on page 27)				dependent on DI 5
{0}	✓	If TRUE, the unit is blocked against automatic transfers.		
{1}	✓			
{2}	✓	TRUE, if DI 5 is NOT energized		
Inhibit XFR to Source 1 (parameter 12610 on page 28)				FALSE
{0}	✓	If TRUE, the unit is blocked against a transfer to source 1.		
{1}	✓			
{2}	✓	Prepared for: - Deactivated by default		
Inhibit XFR to Source 2 (parameter 12620 on page 28)				FALSE
{0}	✓	If TRUE, the unit is blocked against a transfer to source 2.		
{1}	✓			
{2}	✓	Prepared for: - Deactivated by default		

simple (function)		extended (configuration)	result
Remote peak shave (parameter 12630 on page 28)			
{0}	✓	If TRUE, the remote peak shave function will be performed.	
{1}	✓		
{2}	✓		
		Prepared for: - Deactivated by default	FALSE
Interruptible power rates (parameter 12660 on page 29)			
{0}	✓	If TRUE, the interruptible power rate provision function will be performed.	
{1}	✓		
{2}	✓		
		Prepared for: - Deactivated by default	FALSE
External timer bypass (parameter 12820 on page 29)			
{0}	✓	If TRUE, all timers, which are currently in progress, will be bypassed.	
{1}	✓		
{2}	✓		
		Prepared for: - Deactivated by default	FALSE
Gen-Gen enable (parameter 12830 on page 30)			
{0}	---	If TRUE, the gen-gen mode will be enabled.	
{1}	---		
{2}	✓		
		Prepared for: - Deactivated by default	FALSE

simple (function)		extended (configuration)	result
Source 1 priority (parameter 12680 on page 34)			
{0}	✓	If TRUE, source 1 is preferred. Prepared for: - Activated by default	
{1}	✓		
{2}	✓		
Source 2 priority (parameter 12810 on page 34)			
{0}	✓	If TRUE, source 2 is preferred. Prepared for: - Deactivated by default	
{1}	✓		
{2}	✓		
Extended parallel time (parameter 12860 on page 36)			
{0}	✓	If TRUE, the transfer switch remains in overlap position. Prepared for: - Deactivated by default	
{1}	---		
{2}	✓		
Load shed (parameter 12870 on page 38)			
{0}	✓	If TRUE, a load shed from the non-preferred source will be performed. Prepared for: - Deactivated by default	
{1}	---		
{2}	✓		

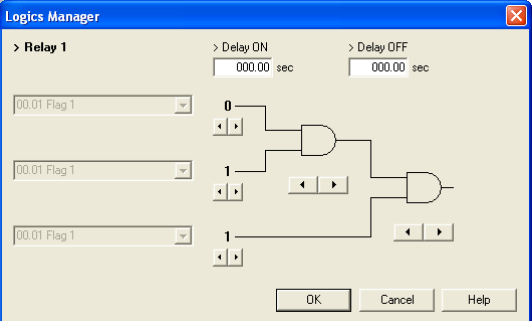
simple (function)		extended (configuration)	result
Delayed mode active (parameter 12850 on page 43)			
{0}	✓	If TRUE, the transfer switch type will be set to Delayed. Prepared for: - Deactivated by default	
{1}	✓		
{2}	✓		
			FALSE
Load test (parameter 12640 on page 48)			
{0}	✓	If TRUE, a load test will be performed. Prepared for: - Deactivated by default	
{1}	✓		
{2}	✓		
			FALSE
No load test (parameter 12650 on page 48)			
{0}	✓	If TRUE, a no-load test will be performed. Prepared for: - Deactivated by default	
{1}	✓		
{2}	✓		
			FALSE
External acknowledgement (parameter 12490 on page 49)			
{0}	✓	If TRUE, alarms are acknowledged from an external source. Prepared for: - Remote acknowledgement	
{1}	✓		
{2}	✓		
			FALSE

simple (function)	extended (configuration)	result
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Factory Setting: Relay Outputs

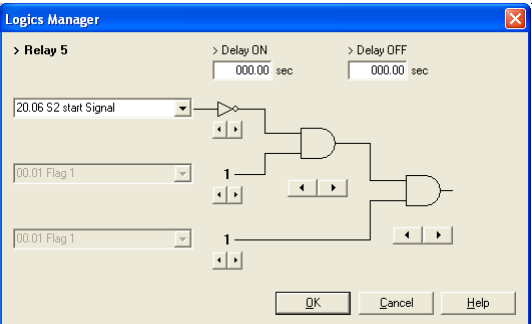
Relay {x} [R0x]; {x} = 1 to 4

(parameters 12100, 12110, 12310, and 12320 on page 79)

{0}	✓	If TRUE, relay 1 will be energized.		FALSE
{1}	✓			
{2}	✓	Prepared for: - Deactivated by default		

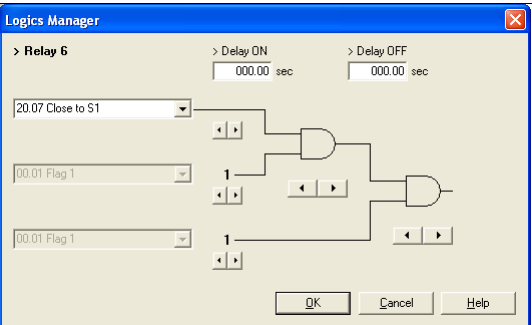
Relay 5 [R05]

(parameter 12130 on page 79)

{0}	✓	If TRUE, relay 5 will be energized.		dependent on Logics Command Variable [20.06]
{1}	✓			
{2}	✓	True, if the Source 2 start signal is issued		

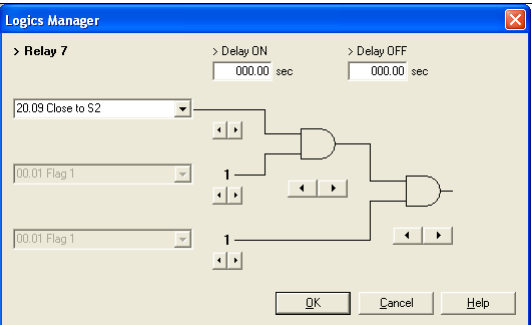
Relay 6 [R06]

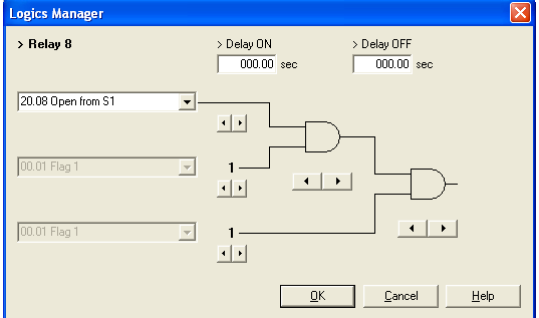
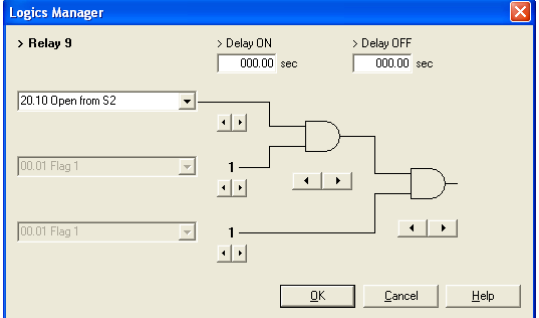
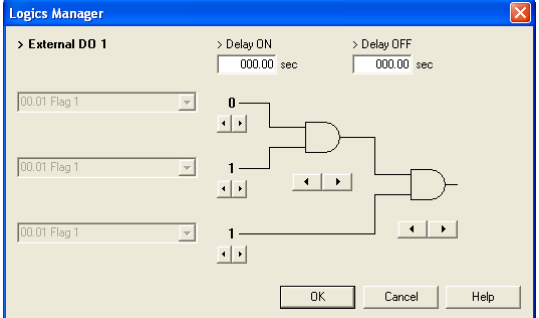
(parameter 12140 on page 79)

{0}	✓	If TRUE, relay 6 will be energized.		dependent on Logics Command Variable [20.07]
{1}	✓			
{2}	✓	True, if the command: Close to Source 1 is issued		

Relay 7 [R07]

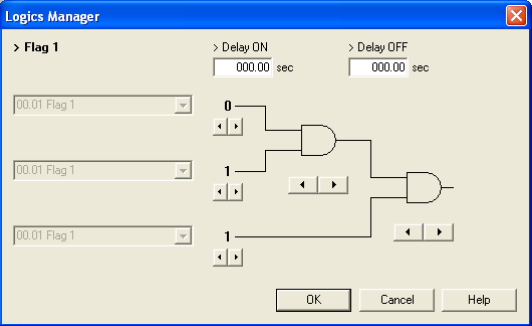
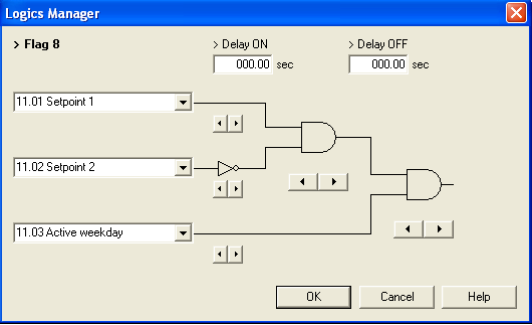
(parameter 12150 on page 79)

{0}	✓	If TRUE, relay 7 will be energized.		dependent on Logics Command Variable [20.09]
{1}	✓			
{2}	✓	True, if the command: Close to Source 2 is issued		

simple (function)		extended (configuration)	result
Relay 8 [R08] (parameter 12160 on page 79)			
{0}	✓	If TRUE, relay 8 will be energized.	
{1}	✓		
{2}	✓		
		True, if the command: Open from Source 1 is issued	 <p>dependent on Logics Command Variable [20.08]</p>
Relay 9 [R09] (parameter 12170 on page 79)			
{0}	✓	If TRUE, relay 9 will be energized.	
{1}	✓		
{2}	✓		
		True, if the command: Open from Source 2 is issued	 <p>dependent on Logics Command Variable [20.10]</p>
External digital output {x} [REx{x}] - free (external expansion card, if connected; {x} = 1-16) (refer to Table 3-12 on page 79 for the parameter IDs of the parameters for external DOs 1 through 16)			
{0}	✓	If TRUE, the external relay {x} will be energized, if this is connected	
{1}	✓		
{2}	✓		
		Prepared for: - Deactivated by default	 <p>FALSE</p>

simple (function)	extended (configuration)	result
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Factory Setting: Internal Flags

Internal flag {x}; {x} = 1 to 7 (refer to Table 3-13 on page 81 for the parameter IDs of the parameters for internal flags 1 through 7)		
{0}	✓	If TRUE, the internal flag {x} will be enabled.
{1}	✓	
{2}	✓	
		Prepared for: - Deactivated by default
		Note: Internal flag 1 is used as default setting in all logical outputs.
		
Internal flag 8 (parameter 12300 on page 81)		
{0}	✓	If TRUE, the internal flag 8 will be enabled.
{1}	✓	
{2}	✓	
		TRUE, once the configured time 1 has been reached [11.01], and the configured time 2 [11.02] has not been reached as well, if the current day is the configured day [11.03]
		

FALSE

dependent
on Logics
Command
Variables
[11.01],
[11.02], and
[11.03]

Discrete Inputs

[D1]	{0}	Reply from ATS switch: Breaker in source 1 position
	{1}	
	{2}	
[D2]	{0}	Reply from ATS switch: Breaker in source 2 position
	{1}	
	{2}	
[D3]	{0}	Reply from ATS switch: Breaker in source 1 open position
	{1}	
	{2}	
[D4]	{0}	Reply from ATS switch: Breaker in source 2 open position
	{1}	
	{2}	
[D5]	{0}	freely configurable discrete input (pre-configured to Inhibit ATS)
	{1}	
	{2}	
[D6]	{0}	freely configurable discrete input (unassigned)
	{1}	
	{2}	
[D7]	{0}	freely configurable discrete input (unassigned)
	{1}	
	{2}	
[D8]	{0}	freely configurable discrete input (unassigned)
	{1}	
	{2}	
[D9]	{0}	freely configurable discrete input (unassigned)
	{1}	
	{2}	
[D10]	{0}	freely configurable discrete input (unassigned)
	{1}	
	{2}	
[D11]	{0}	freely configurable discrete input (unassigned)
	{1}	
	{2}	
[D12]	{0}	freely configurable discrete input (unassigned)
	{1}	
	{2}	



NOTE

The discrete inputs for the breaker position reply messages (DIs 1 through 4) are fixed to N.C. and are evaluated as N.C., i.e. the breaker is considered as "in position" if the respective DI is de-energized.

Appendix B. GetEventLog

The event logger is a 300-entry FIFO (First In/First Out) memory for logging alarm events and operation states of the unit. Refer to the Event History section on page 15 for more info about the event logger.

It is possible to read out the event logger using the direct configuration cable DPC and the GetEventLog software tool.

GetEventLog Software



Installing GetEventLog

GetEventLog can either be used as a stand alone or within LeoPC1. In order to call it up from LeoPC1, it must be installed into the LeoPC1 installation path.

To install GetEventLog, start GetEventLog_vxxxxx.exe from the GetEventLog directory on the CD delivered with the unit.

If you want to use GetEventLog from inside LeoPC1, it must be installed into the LeoPC1 installation directory.

Starting GetEventLog

Connect the DTSC to a free COM port on your computer using the DPC as described under Configuration Using The PC on page 8.

Start GetEventLog directly or call it up by selecting GetEventLog from the menu Tools in LeoPC1.

After starting GetEventLog for the first time, you must configure the communication settings. To do this, select the Interface tab, configure the COM port according to the port, to which you have connected the DPC, and enter the other settings as represented in figure Figure 3-33 since these are the default settings of the DTSC.

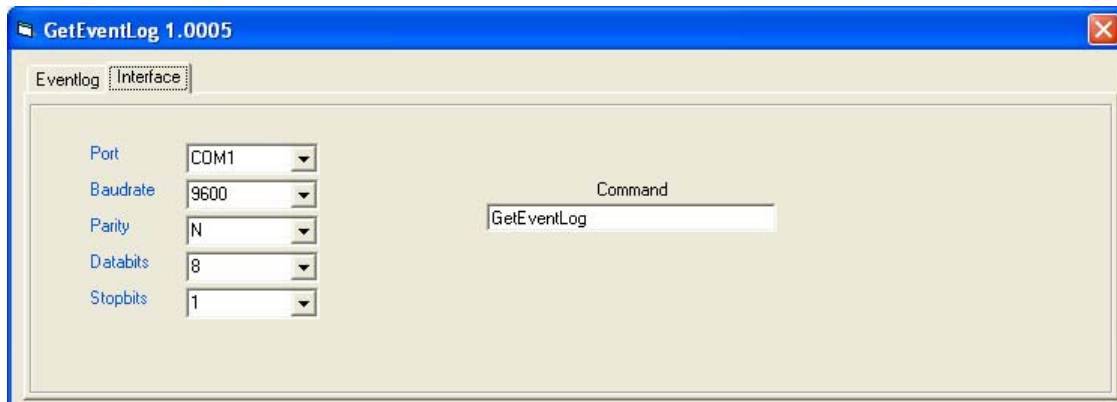


Figure 3-33: GetEventLog - interface configuration

Reading Out GetEventLog

On the Eventlog tab of GetEventLog, click the Request Eventlog button to read out the content of the event logger memory. The content of the event logger is displayed as shown in Figure 3-34.

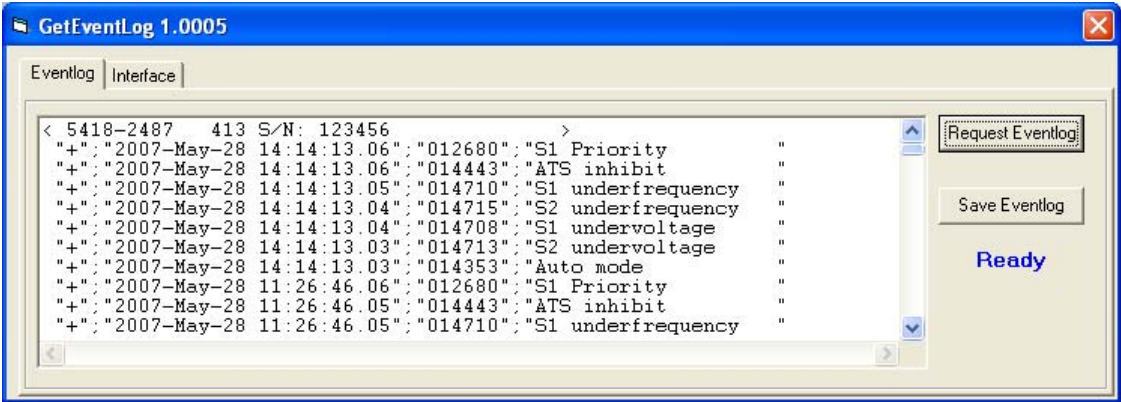


Figure 3-34: GetEventLog - event logger content

The 300 latest events are displayed in chronological order and each entry is composed like this:

"sign";"event date and time";"event no."; "event text"

whereas the **"sign"** "+" indicates the occurrence and "-" indicates the disappearance or acknowledgement of the alarm or state

"event date and time" serves as a timestamp and indicates the date and time of the event occurred

"event no." indicates the event number that occurred

"event text" indicates the event that occurred in clear text

The event text is read out in the language, which is selected in the DTSC, like English or French. Some languages may not be supported by LeoPC1, like Japanese or Chinese. Then you may change the language in the unit.

The event numbers are indicated in Table 3-17 at the end of this section. Please note that some event texts may be configured freely (like analog inputs, etc.) and may not correspond with the original text. The event numbers are unambiguous.

Example: The entry **"+"; "2005-June-15 13:23:05.69"; "014710"; "S1 underfrequency"** means that an Source 1 underfrequency condition **"014710"** occurred **"+"** at June 15, 2005 at 23 minutes, 5 seconds and 69 hundredths of a second after 1 o'clock in the afternoon **"2005-June-15 13:23:05.69"**.

Storing Event Logger Data

Using the Save Eventlog button on the Eventlog tab, you are able to save the content of the event logger in CSV format (comma separated values). You may open the saved file within Excel for example.

	A	B	C	D
1	< 5418-2487	413 S/N: 123456	>	
2	"+"	2007-May-28	12680	S1 Priority
3	"+"	2007-May-28	14443	ATS inhibit
4	"+"	2007-May-28	14710	S1 underfrequency
5	"+"	2007-May-28	14715	S2 underfrequency
6	"+"	2007-May-28	14708	S1 undervoltage
7	"+"	2007-May-28	14713	S2 undervoltage
8	"+"	2007-May-28	14353	Auto mode
9	"+"	2007-May-28	12680	S1 Priority
10	"+"	2007-May-28	14443	ATS inhibit
11	"+"	2007-May-28	14710	S1 underfrequency
12	"+"	2007-May-28	14715	S2 underfrequency
13	"+"	2007-May-28	14708	S1 undervoltage

Figure 3-35: GetEventLog - event logger content in Excel


Resetting the Event Logger

The event logger can be reset using the parameter "Clear event log" via the front panel or LeoPC1 (deleted events or empty entries are represented with a series of dashes in the event logger). To do this, perform the following steps:

Resetting the Event Logger Using the Front Panel

Make sure that you are in code level CL2 (refer to the Password section on page 14).

Set the parameter "Clear event log" to YES (refer to the Event History section on page 15).

The complete event logger is now being cleared (single events may be cleared by pressing the  button).

Resetting the Event Logger Using LeoPC1

Connect the DTSC with your PC and start LeoPC1 as described in Configuration Using The PC on page 8.

Set the parameter "Clear event log" to YES (refer to the Event History section on page 15).

The complete event logger is now being cleared.

Event Texts and Numbers

Event no.	Event text	Description
12680	S1 Priority	Source 1 has priority
12810	S2 Priority	Source 1 has priority
12820	Ext. bypass	External bypass enabled
12830	Gen-Gen enable	Gen-2-Gen mode enabled
12850	Delayed mode act.	Delayed transition mode enabled
12860	Ext. para. time	Extended parallel time enabled
12870	Load shed	Load shed from non-preferred source requested
13226	Pre Signal timer	Elevator pre-signal active
13227	Wait S1 to open	Open transfer switch from S1 position
13228	Wait S2 to open	Open transfer switch from S2 position
13229	Wait S1 to close	Close transfer switch to S1 position
13230	Wait S2 to close	Close transfer switch to S2 position
14353	Auto mode	Auto mode is active
14418	Load test	Load test active
14419	No load test	No Load test active
14434	Rem. peak shave	Remote peak shave active
14435	Motor Load Disc.	Motor load disconnect signal active
14439	Inhib. XFR to S1	Inhibit transfer to Source 1
14440	Inhib. XFR to S2	Inhibit transfer to Source 2
14442	Pwr. rate. prov.	Interruptible power rates active
14443	ATS inhibit	ATS inhibit
14708	S1 undervoltage	Source 1 undervoltage
14709	S1 overvoltage	Source 1 overvoltage
14710	S1 underfrequency	Source 1 underfrequency
14711	S1 overfrequency	Source 1 overfrequency
14712	S1 voltage imbalance	Source 1 voltage imbalance
14713	S2 undervoltage	Source 2 undervoltage
14714	S2 overvoltage	Source 2 overvoltage
14715	S2 underfrequency	Source 2 underfrequency
14716	S2 overfrequency	Source 2 overfrequency
14717	S2 voltage imbalance	Source 2 voltage imbalance

Table 3-17: Event logger - event texts and numbers

Appendix C.

List Of Parameters

Unit number P/N _____ Rev _____

Version DTSC-_____

Project _____

Serial number S/N _____ Date _____

Par. ID.	Parameter	Setting range	Default value	Customer setting	Data type
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MAIN MENU

1700	Language	English / Deutsch	English		UNSIGNED 16
10416	Password	0000 to 9999	---		UNSIGNED 16

EVENT LOG

1706	Clear event log	YES / NO	NO	<input type="checkbox"/> Y <input type="checkbox"/> N	<input type="checkbox"/> Y <input type="checkbox"/> N	UNSIGNED 16
------	-----------------	----------	----	---	---	-------------

MEASUREMENT

1750	Rated system frequency	50/60 Hz	50 Hz			UNSIGNED 16
1774	Rated voltage S1	50 to 650000 V	400 V			UNSIGNED 32
1772	Rated voltage S2	50 to 650000 V	400 V			UNSIGNED 32
1862	S1 voltage measuring	3Ph 4W 3Ph 3W 1Ph 2W 1Ph 3W	3Ph 4W	<input type="checkbox"/> 3Ph4W <input type="checkbox"/> 3Ph3W <input type="checkbox"/> 1Ph2W <input type="checkbox"/> 1Ph3W	<input type="checkbox"/> 3Ph4W <input type="checkbox"/> 3Ph3W <input type="checkbox"/> 1Ph2W <input type="checkbox"/> 1Ph3W	UNSIGNED 16
1861	S2 voltage measuring	3Ph 4W 3Ph 3W 1Ph 2W 1Ph 3W	3Ph 4W	<input type="checkbox"/> 3Ph4W <input type="checkbox"/> 3Ph3W <input type="checkbox"/> 1Ph2W <input type="checkbox"/> 1Ph3W	<input type="checkbox"/> 3Ph4W <input type="checkbox"/> 3Ph3W <input type="checkbox"/> 1Ph2W <input type="checkbox"/> 1Ph3W	UNSIGNED 16
1858	Def. of 1Ph2W measuring	phase - neutral phase - phase	phase - phase	<input type="checkbox"/> p-n <input type="checkbox"/> p-p	<input type="checkbox"/> p-n <input type="checkbox"/> p-p	UNSIGNED 16
1859	Def. of 1Ph2W phase rotation	CW / CCW	CW	<input type="checkbox"/> CW <input type="checkbox"/> CCW	<input type="checkbox"/> CW <input type="checkbox"/> CCW	UNSIGNED 16
1860	Load current measuring	L1 L2 L3 Phase L1 Phase L2 Phase L3	L1 L2 L3	<input type="checkbox"/> L123 <input type="checkbox"/> Ph.L1 <input type="checkbox"/> Ph.L2 <input type="checkbox"/> Ph.L3	<input type="checkbox"/> L123 <input type="checkbox"/> Ph.L1 <input type="checkbox"/> Ph.L2 <input type="checkbox"/> Ph.L3	UNSIGNED 16
1752	Rated active power [kW]	0.5 to 99999.9 kW	200.0 kW			UNSIGNED 32
1754	Rated current	5 to 32000 A	300 A			UNSIGNED 16
Transformer						
1819	S1 voltage transf. primary	50 to 650000 V	400 V			UNSIGNED 32
1818	S1 voltage transf. secondary	50 to 480 V	400 V			UNSIGNED 16
1816	S2 voltage transf. primary	50 to 650000 V	400 V			UNSIGNED 32
1815	S2 voltage transf. secondary	50 to 480 V	400 V			UNSIGNED 16
1821	Load current transformer	1 to 32000/5 A	500/5 A			UNSIGNED 16
1822	Load current transformer	1 to 32000/1 A	500/1 A			UNSIGNED 16

Par. ID.	Parameter	Setting range	Default value	Customer setting	Data type
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APPLICATION

4148	Application mode	Util-Gen Gen-Gen Util-Util	Util-Gen	<input type="checkbox"/> Util-Gen <input type="checkbox"/> Gen-Gen <input type="checkbox"/> Util-Util	<input type="checkbox"/> Util-Gen <input type="checkbox"/> Gen-Gen <input type="checkbox"/> Util-Util	UNSIGNED 16
4146	Transfer Commit	YES / NO	NO	<input type="checkbox"/> Y <input type="checkbox"/> N	<input type="checkbox"/> Y <input type="checkbox"/> N	UNSIGNED 16
4149	S1 start delay time	1 to 300 s	10 s			UNSIGNED 16
3330	S2 start delay time	1 to 300 s	10 s			UNSIGNED 16
3333	S1 source stable time	1 to 6500 s	10 s			UNSIGNED 16
3332	S2 source stable time	1 to 6500 s	10 s			UNSIGNED 16
2804	S1 outage delay	0.1 to 10.0 s	1.0 s			UNSIGNED 16
2803	S2 outage delay	0.1 to 10.0 s	1.0 s			UNSIGNED 16
3343	S1 cooldown time	1 to 6500 s	20 s			UNSIGNED 16
3344	S2 cooldown time	1 to 6500 s	20 s			UNSIGNED 16
12600	Inhibit ATS	see descr. in <i>LogicsManager</i> chap. starting p. 112; default: (!09.05 & 1) & 1				Logman
12610	Inhib. XFR to S1	see descr. in <i>LogicsManager</i> chap. starting page 112; default: (0 & 1) & 1				Logman
12620	Inhib. XFR to S2	see descr. in <i>LogicsManager</i> chap. starting page 112; default: (0 & 1) & 1				Logman
12630	Remote peak shave	see descr. in <i>LogicsManager</i> chap. starting page 112; default: (0 & 1) & 1				Logman
12660	Int. pow. rates	see descr. in <i>LogicsManager</i> chap. starting page 112; default: (0 & 1) & 1				Logman
12820	Ext. bypass	see descr. in <i>LogicsManager</i> chap. starting page 112; default: (0 & 1) & 1				Logman
12830	Gen-Gen enable	see descr. in <i>LogicsManager</i> chap. starting page 112; default: (0 & 1) & 1				Logman
Elevator Pre Signal						
4490	Elevator Pre signal	ON / OFF	OFF	<input type="checkbox"/> 1 <input type="checkbox"/> 0	<input type="checkbox"/> 1 <input type="checkbox"/> 0	UNSIGNED 16
4491	Elevator pre-signal duration	1 to 6500 s	5 s			UNSIGNED 16
Motor Load Disconnect						
4550	Motor Load Disconnect	ON / OFF	OFF	<input type="checkbox"/> 1 <input type="checkbox"/> 0	<input type="checkbox"/> 1 <input type="checkbox"/> 0	UNSIGNED 16
4553	Active direction	S1->S2 S2->S1 Both	S1->S2	<input type="checkbox"/> S1->S2 <input type="checkbox"/> S2->S1 <input type="checkbox"/> Both	<input type="checkbox"/> S1->S2 <input type="checkbox"/> S2->S1 <input type="checkbox"/> Both	UNSIGNED 16
4551	Disconnect time S1->S2	1 to 6500 s	5 s			UNSIGNED 16
4552	Disconnect time S2->S1	1 to 6500 s	5 s			UNSIGNED 16
Source Priority						
12680	S1 Priority	see descr. in <i>LogicsManager</i> chap. starting page 112; default: (1 & 1) & 1				Logman
12810	S2 Priority	see descr. in <i>LogicsManager</i> chap. starting page 112; default: (0 & 1) & 1				Logman
12860	Ext. para.time	see descr. in <i>LogicsManager</i> chap. starting page 112; default: (0 & 1) & 1				Logman
12870	Load shed	see descr. in <i>LogicsManager</i> chap. starting page 112; default: (0 & 1) & 1				Logman

BREAKER

3424	Transfer switch type	Standard Delayed Closet	Standard	<input type="checkbox"/> Standard <input type="checkbox"/> Delayed <input type="checkbox"/> Closed	<input type="checkbox"/> Standard <input type="checkbox"/> Delayed <input type="checkbox"/> Closed	UNSIGNED 16
3434	Use limit sw. OPEN replies	YES / NO	YES	<input type="checkbox"/> Y <input type="checkbox"/> N	<input type="checkbox"/> Y <input type="checkbox"/> N	UNSIGNED 16
12850	Delayed mode act.	see descr. in <i>LogicsManager</i> chap. starting page 112; default: (0 & 1) & 1				Logman
3426	Neutral time S2->S1	1 to 6500 s	3 s			UNSIGNED 16
3425	Neutral time S1->S2	1 to 6500 s	3 s			UNSIGNED 16
3428	Limit switch reply timeout	0.1 to 99.9 s	1.0 s			UNSIGNED 16
3429	Wait time until next XFR attempt	0.1 to 99.9 s	3.0 s			UNSIGNED 16
3427	Max. of Transfer attempts	1 to 10	2			UNSIGNED 16

TESTMODES

12640	Load Test	see descr. in <i>LogicsManager</i> chap. starting page 112; default: (0 & 1) & 1				Logman
12650	No Load Test	see descr. in <i>LogicsManager</i> chap. starting page 112; default: (0 & 1) & 1				Logman

Par. ID.	Parameter	Setting range	Default value	Customer setting	Data type
MONITORING					
1756	Time until horn reset	0 to 1000 s	180 s		UNSIGNED 16
12490	External acknowledge	see descr. in <i>LogicsManager</i> chap. starting page 112; default: (0 & 0)+ 0			Logman
3430	Limit switch monitoring	ON / OFF	OFF	<input type="checkbox"/> 1 <input type="checkbox"/> 0	UNSIGNED 16
S1 Monitoring					
1787	Voltage monitoring S1	3 phase/4 phase	3 phase	<input type="checkbox"/> 3 <input type="checkbox"/> 4	UNSIGNED 16
4450	S1 undervoltage restore	50.0 to 125.0 %	90.0 %		UNSIGNED 16
4451	S1 undervoltage fail	50.0 to 125.0 %	80.0 %		UNSIGNED 16
4452	S1 underfrequency monitoring	ON / OFF	ON	<input type="checkbox"/> 1 <input type="checkbox"/> 0	UNSIGNED 16
4453	S1 underfrequency restore	50.0 to 130.0 %	95.0 %		UNSIGNED 16
4454	S1 underfrequency fail	50.0 to 130.0 %	90.0 %		UNSIGNED 16
4455	S1 overvoltage monitoring	ON / OFF	ON	<input type="checkbox"/> 1 <input type="checkbox"/> 0	UNSIGNED 16
4456	S1 overvoltage restore	50.0 to 125.0 %	105.0 %		UNSIGNED 16
4457	S1 overvoltage fail	50.0 to 125.0 %	110.0 %		UNSIGNED 16
4458	S1 overfrequency monitoring	ON / OFF	ON	<input type="checkbox"/> 1 <input type="checkbox"/> 0	UNSIGNED 16
4459	S1 overfrequency restore	50.0 to 130.0 %	102.0 %		UNSIGNED 16
4460	S1 overfrequency fail	50.0 to 130.0 %	105.0 %		UNSIGNED 16
4461	S1 voltage imbalance monitoring	ON / OFF	ON	<input type="checkbox"/> 1 <input type="checkbox"/> 0	UNSIGNED 16
4462	S1 volt. imbalance restore	0.5 to 99.9 %	8.0 %		UNSIGNED 16
4463	S1 volt. imbalance fail	0.5 to 99.9 %	10.0 %		UNSIGNED 16
3914	Delay	0.02 to 99.99 s	5.00 s		UNSIGNED 16
4562	S1 phase rotation	ON / OFF	ON	<input type="checkbox"/> 1 <input type="checkbox"/> 0	UNSIGNED 16
4563	S1 phase rotation	CW CCW	CW	<input type="checkbox"/> CW <input type="checkbox"/> CCW	UNSIGNED 16
S2 Monitoring					
1786	Voltage monitoring S2	3 phase/4 phase	3 phase	<input type="checkbox"/> 3 <input type="checkbox"/> 4	UNSIGNED 16
4465	S2 undervoltage restore	50.0 to 125.0 %	90.0 %		UNSIGNED 16
4466	S2 undervoltage fail	50.0 to 125.0 %	80.0 %		UNSIGNED 16
4467	S2 underfrequency monitoring	ON / OFF	ON	<input type="checkbox"/> 1 <input type="checkbox"/> 0	UNSIGNED 16
4468	S2 underfrequency restore	50.0 to 130.0 %	95.0 %		UNSIGNED 16
4469	S2 underfrequency fail	50.0 to 130.0 %	90.0 %		UNSIGNED 16
4470	S2 overvoltage monitoring	ON / OFF	ON	<input type="checkbox"/> 1 <input type="checkbox"/> 0	UNSIGNED 16
4471	S2 overvoltage restore	50.0 to 125.0 %	105.0 %		UNSIGNED 16
4472	S2 overvoltage fail	50.0 to 125.0 %	110.0 %		UNSIGNED 16
4473	S2 overfrequency monitoring	ON / OFF	ON	<input type="checkbox"/> 1 <input type="checkbox"/> 0	UNSIGNED 16
4474	S2 overfrequency restore	50.0 to 130.0 %	102.0 %		UNSIGNED 16
4475	S2 overfrequency fail	50.0 to 130.0 %	105.0 %		UNSIGNED 16
4476	S2 voltage imbalance monitoring	ON / OFF	ON	<input type="checkbox"/> 1 <input type="checkbox"/> 0	UNSIGNED 16
4477	S2 volt. imbalance restore	0.5 to 99.9 %	8.0 %		UNSIGNED 16
4478	S2 volt. imbalance fail	0.5 to 99.9 %	10.0 %		UNSIGNED 16
3904	Delay	0.02 to 99.99 s	5.00 s		UNSIGNED 16
4566	S2 phase rotation	ON / OFF	ON	<input type="checkbox"/> 1 <input type="checkbox"/> 0	UNSIGNED 16
4567	S2 phase rotation	CW CCW	CW	<input type="checkbox"/> CW <input type="checkbox"/> CCW	UNSIGNED 16
In-Phase Monitoring					
4570	In-Phase monitor	ON / OFF	ON	<input type="checkbox"/> 1 <input type="checkbox"/> 0	UNSIGNED 16
4571	Voltage window	0.50 to 9.99 %	1.00 %		UNSIGNED 16
4572	Positive frequency window	0.02 to 0.49 Hz	0.18 Hz		SIGNED 16
4573	Negative frequency window	-0.02 to -0.49 Hz	-0.18 Hz		SIGNED 16
4577	Max. overlap time	0.1 to 9.99 s	0.10 s		UNSIGNED 16
4578	Open trans. switch reac. time	15 to 300 ms	30 ms		UNSIGNED 16
4583	Closed trans. switch reac. time	15 to 300 ms	30 ms		UNSIGNED 16
4581	Vector group angle adjustment	-180° to 180°	0°		SIGNED 16
4576	In-phase timeout after	0 to 6500 s	60 s		UNSIGNED 16
4582	Outcome on In-phase timeout	Abort Delayed	Abort	<input type="checkbox"/> Abort <input type="checkbox"/> Delayed	UNSIGNED 16

Par. ID.	Parameter	Setting range	Default value	Customer setting		Data type
MONITORING						
	Load Monitoring					
	Overcurrent Monitoring level 1					
2200	Monitoring	ON / OFF	ON	<input type="checkbox"/> 1 <input type="checkbox"/> 0	<input type="checkbox"/> 1 <input type="checkbox"/> 0	UNSIGNED 16
2204	Limit	50.0 to 300.0 %	110.0 %			UNSIGNED 16
2205	Delay	0.02 to 99.99 s	30.00 s			UNSIGNED 16
2202	Self acknowledge	YES / NO	NO	<input type="checkbox"/> Y <input type="checkbox"/> N	<input type="checkbox"/> Y <input type="checkbox"/> N	UNSIGNED 16
	Overcurrent Monitoring level 2					
2206	Monitoring	ON / OFF	ON	<input type="checkbox"/> 1 <input type="checkbox"/> 0	<input type="checkbox"/> 1 <input type="checkbox"/> 0	UNSIGNED 16
2210	Limit	50.0 to 300.0 %	150.0 %			UNSIGNED 16
2211	Delay	0.02 to 99.99 s	1.00 s			UNSIGNED 16
2208	Self acknowledge	YES / NO	NO	<input type="checkbox"/> Y <input type="checkbox"/> N	<input type="checkbox"/> Y <input type="checkbox"/> N	UNSIGNED 16
	Overcurrent Monitoring level 3					
2212	Monitoring	ON / OFF	ON	<input type="checkbox"/> 1 <input type="checkbox"/> 0	<input type="checkbox"/> 1 <input type="checkbox"/> 0	UNSIGNED 16
2216	Limit	50.0 to 300.0 %	250.0 %			UNSIGNED 16
2217	Delay	0.02 to 99.99 s	0.40 s			UNSIGNED 16
2214	Self acknowledge	YES / NO	NO	<input type="checkbox"/> Y <input type="checkbox"/> N	<input type="checkbox"/> Y <input type="checkbox"/> N	UNSIGNED 16
	Overload Monitoring level 1					
2300	Monitoring	ON / OFF	ON	<input type="checkbox"/> 1 <input type="checkbox"/> 0	<input type="checkbox"/> 1 <input type="checkbox"/> 0	UNSIGNED 16
2304	Limit	50.0 to 300.0 %	110.0 %			UNSIGNED 16
2305	Delay	0.02 to 99.99 s	11.00 s			UNSIGNED 16
2302	Self acknowledge	YES / NO	NO	<input type="checkbox"/> Y <input type="checkbox"/> N	<input type="checkbox"/> Y <input type="checkbox"/> N	UNSIGNED 16
	Overload Monitoring level 2					
2306	Monitoring	ON / OFF	ON	<input type="checkbox"/> 1 <input type="checkbox"/> 0	<input type="checkbox"/> 1 <input type="checkbox"/> 0	UNSIGNED 16
2510	Limit	50.0 to 300.0 %	120.0 %			UNSIGNED 16
2511	Delay	0.02 to 99.99 s	0.10 s			UNSIGNED 16
2308	Self acknowledge	YES / NO	NO	<input type="checkbox"/> Y <input type="checkbox"/> N	<input type="checkbox"/> Y <input type="checkbox"/> N	UNSIGNED 16
	Engine Monitoring					
	Start Failure S1 Monitoring					
3341	S1 Start fail delay time	1 to 100 s	8 s			UNSIGNED 16
	Start Failure S2 Monitoring					
3331	S2 Start fail delay time	1 to 100 s	8 s			UNSIGNED 16
	Battery Voltage Monitoring					
	Overvoltage Monitoring level 1					
3450	Monitoring	ON / OFF	ON	<input type="checkbox"/> 1 <input type="checkbox"/> 0	<input type="checkbox"/> 1 <input type="checkbox"/> 0	UNSIGNED 16
3454	Limit	8.0 to 42.0 V	32.0 V			UNSIGNED 16
3455	Delay	0.02 to 99.99 s	5.00 s			UNSIGNED 16
3452	Self acknowledge level 1	YES / NO	NO	<input type="checkbox"/> Y <input type="checkbox"/> N	<input type="checkbox"/> Y <input type="checkbox"/> N	UNSIGNED 16
	Overvoltage Monitoring level 2					
3456	Monitoring	ON / OFF	OFF	<input type="checkbox"/> 1 <input type="checkbox"/> 0	<input type="checkbox"/> 1 <input type="checkbox"/> 0	UNSIGNED 16
3460	Limit	8.0 to 42.0 V	35.0 V			UNSIGNED 16
3461	Delay	0.02 to 99.99 s	1.00 s			UNSIGNED 16
3458	Self acknowledge	YES / NO	NO	<input type="checkbox"/> Y <input type="checkbox"/> N	<input type="checkbox"/> Y <input type="checkbox"/> N	UNSIGNED 16
	Undervoltage Monitoring level 1					
3500	Monitoring	ON / OFF	ON	<input type="checkbox"/> 1 <input type="checkbox"/> 0	<input type="checkbox"/> 1 <input type="checkbox"/> 0	UNSIGNED 16
3504	Limit	8.0 to 42.0 V	24.0 V			UNSIGNED 16
3505	Delay	0.02 to 99.99 s	60.00 s			UNSIGNED 16
3502	Self acknowledge	YES / NO	NO	<input type="checkbox"/> Y <input type="checkbox"/> N	<input type="checkbox"/> Y <input type="checkbox"/> N	UNSIGNED 16
	Undervoltage Monitoring level 2					
3506	Monitoring	ON / OFF	ON	<input type="checkbox"/> 1 <input type="checkbox"/> 0	<input type="checkbox"/> 1 <input type="checkbox"/> 0	UNSIGNED 16
3510	Limit	8.0 to 42.0 V	20.0 V			UNSIGNED 16
3511	Delay	0.02 to 99.99 s	10.00 s			UNSIGNED 16
3508	Self acknowledge	YES / NO	NO	<input type="checkbox"/> Y <input type="checkbox"/> N	<input type="checkbox"/> Y <input type="checkbox"/> N	UNSIGNED 16
	CANopen Interface Monitoring					
3150	Monitoring	ON / OFF	OFF	<input type="checkbox"/> 1 <input type="checkbox"/> 0	<input type="checkbox"/> 1 <input type="checkbox"/> 0	UNSIGNED 16
3154	Delay	0.1 to 650.0 s	2.0 s			UNSIGNED 16
3152	Self acknowledge	YES / NO	NO	<input type="checkbox"/> Y <input type="checkbox"/> N	<input type="checkbox"/> Y <input type="checkbox"/> N	UNSIGNED 16

Par. ID.	Parameter	Setting range	Default value	Customer setting	Data type
DIGITAL INPUTS					
Digital Input 1					
	DI 1 operation	N.O. N.C.	N.C.		UNSIGNED 16
	DI 1 delay	0.08 to 650.00 s	0.08 s		UNSIGNED 16
Digital Input 2					
	DI 2 operation	N.O. N.C.	N.C.		UNSIGNED 16
	DI 2 delay	0.08 to 650.00 s	0.08 s		UNSIGNED 16
Digital Input 3					
	DI 3 operation	N.O. N.C.	N.C.		UNSIGNED 16
	DI 3 delay	0.08 to 650.00 s	0.08 s		UNSIGNED 16
Digital Input 4					
	DI 4 operation	N.O. N.C.	N.C.		UNSIGNED 16
	DI 4 delay	0.08 to 650.00 s	0.08 s		UNSIGNED 16
Digital Input 5					
1281	DI 5 operation	N.O. N.C.	N.O.	<input type="checkbox"/> N.O. <input type="checkbox"/> N.C.	UNSIGNED 16
1280	DI 5 delay	0.08 to 650.00 s	0.08 s		UNSIGNED 16
Digital Input 6					
1301	DI 6 operation	N.O. N.C.	N.O.	<input type="checkbox"/> N.O. <input type="checkbox"/> N.C.	UNSIGNED 16
1300	DI 6 delay	0.08 to 650.00 s	0.08 s		UNSIGNED 16
Digital Input 7					
1321	DI 7 operation	N.O. N.C.	N.O.	<input type="checkbox"/> N.O. <input type="checkbox"/> N.C.	UNSIGNED 16
1320	DI 7 delay	0.08 to 650.00 s	0.08 s		UNSIGNED 16
Digital Input 8					
1341	DI 8 operation	N.O. N.C.	N.O.	<input type="checkbox"/> N.O. <input type="checkbox"/> N.C.	UNSIGNED 16
1340	DI 8 delay	0.08 to 650.00 s	0.08 s		UNSIGNED 16
Digital Input 9					
1361	DI 9 operation	N.O. N.C.	N.O.	<input type="checkbox"/> N.O. <input type="checkbox"/> N.C.	UNSIGNED 16
1360	DI 9 delay	0.08 to 650.00 s	0.08 s		UNSIGNED 16
Digital Input 10					
1381	DI 10 operation	N.O. N.C.	N.O.	<input type="checkbox"/> N.O. <input type="checkbox"/> N.C.	UNSIGNED 16
1380	DI 10 delay	0.08 to 650.00 s	0.08 s		UNSIGNED 16
Digital Input 11					
1206	DI 11 operation	N.O. N.C.	N.O.	<input type="checkbox"/> N.O. <input type="checkbox"/> N.C.	UNSIGNED 16
1205	DI 11 delay	0.08 to 650.00 s	0.08 s		UNSIGNED 16
Digital Input 12					
1226	DI 12 operation	N.O. N.C.	N.O.	<input type="checkbox"/> N.O. <input type="checkbox"/> N.C.	UNSIGNED 16
1225	DI 12 delay	0.08 to 650.00 s	0.08 s		UNSIGNED 16
External Digital Input 1					
16001	Operation	N.O. N.C.	N.O.	<input type="checkbox"/> N.O. <input type="checkbox"/> N.C.	UNSIGNED 16
16000	Delay	0.05 to 650.00 s	0.20 s		UNSIGNED 16
External Digital Input 2					
16011	Operation	N.O. N.C.	N.O.	<input type="checkbox"/> N.O. <input type="checkbox"/> N.C.	UNSIGNED 16
16010	Delay	0.05 to 650.00 s	0.20 s		UNSIGNED 16

Par. ID.	Parameter	Setting range	Default value	Customer setting		Data type
DIGITAL INPUTS						
External Digital Input 3						
16021	Operation	N.O. N.C.	N.O.	<input type="checkbox"/> N.O. <input type="checkbox"/> N.C.	<input type="checkbox"/> N.O. <input type="checkbox"/> N.C.	UNSIGNED 16
16020	Delay	0.05 to 650.00 s	0.20 s			UNSIGNED 16
External Digital Input 4						
16031	Operation	N.O. N.C.	N.O.	<input type="checkbox"/> N.O. <input type="checkbox"/> N.C.	<input type="checkbox"/> N.O. <input type="checkbox"/> N.C.	UNSIGNED 16
16030	Delay	0.05 to 650.00 s	0.20 s			UNSIGNED 16
External Digital Input 5						
16041	Operation	N.O. N.C.	N.O.	<input type="checkbox"/> N.O. <input type="checkbox"/> N.C.	<input type="checkbox"/> N.O. <input type="checkbox"/> N.C.	UNSIGNED 16
16040	Delay	0.05 to 650.00 s	0.20 s			UNSIGNED 16
External Digital Input 6						
16051	Operation	N.O. N.C.	N.O.	<input type="checkbox"/> N.O. <input type="checkbox"/> N.C.	<input type="checkbox"/> N.O. <input type="checkbox"/> N.C.	UNSIGNED 16
16050	Delay	0.05 to 650.00 s	0.20 s			UNSIGNED 16
External Digital Input 7						
16061	Operation	N.O. N.C.	N.O.	<input type="checkbox"/> N.O. <input type="checkbox"/> N.C.	<input type="checkbox"/> N.O. <input type="checkbox"/> N.C.	UNSIGNED 16
16060	Delay	0.05 to 650.00 s	0.20 s			UNSIGNED 16
External Digital Input 8						
16071	Operation	N.O. N.C.	N.O.	<input type="checkbox"/> N.O. <input type="checkbox"/> N.C.	<input type="checkbox"/> N.O. <input type="checkbox"/> N.C.	UNSIGNED 16
16070	Delay	0.05 to 650.00 s	0.20 s			UNSIGNED 16
External Digital Input 9						
16081	Operation	N.O. N.C.	N.O.	<input type="checkbox"/> N.O. <input type="checkbox"/> N.C.	<input type="checkbox"/> N.O. <input type="checkbox"/> N.C.	UNSIGNED 16
16080	Delay	0.05 to 650.00 s	0.20 s			UNSIGNED 16
External Digital Input 10						
16091	Operation	N.O. N.C.	N.O.	<input type="checkbox"/> N.O. <input type="checkbox"/> N.C.	<input type="checkbox"/> N.O. <input type="checkbox"/> N.C.	UNSIGNED 16
16090	Delay	0.05 to 650.00 s	0.20 s			UNSIGNED 16
External Digital Input 11						
16101	Operation	N.O. N.C.	N.O.	<input type="checkbox"/> N.O. <input type="checkbox"/> N.C.	<input type="checkbox"/> N.O. <input type="checkbox"/> N.C.	UNSIGNED 16
16100	Delay	0.05 to 650.00 s	0.20 s			UNSIGNED 16
External Digital Input 12						
16111	Operation	N.O. N.C.	N.O.	<input type="checkbox"/> N.O. <input type="checkbox"/> N.C.	<input type="checkbox"/> N.O. <input type="checkbox"/> N.C.	UNSIGNED 16
16110	Delay	0.05 to 650.00 s	0.20 s			UNSIGNED 16
External Digital Input 13						
16121	Operation	N.O. N.C.	N.O.	<input type="checkbox"/> N.O. <input type="checkbox"/> N.C.	<input type="checkbox"/> N.O. <input type="checkbox"/> N.C.	UNSIGNED 16
16120	Delay	0.05 to 650.00 s	0.20 s			UNSIGNED 16
External Digital Input 14						
16131	Operation	N.O. N.C.	N.O.	<input type="checkbox"/> N.O. <input type="checkbox"/> N.C.	<input type="checkbox"/> N.O. <input type="checkbox"/> N.C.	UNSIGNED 16
16130	Delay	0.05 to 650.00 s	0.20 s			UNSIGNED 16
External Digital Input 15						
16141	Operation	N.O. N.C.	N.O.	<input type="checkbox"/> N.O. <input type="checkbox"/> N.C.	<input type="checkbox"/> N.O. <input type="checkbox"/> N.C.	UNSIGNED 16
16140	Delay	0.05 to 650.00 s	0.20 s			UNSIGNED 16
External Digital Input 16						
16151	Operation	N.O. N.C.	N.O.	<input type="checkbox"/> N.O. <input type="checkbox"/> N.C.	<input type="checkbox"/> N.O. <input type="checkbox"/> N.C.	UNSIGNED 16
16150	Delay	0.05 to 650.00 s	0.20 s			UNSIGNED 16

Par. ID.	Parameter	Setting range	Default value	Customer setting	Data type
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DIGITAL OUTPUTS

12100	Relay 1	see descr. in <i>LogicsManager</i> chap. starting page 116; default: (0 & 1) & 1			Logman
12110	Relay 2	see descr. in <i>LogicsManager</i> chap. starting page 116; default: (0 & 1) & 1			Logman
12310	Relay 3	see descr. in <i>LogicsManager</i> chap. starting page 116; default: (0 & 1) & 1			Logman
12320	Relay 4	see descr. in <i>LogicsManager</i> chap. starting page 116; default: (0 & 1) & 1			Logman
12130	Relay 5	see descr. in <i>LogicsManager</i> chap. starting p. 116; default: (!20.06 & 1) & 1			Logman
12140	Relay 6	see descr. in <i>LogicsManager</i> chap. starting page 116; default: (20.07 & 1) & 1			Logman
12150	Relay 7	see descr. in <i>LogicsManager</i> chap. starting page 116; default: (20.09 & 1) & 1			Logman
12160	Relay 8	see descr. in <i>LogicsManager</i> chap. starting page 116; default: (20.08 & 1) & 1			Logman
12170	Relay 9	see descr. in <i>LogicsManager</i> chap. starting page 116; default: (20.10 & 1) & 1			Logman
12330	External DO 1	see descr. in <i>LogicsManager</i> chap. starting page 116; default: (0 & 1) & 1			Logman
12340	External DO 2	see descr. in <i>LogicsManager</i> chap. starting page 116; default: (0 & 1) & 1			Logman
12350	External DO 3	see descr. in <i>LogicsManager</i> chap. starting page 116; default: (0 & 1) & 1			Logman
12360	External DO 4	see descr. in <i>LogicsManager</i> chap. starting page 116; default: (0 & 1) & 1			Logman
12370	External DO 5	see descr. in <i>LogicsManager</i> chap. starting page 116; default: (0 & 1) & 1			Logman
12380	External DO 6	see descr. in <i>LogicsManager</i> chap. starting page 116; default: (0 & 1) & 1			Logman
12390	External DO 7	see descr. in <i>LogicsManager</i> chap. starting page 116; default: (0 & 1) & 1			Logman
12400	External DO 8	see descr. in <i>LogicsManager</i> chap. starting page 116; default: (0 & 1) & 1			Logman
12410	External DO 9	see descr. in <i>LogicsManager</i> chap. starting page 116; default: (0 & 1) & 1			Logman
12420	External DO 10	see descr. in <i>LogicsManager</i> chap. starting page 116; default: (0 & 1) & 1			Logman
12430	External DO 11	see descr. in <i>LogicsManager</i> chap. starting page 116; default: (0 & 1) & 1			Logman
12440	External DO 12	see descr. in <i>LogicsManager</i> chap. starting page 116; default: (0 & 1) & 1			Logman
12450	External DO 13	see descr. in <i>LogicsManager</i> chap. starting page 116; default: (0 & 1) & 1			Logman
12460	External DO 14	see descr. in <i>LogicsManager</i> chap. starting page 116; default: (0 & 1) & 1			Logman
12470	External DO 15	see descr. in <i>LogicsManager</i> chap. starting page 116; default: (0 & 1) & 1			Logman
12480	External DO 16	see descr. in <i>LogicsManager</i> chap. starting page 116; default: (0 & 1) & 1			Logman

COUNTERS

2515	Counter value preset	0 to 99999999				UNSIGNED 32
2510	Set active energy in 0.00MWh	YES / NO	NO	<input type="checkbox"/> Y <input type="checkbox"/> N	<input type="checkbox"/> Y <input type="checkbox"/> N	UNSIGNED 16
2511	Set reactive energy in 0.00Mvarh	YES / NO	NO	<input type="checkbox"/> Y <input type="checkbox"/> N	<input type="checkbox"/> Y <input type="checkbox"/> N	UNSIGNED 16

LOGICSMANAGER

Internal Flags					
12230	Flag 1	see descr. in <i>LogicsManager</i> chap. starting page 116; default: (0 & 1) & 1			Logman
12240	Flag 2	see descr. in <i>LogicsManager</i> chap. starting page 116; default: (0 & 1) & 1			Logman
12250	Flag 3	see descr. in <i>LogicsManager</i> chap. starting page 116; default: (0 & 1) & 1			Logman
12260	Flag 4	see descr. in <i>LogicsManager</i> chap. starting page 116; default: (0 & 1) & 1			Logman
12270	Flag 5	see descr. in <i>LogicsManager</i> chap. starting page 116; default: (0 & 1) & 1			Logman
12280	Flag 6	see descr. in <i>LogicsManager</i> chap. starting page 116; default: (0 & 1) & 1			Logman
12290	Flag 7	see descr. in <i>LogicsManager</i> chap. starting page 116; default: (0 & 1) & 1			Logman
12300	Flag 8	see descr. in <i>LogicsManager</i> ch. start. p. 116; def.: (11.01 & !11.02) & 11.03			Logman
Set Timers					
1652	Setpoint 1: Hour	0 to 23 h	8 h		UNSIGNED 8
1651	Setpoint 1: Minute	0 to 59 min	0 min		UNSIGNED 8
1650	Setpoint 1: Second	0 to 59 s	0 s		UNSIGNED 8
1657	Setpoint 2: Hour	0 to 23 h	17 h		UNSIGNED 8
1656	Setpoint 2: Minute	0 to 59 min	0 min		UNSIGNED 8
1655	Setpoint 2: Second	0 to 59 s	0 s		UNSIGNED 8
1663	Active day	1 to 31	1		UNSIGNED 8
1662	Active hour	0 to 23 h	12 h		UNSIGNED 8
1661	Active minute	0 to 59 min	0 min		UNSIGNED 8
1660	Active second	0 to 59 s	0 s		UNSIGNED 8
1670	Monday active	YES / NO	YES	<input type="checkbox"/> Y <input type="checkbox"/> N	UNSIGNED 16
1671	Tuesday active	YES / NO	YES	<input type="checkbox"/> Y <input type="checkbox"/> N	UNSIGNED 16
1672	Wednesday active	YES / NO	YES	<input type="checkbox"/> Y <input type="checkbox"/> N	UNSIGNED 16
1673	Thursday active	YES / NO	YES	<input type="checkbox"/> Y <input type="checkbox"/> N	UNSIGNED 16
1674	Friday active	YES / NO	YES	<input type="checkbox"/> Y <input type="checkbox"/> N	UNSIGNED 16
1675	Saturday active	YES / NO	NO	<input type="checkbox"/> Y <input type="checkbox"/> N	UNSIGNED 16
1676	Sunday active	YES / NO	NO	<input type="checkbox"/> Y <input type="checkbox"/> N	UNSIGNED 16

Par. ID.	Parameter	Setting range	Default value	Customer setting	Data type
COMMUNICATION INTERFACES					
1702	Device number	1 to 127	1		UNSIGNED 16
CAN Interfaces					
3155	Protocol	OFF CAN Open LeoPC	CAN Open	<input type="checkbox"/> OFF <input type="checkbox"/> CAN O. <input type="checkbox"/> LeoPC	<input type="checkbox"/> OFF <input type="checkbox"/> CAN O. <input type="checkbox"/> LeoPC
3156	Baudrate	20/50/100/125/250/500/ 800/1000 kBd	125 kBd		UNSIGNED 16
CANopen Interfaces					
9000	CAN-Open Master	YES / NO	YES	<input type="checkbox"/> Y <input type="checkbox"/> N	<input type="checkbox"/> Y <input type="checkbox"/> N
9120	Producer Heartbeat Time	20 to 65530 ms	2000 ms		UNSIGNED 16
9100	COB-ID SYNC Message	1 to FFFFFFFF	80		UNSIGNED 32
9010	Max. answer time ext. devices	0.1 to 9.9 s	3.0 s		UNSIGNED 16
9009	Time re-init. ext. devices	0 to 9999 s	10 s		UNSIGNED 16
Additional Server SDOs					
9020	2nd Client->Server COB-ID (rx)	1 to FFFFFFFF	80000601		UNSIGNED 32
9022	2nd Server->Client COB-ID (tx)	1 to FFFFFFFF	80000581		UNSIGNED 32
9024	3rd Client->Server COB-ID (rx)	1 to FFFFFFFF	80000602		UNSIGNED 32
9026	3rd Server->Client COB-ID (tx)	1 to FFFFFFFF	80000582		UNSIGNED 32
9028	4th Client->Server COB-ID (rx)	1 to FFFFFFFF	80000603		UNSIGNED 32
9030	4th Server->Client COB-ID (tx)	1 to FFFFFFFF	80000583		UNSIGNED 32
9032	5th Client->Server COB-ID (rx)	1 to FFFFFFFF	80000604		UNSIGNED 32
9034	5th Server->Client COB-ID (tx)	1 to FFFFFFFF	80000584		UNSIGNED 32
Receive PDO 1					
9300	COB-ID	1 to FFFFFFFF	201		UNSIGNED 32
9050	Function	no func. 1st IKD 2nd IKD BK 16DIDO Co 16DIDO	no func.	<input type="checkbox"/> no func. <input type="checkbox"/> 1st IKD <input type="checkbox"/> 2nd IKD <input type="checkbox"/> BK 16 <input type="checkbox"/> Co 16	<input type="checkbox"/> no func. <input type="checkbox"/> 1st IKD <input type="checkbox"/> 2nd IKD <input type="checkbox"/> BK 16 <input type="checkbox"/> Co 16
9060	Node-ID of the device	1 to 127	2		UNSIGNED 16
9070	RPDO-COB-ID ext. device 1	1 to FFFFFFFF	181		UNSIGNED 32
Receive PDO 2					
9310	COB-ID	1 to FFFFFFFF	202		UNSIGNED 32
9051	Function	no func. 1st IKD 2nd IKD BK 16DIDO Co 16DIDO	no func.	<input type="checkbox"/> no func. <input type="checkbox"/> 1st IKD <input type="checkbox"/> 2nd IKD <input type="checkbox"/> BK 16 <input type="checkbox"/> Co 16	<input type="checkbox"/> no func. <input type="checkbox"/> 1st IKD <input type="checkbox"/> 2nd IKD <input type="checkbox"/> BK 16 <input type="checkbox"/> Co 16
9061	Node-ID of the device	1 to 127	3		UNSIGNED 16
9072	RPDO-COB-ID ext. device 2	1 to FFFFFFFF	182		UNSIGNED 32
Transmit PDO 1					
9600	COB-ID	1 to FFFFFFFF	181		UNSIGNED 32
9602	Transmission type	0 to 255	255		UNSIGNED 8
9604	Event-timer	20 to 65000 ms	20 ms		UNSIGNED 16
9609	Number of mapped objects	0 to 4	4		UNSIGNED 8
9605	1.Mapped Object	0 to 65535	8001		UNSIGNED 16
9606	2.Mapped Object	0 to 65535	8000		UNSIGNED 16
9607	3.Mapped Object	0 to 65535	8000		UNSIGNED 16
9608	4.Mapped Object	0 to 65535	8000		UNSIGNED 16
Transmit PDO 2					
9610	COB-ID	1 to FFFFFFFF	182		UNSIGNED 32
9612	Transmission type	0 to 255	255		UNSIGNED 8
9614	Event-timer	20 to 65000 ms	20 ms		UNSIGNED 16
9619	Number of mapped objects	0 to 4	4		UNSIGNED 8
9615	1.Mapped Object	0 to 65535	8002		UNSIGNED 16
9616	2.Mapped Object	0 to 65535	8000		UNSIGNED 16
9617	3.Mapped Object	0 to 65535	8000		UNSIGNED 16
9618	4.Mapped Object	0 to 65535	8000		UNSIGNED 16

Par. ID.	Parameter	Setting range	Default value	Customer setting	Data type	
COMMUNICATION INTERFACES						
Transmit PDO 3						
9620	COB-ID	1 to FFFFFFFF	381		UNSIGNED 32	
9622	Transmission type	0 to 255	255		UNSIGNED 8	
9624	Event-timer	20 to 65000 ms	20 ms		UNSIGNED 16	
9629	Number of mapped objects	0 to 4	1		UNSIGNED 8	
9625	1.Mapped Object	0 to 65535	3196		UNSIGNED 16	
9626	2.Mapped Object	0 to 65535	0		UNSIGNED 16	
9627	3.Mapped Object	0 to 65535	0		UNSIGNED 16	
9628	4.Mapped Object	0 to 65535	0		UNSIGNED 16	
Transmit PDO 4						
9630	COB-ID	1 to FFFFFFFF	481		UNSIGNED 32	
9632	Transmission type	0 to 255	255		UNSIGNED 8	
9634	Event-timer	20 to 65000 ms	20 ms		UNSIGNED 16	
9639	Number of mapped objects	0 to 4	1		UNSIGNED 8	
9635	1.Mapped Object	0 to 65535	3190		UNSIGNED 16	
9636	2.Mapped Object	0 to 65535	0		UNSIGNED 16	
9637	3.Mapped Object	0 to 65535	0		UNSIGNED 16	
9638	4.Mapped Object	0 to 65535	0		UNSIGNED 16	
Serial Interface 1						
3163	Baudrate	2400 Bd 4800 Bd 9600 Bd 14.4 kBd 19.2 kBd 38.4 kBd 56 kBd 115 kBd	9600 Bd	<input type="checkbox"/> 2400 Bd <input type="checkbox"/> 4800 Bd <input type="checkbox"/> 9600 Bd <input type="checkbox"/> 14.4 kBd <input type="checkbox"/> 19.2 kBd <input type="checkbox"/> 38.4 kBd <input type="checkbox"/> 56 kBd <input type="checkbox"/> 115 kBd	<input type="checkbox"/> 2400 Bd <input type="checkbox"/> 4800 Bd <input type="checkbox"/> 9600 Bd <input type="checkbox"/> 14.4 kBd <input type="checkbox"/> 19.2 kBd <input type="checkbox"/> 38.4 kBd <input type="checkbox"/> 56 kBd <input type="checkbox"/> 115 kBd	UNSIGNED 16
3161	Parity	No Even Odd	No	<input type="checkbox"/> No <input type="checkbox"/> Even <input type="checkbox"/> Odd	<input type="checkbox"/> No <input type="checkbox"/> Even <input type="checkbox"/> Odd	UNSIGNED 16
3162	Stop Bits	One Two	One	<input type="checkbox"/> One <input type="checkbox"/> Two	<input type="checkbox"/> One <input type="checkbox"/> Two	UNSIGNED 16
Serial Interface 2						
3170	Baudrate	2400 Bd 4800 Bd 9600 Bd 14.4 kBd 19.2 kBd 38.4 kBd 56 kBd 115 kBd	19200 Bd	<input type="checkbox"/> 9600 Bd <input type="checkbox"/> 14.4 kBd <input type="checkbox"/> 19.2 kBd <input type="checkbox"/> 38.4 kBd <input type="checkbox"/> 56 kBd <input type="checkbox"/> 115 kBd	<input type="checkbox"/> 9600 Bd <input type="checkbox"/> 14.4 kBd <input type="checkbox"/> 19.2 kBd <input type="checkbox"/> 38.4 kBd <input type="checkbox"/> 56 kBd <input type="checkbox"/> 115 kBd	UNSIGNED 16
3171	Parity	No Even Odd	No	<input type="checkbox"/> No <input type="checkbox"/> Even <input type="checkbox"/> Odd	<input type="checkbox"/> No <input type="checkbox"/> Even <input type="checkbox"/> Odd	UNSIGNED 16
3172	Stop Bits	One Two	One	<input type="checkbox"/> One <input type="checkbox"/> Two	<input type="checkbox"/> One <input type="checkbox"/> Two	UNSIGNED 16
3173	Full-, halfduplex mode	Fullduplex Halfduplex	Fullduplex	<input type="checkbox"/> Full <input type="checkbox"/> Half	<input type="checkbox"/> Full <input type="checkbox"/> Half	UNSIGNED 16
3185	ModBus Slave ID	0 to 255	1			UNSIGNED 16
3186	Modbus Reply delay time	0.00 to 1.00 s	0.00 s			UNSIGNED 16

Par. ID.	Parameter	Setting range	Default value	Customer setting	Data type
SYSTEM PARAMETER					
Display Backlight					
4556	Configure display backlight	On Off Auto Key actv.	On	<input type="checkbox"/> On <input type="checkbox"/> Off <input type="checkbox"/> Auto <input type="checkbox"/> Key act.	<input type="checkbox"/> On <input type="checkbox"/> Off <input type="checkbox"/> Auto <input type="checkbox"/> Key act.
4557	Time until backlight shutdown	1 to 999 s	600 s		UNSIGNED 16
Daylight saving time					
4591	Daylight saving time	On Off	Off	<input type="checkbox"/> On <input type="checkbox"/> Off	<input type="checkbox"/> On <input type="checkbox"/> Off
4593	DST begin month	1 to 12	1		UNSIGNED 8
4592	DST begin sunday	1 to 4	1		UNSIGNED 8
4594	DST begin time	1 to 23 h	0 h		UNSIGNED 8
4596	DST end month	1 to 12	1		UNSIGNED 8
4595	DST end sunday	1 to 4	1		UNSIGNED 8
4597	DST end time	1 to 23 h	0 h		UNSIGNED 8
Password System					
10405	Code level display	0000 to 9999	---		UNSIGNED 16
10407	Code level CAN port	0000 to 9999	---		UNSIGNED 16
10406	Code level serial port / DPC	0000 to 9999	---		UNSIGNED 16
10411	Supercomm. level code	0000 to 9999	---		UNSIGNED 16
10412	Temp. supercomm. level code	0000 to 9999	---		UNSIGNED 16
10413	Commissioning level code	0000 to 9999	---		UNSIGNED 16
10414	Temp. commissioning level code	0000 to 9999	---		UNSIGNED 16
10415	Basic level code	0000 to 9999	---		UNSIGNED 16
1703	Factory settings	YES / NO	NO	<input type="checkbox"/> Y <input type="checkbox"/> N	<input type="checkbox"/> Y <input type="checkbox"/> N
1704	Factory settings DPC/RS232	YES / NO	NO	<input type="checkbox"/> Y <input type="checkbox"/> N	<input type="checkbox"/> Y <input type="checkbox"/> N
1705	Factory settings CAN	YES / NO	NO	<input type="checkbox"/> Y <input type="checkbox"/> N	<input type="checkbox"/> Y <input type="checkbox"/> N
1701	Set default values	YES / NO	NO	<input type="checkbox"/> Y <input type="checkbox"/> N	<input type="checkbox"/> Y <input type="checkbox"/> N
10500	Start Bootloader	00000 to 99999	---		UNSIGNED 16
Clock Set					
1762	Hour	0 to 23 h	---		UNSIGNED 8
1761	Minute	0 to 59 min	---		UNSIGNED 8
1760	Second	0 to 59 s	---		UNSIGNED 8
1763	Day	1 to 31	---		UNSIGNED 8
1764	Month	1 to 12	---		UNSIGNED 8
1765	Year	0 to 99	---		UNSIGNED 8
Version					
900	Serial number	Info	---		UNSIGNED 8
950	Boot item number	Info	---		UNSIGNED 8
960	Boot revision	Info	---		UNSIGNED 8
965	Boot version	Info	---		UNSIGNED 8
930	Program item number	Info	---		UNSIGNED 8
940	Program revision	Info	---		UNSIGNED 8
945	Program version	Info	---		UNSIGNED 8

**NOTE**

All parameters shaded in gray color are fixed parameters and cannot be configured by the operator.

Appendix D. Service Options

Product Service Options



The following factory options are available for servicing Woodward equipment, based on the standard Woodward Product and Service Warranty (5-01-1205) that is in effect at the time the product is purchased from Woodward or the service is performed. If you are experiencing problems with installation or unsatisfactory performance of an installed system, the following options are available:

- Consult the troubleshooting guide in the manual.
- Contact Woodward technical assistance (see "How to Contact Woodward" later in this chapter) and discuss your problem. In most cases, your problem can be resolved over the phone. If not, you can select which course of action you wish to pursue based on the available services listed in this section.

Returning Equipment For Repair



If a control (or any part of an electronic control) is to be returned to Woodward for repair, please contact Woodward in advance to obtain a Return Authorization Number. When shipping the unit(s), attach a tag with the following information:

- name and location where the control is installed;
- name and phone number of contact person;
- complete Woodward part numbers (P/N) and serial number (S/N);
- description of the problem;
- instructions describing the desired repair.



CAUTION

To prevent damage to electronic components caused by improper handling, read and observe the precautions in Woodward manual 82715, *Guide for Handling and Protection of Electronic Controls, Printed Circuit Boards, and Modules*.

Packing A Control

Use the following materials when returning a complete control:

- protective caps on any connectors;
- antistatic protective bags on all electronic modules;
- packing materials that will not damage the surface of the unit;
- at least 100 mm (4 inches) of tightly packed, industry-approved packing material;
- a packing carton with double walls;
- a strong tape around the outside of the carton for increased strength.

Return Authorization Number RAN

When returning equipment to Woodward, please telephone and ask for the Customer Service Department in Stuttgart [+49 (0) 711 789 54-0]. They will help expedite the processing of your order through our distributors or local service facility. To expedite the repair process, contact Woodward in advance to obtain a Return Authorization Number, and arrange for issue of a purchase order for the unit(s) to be repaired. No work can be started until a purchase order is received.



NOTE

We highly recommend that you make arrangement in advance for return shipments. Contact a Woodward customer service representative at +49 (0) 711 789 54-0 for instructions and for a Return Authorization Number.

Replacement Parts



When ordering replacement parts for controls, include the following information:

- the part numbers P/N (XXXX-XXX) that is on the enclosure nameplate;
- the unit serial number S/N, which is also on the nameplate.

How To Contact Woodward



Please contact following address if you have questions or if you want to send a product for repair:

Woodward GmbH
Handwerkstrasse 29
70565 Stuttgart - Germany

Phone: +49 (0) 711 789 54-0 (8.00 - 16.30 German time)
Fax: +49 (0) 711 789 54-100
e-mail: stgt-info@woodward.com

For assistance outside Germany, call one of the following international Woodward facilities to obtain the address and phone number of the facility nearest your location where you will be able to get information and service.

Facility	Phone number
USA	+1 (970) 482 5811
India	+91 (129) 409 7100
Brazil	+55 (19) 3708 4800
Japan	+81 (476) 93 4661
The Netherlands	+31 (23) 566 1111

You can also contact the Woodward Customer Service Department or consult our worldwide directory on Woodward’s website (www.woodward.com) for the name of your nearest Woodward distributor or service facility. [For worldwide directory information, go to www.woodward.com/ic/locations.]

Engineering Services



Woodward Industrial Controls Engineering Services offers the following after-sales support for Woodward products. For these services, you can contact us by telephone, by e-mail, or through the Woodward website.

- Technical support
- Product training
- Field service during commissioning

Technical Support is available through our many worldwide locations, through our authorized distributors, or through GE Global Controls Services, depending on the product. This service can assist you with technical questions or problem solving during normal business hours. Emergency assistance is also available during non-business hours by phoning our toll-free number and stating the urgency of your problem. For technical engineering support, please contact us via our toll-free or local phone numbers, e-mail us, or use our website and reference technical support.

Product Training is available on-site from several of our worldwide facilities, at your location, or from GE Global Controls Services, depending on the product. This training, conducted by experienced personnel, will assure that you will be able to maintain system reliability and availability. For information concerning training, please contact us via our toll-free or local phone numbers, e-mail us, or use our website and reference *customer training*.

Field Service engineering on-site support is available, depending on the product and location, from our facility in Colorado, or from one of many worldwide Woodward offices or authorized distributors. Field engineers are experienced on both Woodward products as well as on much of the non-Woodward equipment with which our products interface. For field service engineering assistance, please contact us via our toll-free or local phone numbers, e-mail us, or use our website and reference *field service*.

Technical Assistance



If you need to telephone for technical assistance, you will need to provide the following information. Please write it down here before phoning:

Contact

Your company _____

Your name _____

Phone number _____

Fax number _____

Control (see name plate)

Unit no. and revision: P/N: _____ REV: _____

Unit type DTSC-200 _____

Serial number S/N _____

Description of your problem

Please be sure you have a list of all parameters available. You can print this using LeoPC1. Additionally you can save the complete set of parameters (standard values) and send them to our Service department via e-mail.

We appreciate your comments about the content of our publications.
Please send comments to: stgt-documentation@woodward.com
Please include the manual number from the front cover of this publication.



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Homepage

<http://www.woodward.com/power>

Woodward has company-owned plants, subsidiaries, and branches, as well as authorized distributors and other authorized service and sales facilities throughout the world.

Complete address/phone/fax/e-mail information
for all locations is available on our website (www.woodward.com).

2007/12/Stuttgart