

# **DYNA 8000 GOVERNOR SYSTEM**

### GENERAL

The DYNA 8000 system will provide an engine governor for speed and power control of piston and gas turbine engines or steam and water turbines.

The actuator is basically a simple, proportional, electric solenoid having a sliding armature whose magnetic force is proportional to input coil current. Balanced between the force of its return spring and the magnetic force, the armature glides on anti-friction bearings, providing a hysteresis-free linear movement. Linear motion is converted to an output shaft rotation by a bell crank.





## **TYPICAL APPLICATIONS**

- Speed governing
- Remote throttle control
- Test stand throttle control
- · Generator sets
- Power carts
- Pump sets

## **STANDARD FEATURES**

- All electric
- · All engine compatibility
- · Mounts in any position
- Engine mounted (actuator only)
- · High reliability due to few moving parts
- Proportional actuator
- No hydraulic or oil line
- No special maintenance
- Spring returns output shaft to minimum position on removal of power or loss of magnetic pickup signal
- · Precise repeatability

## AVAILABLE MODELS

#### Actuators:

## Part No.

DYNC-11020-000-0-12 DYNC-11020-000-0-24 DYNC-11024-000-0-12 DYNC-11024-000-0-24

Standard Clockwise Output Shaft Rotation Standard Counter Clockwise Output Shaft Rotation

#### **Controllers: Speed Controllers**

	Part No.	Input Signal Frequency
	DYN1 -10652-000-0-12/24	250-1200 Hz
	DYN1 -10653-000-0-12/24	(U) 1200-2500 Hz
	DYN1 -10654-000-0-12/24	2500-5000 Hz
	DYN1 -10656-000-0-12/24	5000-9500 Hz
al	DYN1 -10682-000-0-12/24	250-1200 Hz
	DYN1 -10683-000-0-12/24	1200-2500 Hz
	DYN1 -10684-000-0-12/24	2500-5000 Hz
	DYN1 -10686-000-0-12/24	5000-9500 Hz

#### Controllers: Conforming to (CSpecifications

	In
001-0-12/24	
001-0-12/24	
001-0-12/24	
001-0-12/24	F
001-0-12/24	
001-0-12/24	
001-0-12/24	
001-0-12/24	

Input Signal Frequency 250-1200 Hz 1200-2500 Hz 2500-5000 Hz 5000-9500 Hz 250-1200 Hz 1200-2500 Hz 2500-5000 Hz 5000-9500 Hz

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## **SPECIFICATIONS (ACTUATOR)**

# Operating Voltage:

12 VDC or 24 VDC, ± 20%

Sealed Unit: Oil, water and dust tight

**Connection:** Terminal strip

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Actuator Ambient Operating Temperature: -65°F (-55°C) to +255°F (+125°C)

### **Mechanical Vibration:**

5 to 500 Hz, Curve F, per Mil-Std. 810C, Method 514-2.

# INPUT SIGNAL FREQUENCY

Input Signal Frequency in Hertz Engine RPM x Number of Gear Teeth on Flywheel 60 Seconds

Select your controller for the correct input signal frequency range generated by the magnetic pickup at the maximum engine operated (RPM) speed.

## **DYNA 8000 Actuators**

# SPECIFICATIONS (CONTROLLER)

## **Operating Voltages:**

12 VDC or 24 VDC,  $\pm$  20%

### **Circuit Boards:**

Are covered with a heavy conformal coating for moisture and vibration protection.

#### **Connection:**

**Terminal Strip** 

## **Controller Ambient Operating Temperature:**

-40°F (-40°C) to +180°F (+85°C).

### **Temperature Stability:**

Better than  $\pm$  0.5 percent over a temperature range of -40°F (-40°C) to 167°F (+75°C)

### Steady State Speed Band:

 $\pm 0.25\%$ 

### Adjustments:

Speed, Gain, Integral and Droop.

### **Mechanical Vibration:**

Withstands the following vibration without failure or degraded performance: 0.06 inch double amplitude at 5 to 18 Hz; 1 G at 18 to 30 Hz; 0.02 inch double amplitude at 30 to 48 Hz; 2.5 G's at 48 to 70 Hz.

Work	Joules	1.2			
	Foot-Pounds	1.0			
	Newton-Meters	1.4			
Torque	Pound-Foot	1.0			
Output	Rotary	35°			
Weight	Kilograms	5			
	Pounds	11.0			
Current @ 12 VDC	Maximum Amperes @ Stall	12.5			
	Nominal Steady State Amperes	3.5			
Current @ 24 VDC	Maximum Amperes @ Stall	9.5			
	Nominal Steady State Amperes	2.5			
Nominal Response Time for 63% of Stroke					
(Seconds)	0.030				

## **DYNA 8000 Controllers**

Output	Nominal Quiescent Current	80 ma
Current@ 12 VDC	Maximum Amperes @ Stall	13 amps
Output	Nominal Quiescent Current	80 ma
Current@ 24 VDC	Maximum Amperes @ Stall	13 amps
Weight	Kilograms	0.863
	Pounds	1.9

## **DIMENSIONS — DYNA 8000 CONTROLLER**

3

4

5

6

+8V

гh

Actuator

+4V

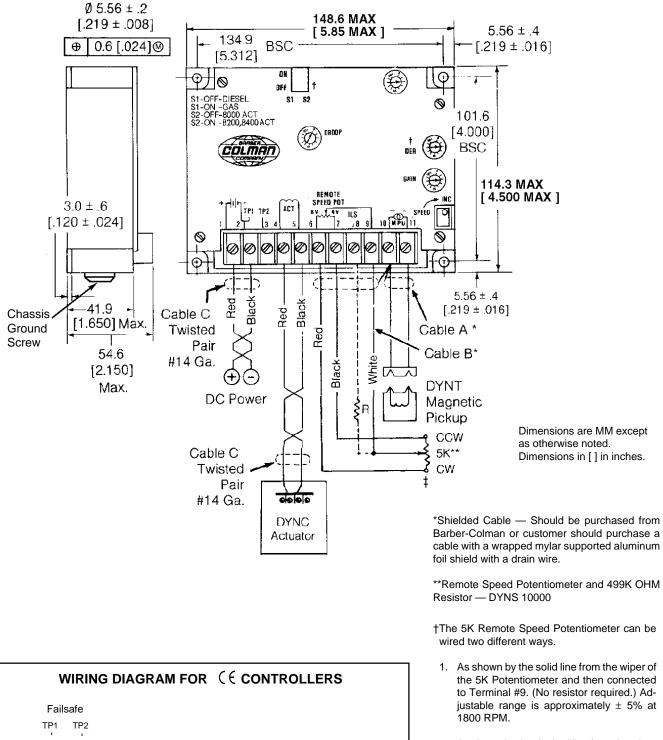
Chassis

Gnd

Screw

2

Battery



2. As shown by the dashed line from the wiper of the 5K Potentiometer through Resistor R and then connected to Terminal #8. Reducing the value of R increases the remote adjustable speed range.



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External

Speed

Adjust

11

Wht

Blk

Magnetic Pick-up

*山* Chassis

Gnd

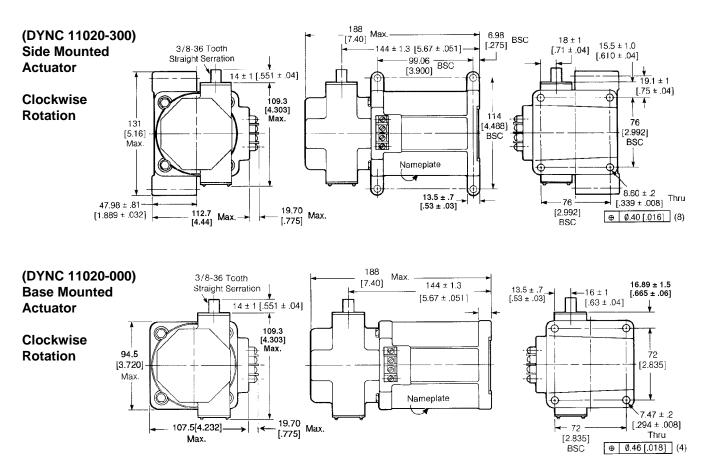
Screw

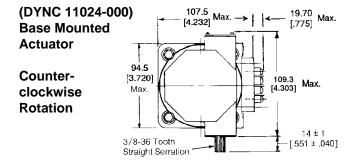
3

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ILS

### INSTALLATION DRAWINGS





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#### CAUTION

As a safety measure, the engine should be equipped with an independent overspeed shutdown device in the event of failure which may render the governor inoperative.

#### NOTE

Barber-Colman believes that all information provided herein is correct and reliable and reserves the right to update at any time. Barber-Colman does not assume any responsibility for its use unless otherwise expressly undertaken.